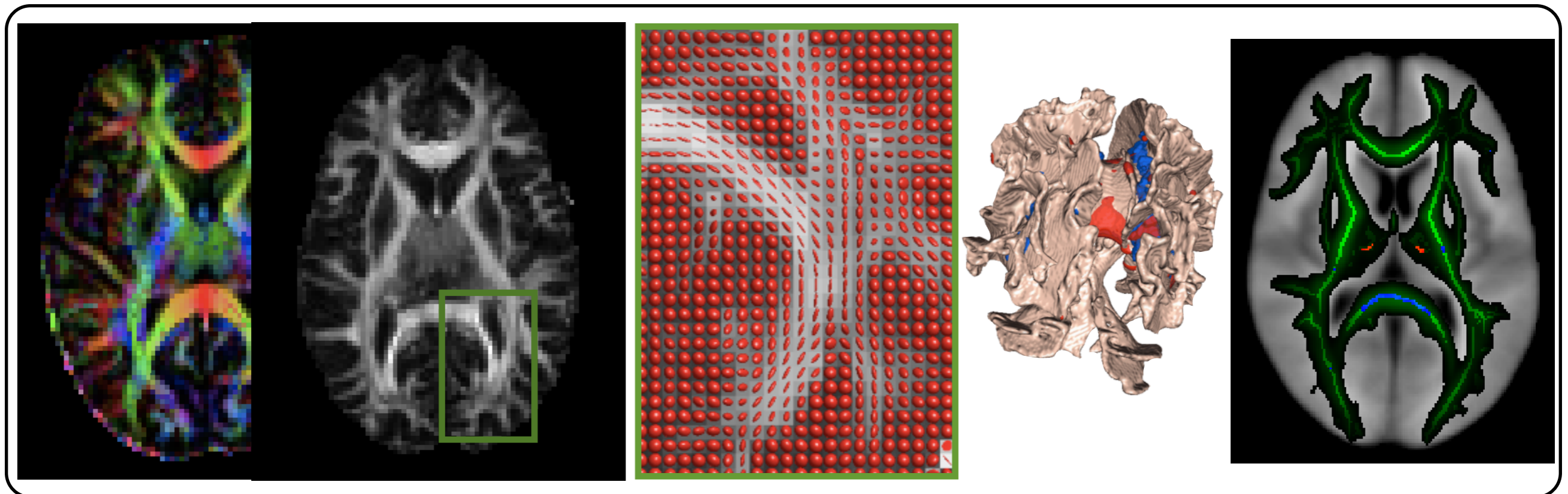




Diffusion MRI Processing and Analysis

弥散MRI的处理与分析

中文翻译：李宏 孔亚卓

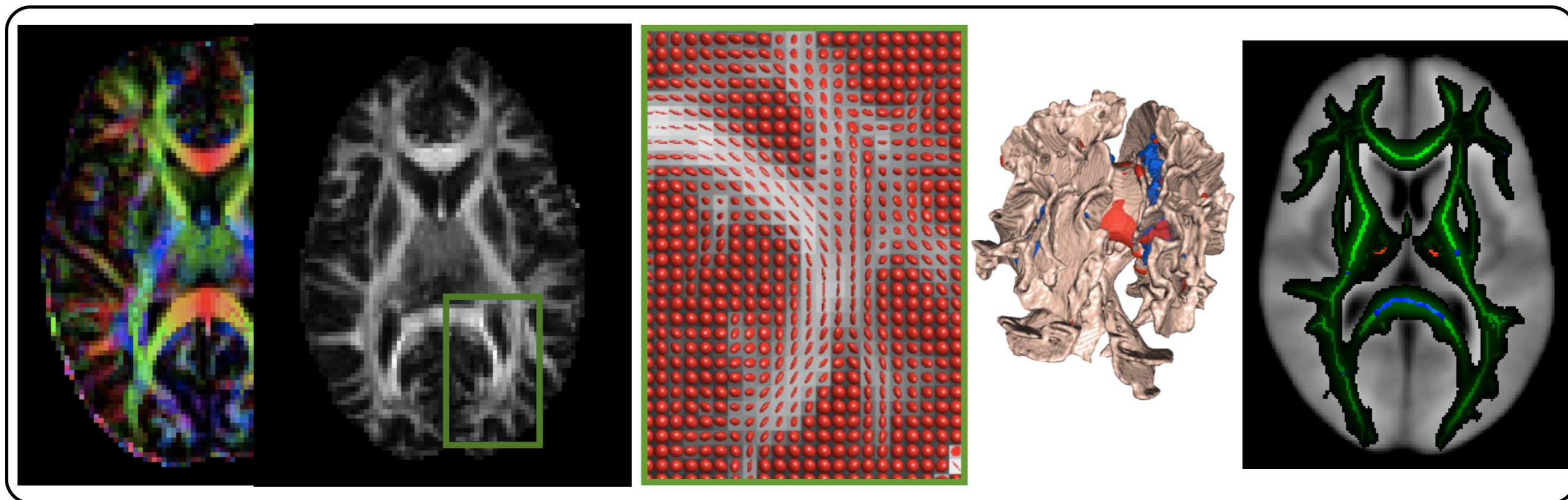




Overview

概述

- What is Diffusion? Diffusion-weighting in MRI 什么是弥散? MRI中的扩散加权
- Diffusion Tensor Model and DTI 扩散张量模型和DTI
- Tract-Based Diffusion analysis (TBSS) 纤维素追踪分析 (TBSS)
- Distortion Correction for Diffusion MRI 扩散MRI的畸变校正



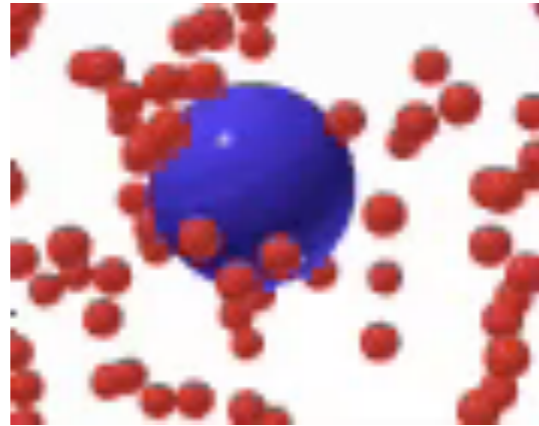


Diffusion - Brownian Motion

扩散-布朗运动



Robert Brown (1773-1858)



Molecules are in constant motion at non-zero absolute temperatures ($> -273^{\circ}\text{C}$)

分子在非零绝对温度下持续运动

Diffusion = thermally-driven random motion

弥散=热驱动随机运动



Diffusion - Brownian Motion

扩散-布朗运动



Albert Einstein (1879-1955)

How can we describe this motion?

我们应该怎么形容这种运动呢？

For an ensemble of molecules, in n -dimensional space: 对于 n 维空间中的分子集合：

$$\langle x^2 \rangle = 2nDt$$

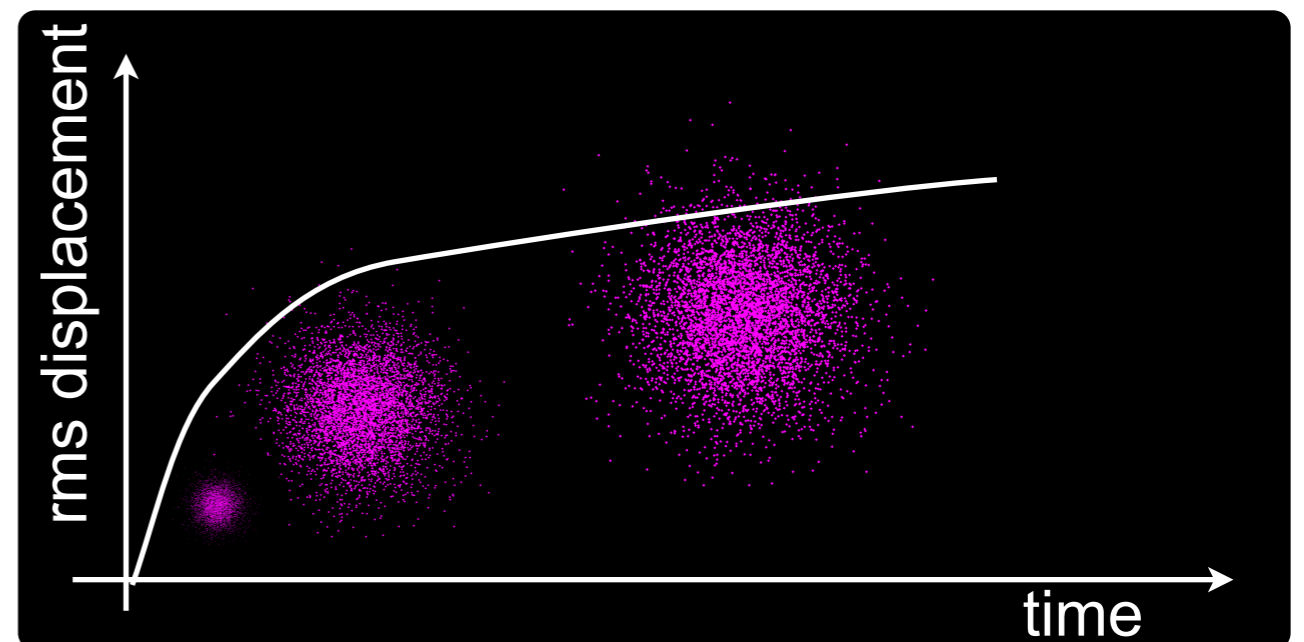
mean squared displacement

Diffusion coefficient

time

Valid for a homogeneous, barrier-free medium.

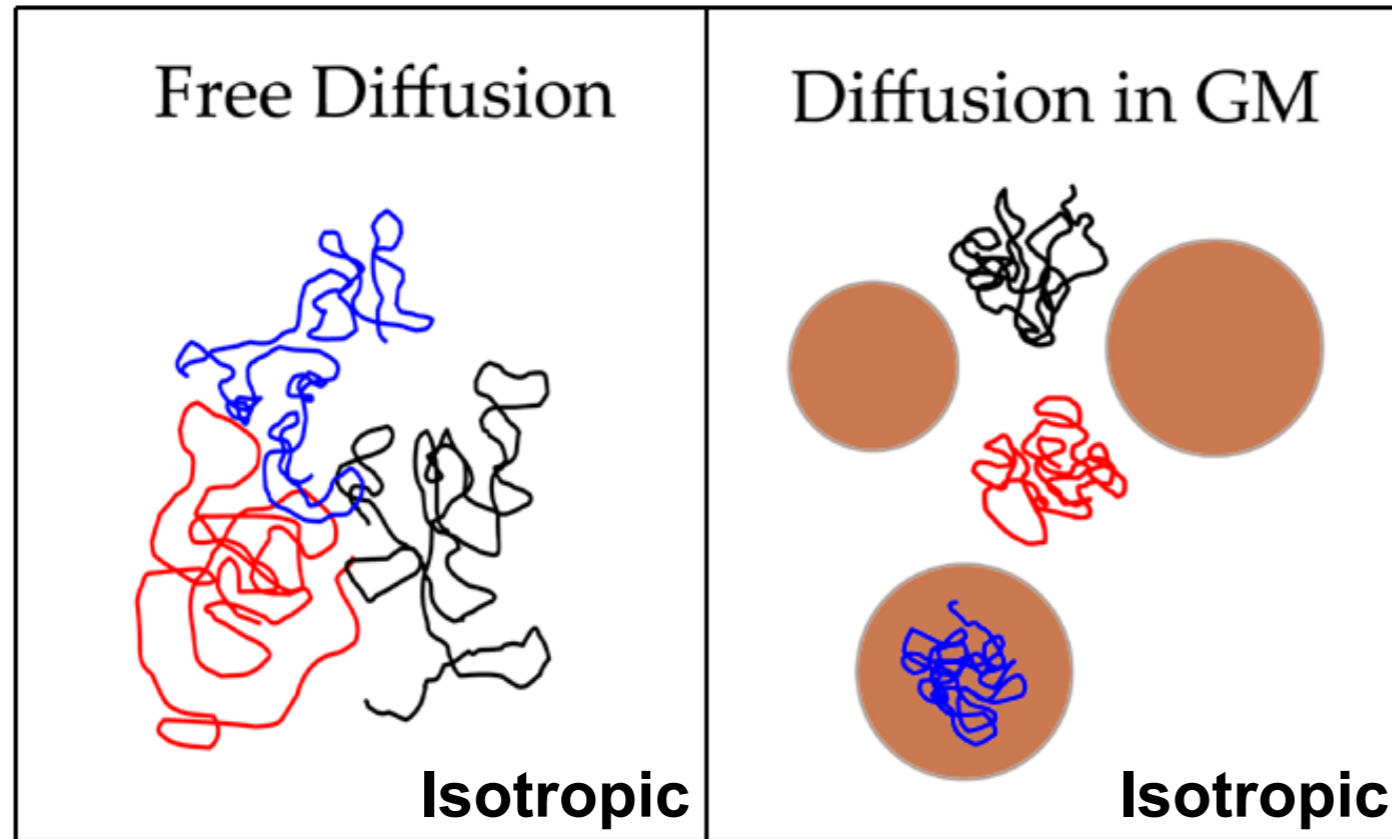
适用于同质，无障碍媒介。



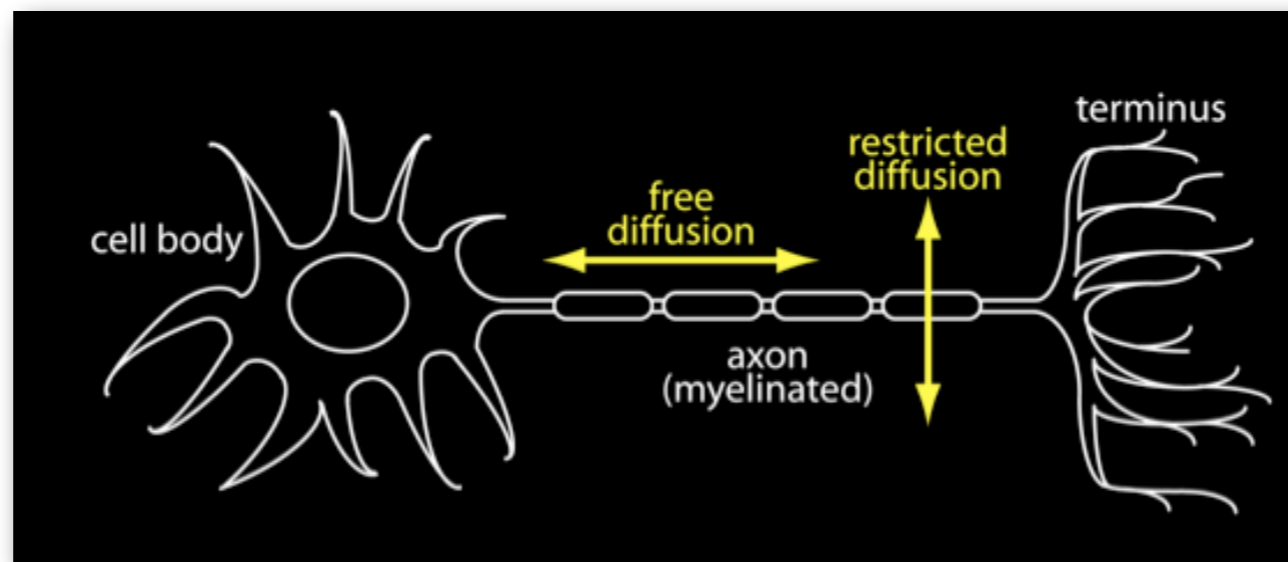
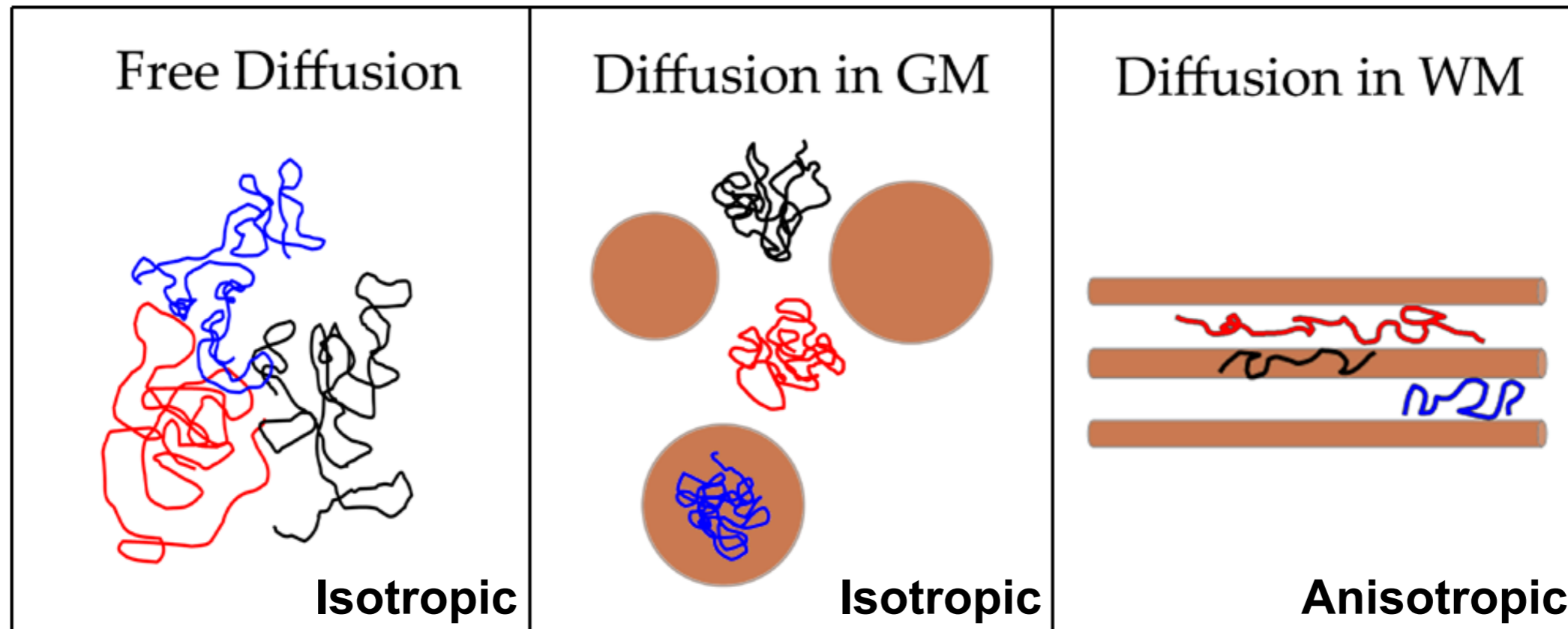
Water Diffusion in the Brain. Why is it Interesting?



Water Diffusion in the Brain. Why is it Interesting?



Water Diffusion in the Brain. Why is it Interesting?

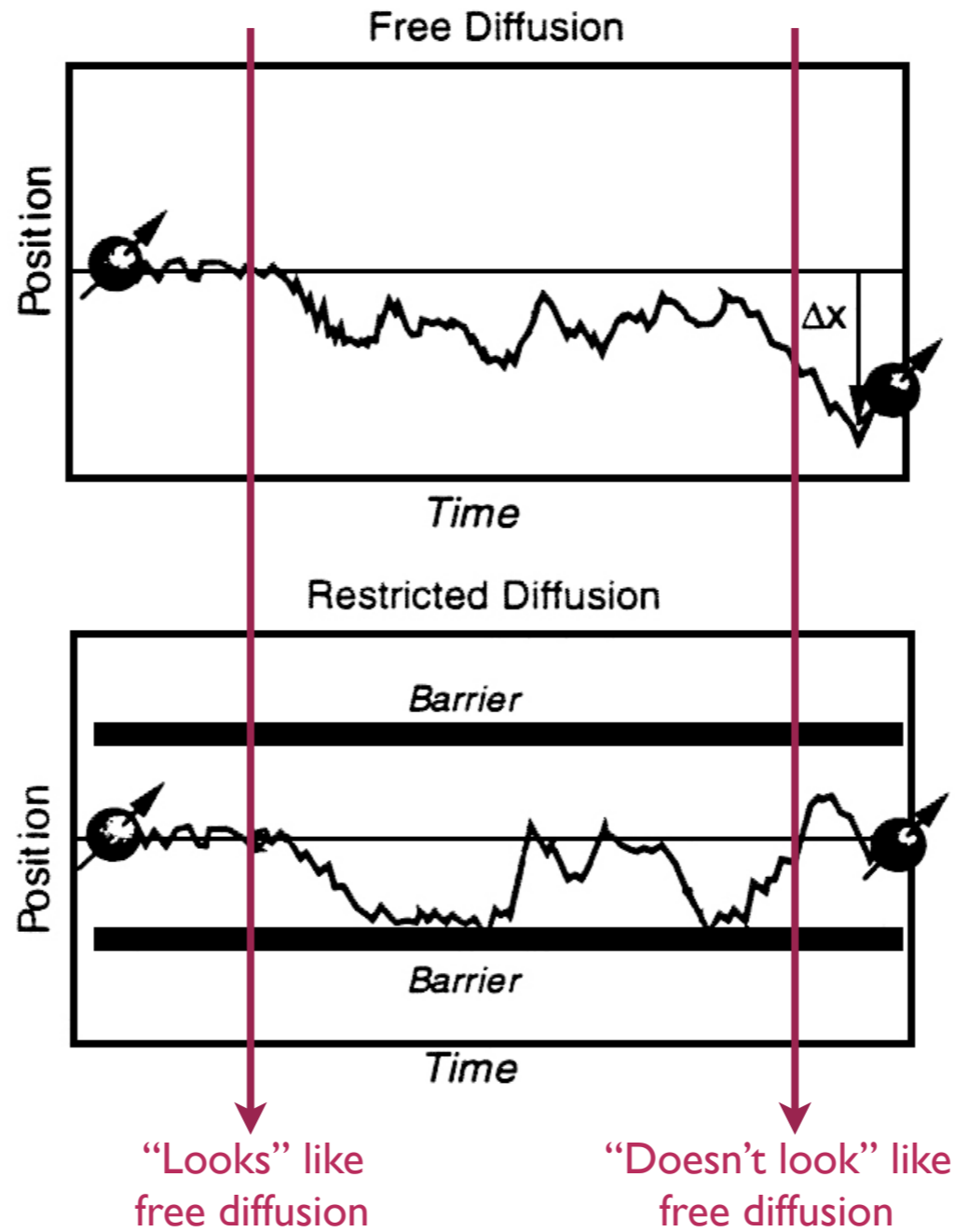


Diffusion is restricted by tissue boundaries, membranes, etc.
Marker for tissue microstructure (healthy and pathology)
Diffusion is **anisotropic** in white matter

[Beaulieu, NMR Biomed, 2002]



Apparent Diffusion 表观扩散



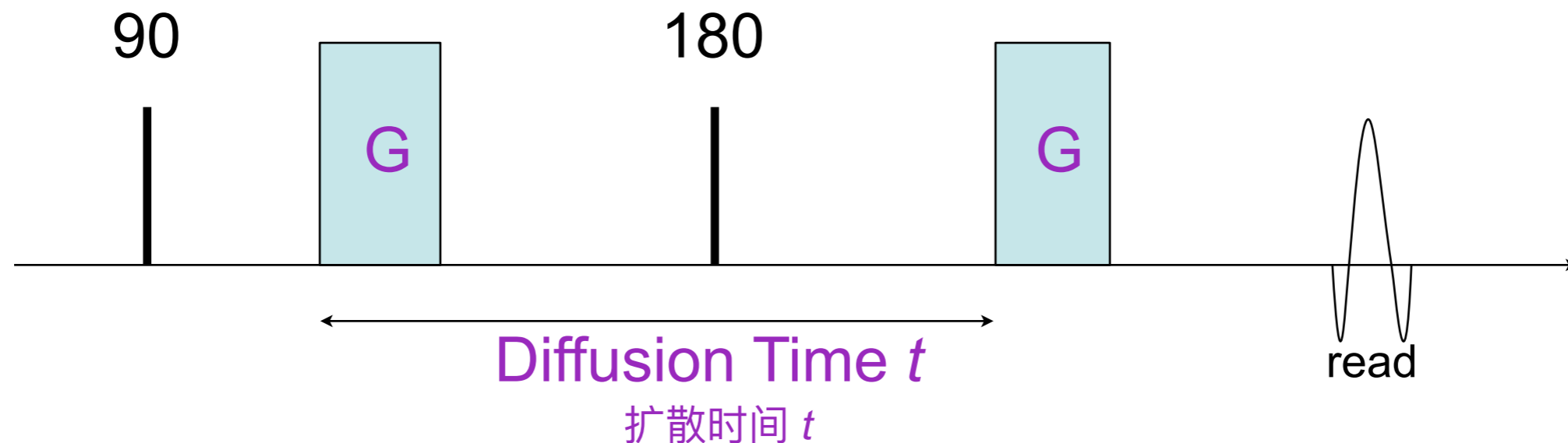
Observed diffusion in tissues depends on the experiment = “Apparent diffusion” & “Apparent diffusion coefficient” (ADC)
组织中观察到的扩散取决于实验=“表观扩散”和“表观扩散系数” (ADC)



Measuring Diffusion with MRI:

用MRI测量扩散: Diffusion MRI (dMRI)

Pulsed-Gradient Spin-Echo Sequence: 脉冲梯度自旋回波序列:
To achieve diffusion-weighting along a direction \mathbf{x} , apply strong magnetic field gradients along \mathbf{x} . 为了沿x方向实现扩散加权, 沿x施加强磁场梯度。



If particles diffuse along \mathbf{x} during the allowed time (DiffTime), a signal attenuation is observed, compared to the signal with $G=0$.

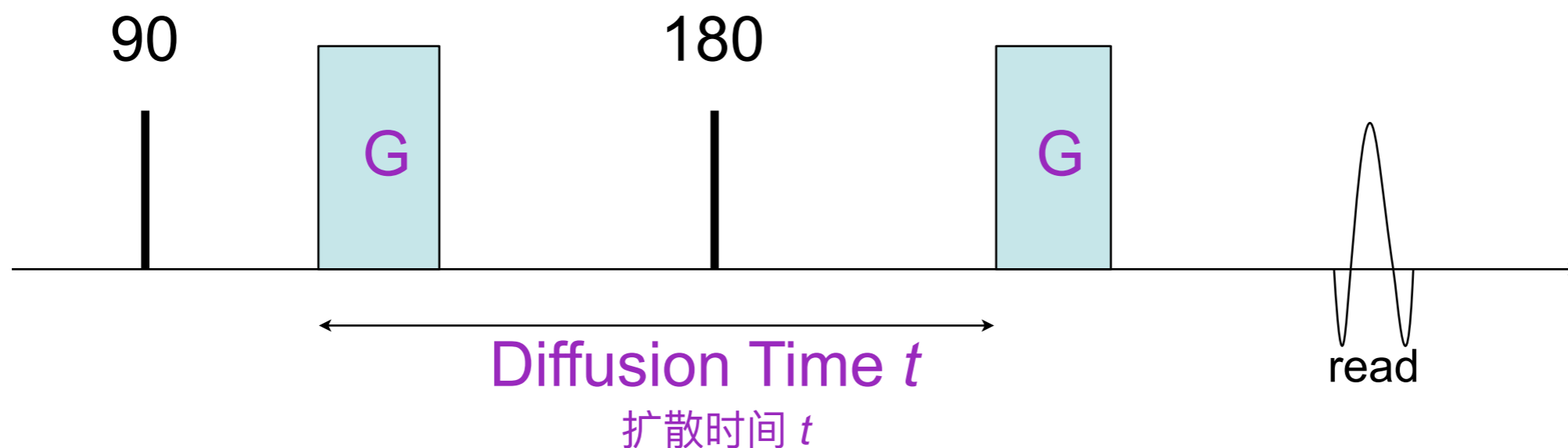
如果粒子在允许时间 (DiffTime) 期间沿x扩散, 则与 $G = 0$ 的信号相比, 观察到信号衰减。



Measuring Diffusion with MRI:

用MRI测量扩散: Diffusion MRI (dMRI)

Pulsed-Gradient Spin-Echo Sequence: 脉冲梯度自旋回波序列:
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$D \sim 2.4 \mu\text{m}^2/\text{ms}$
 $t \sim 50\text{ms}$

$x = \sqrt{6Dt} \sim 27\mu\text{m}$

st. deviation of displacements
位移偏差



Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

T2w Image
No Diffusion-weighting

T2加权图像
没有扩散加权

($G=0$)

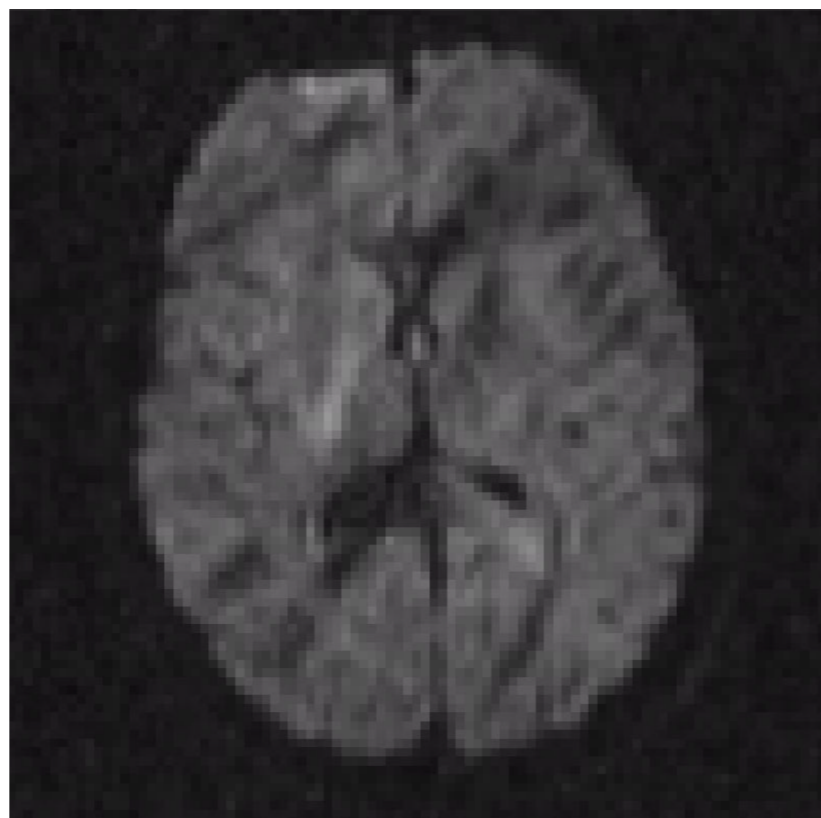
S_0



Diffusion-weighted
Image

弥散加权图像

S



Ratio

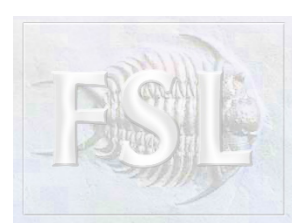
比值

S/S_0



Removes T2w contrast

去除T2加权对比度



Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

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No Diffusion-weighting

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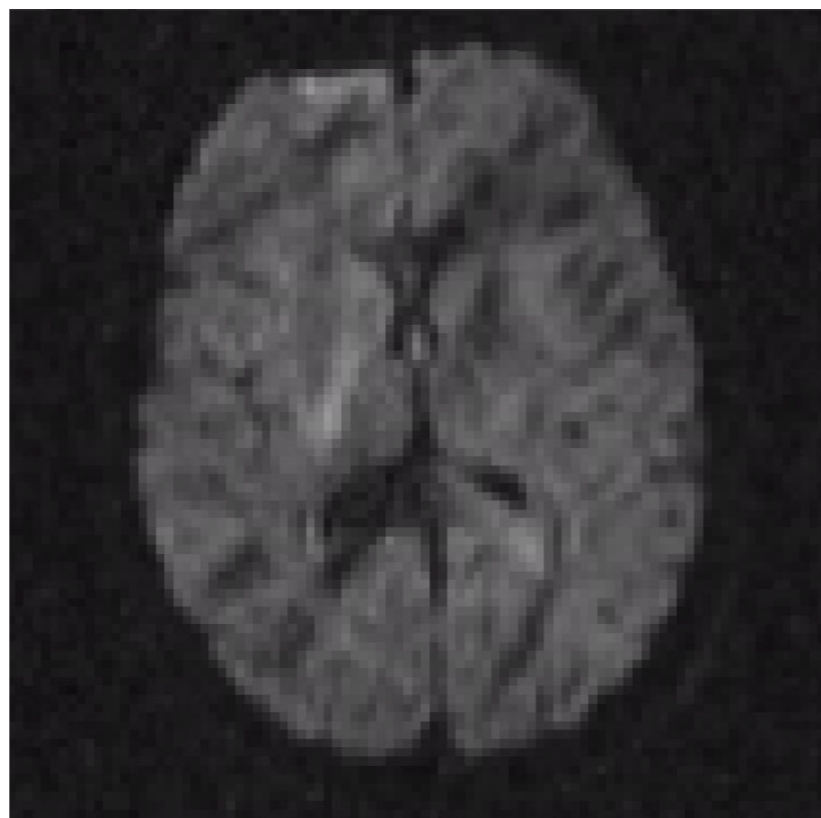
S_0



Diffusion-weighted
Image

弥散加权图像

S



Ratio

比值

S/S_0



Removes T2w contrast

去除T2加权对比度



Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

T2w Image
No Diffusion-weighting

T2加权图像
没有扩散加权

($G=0$)

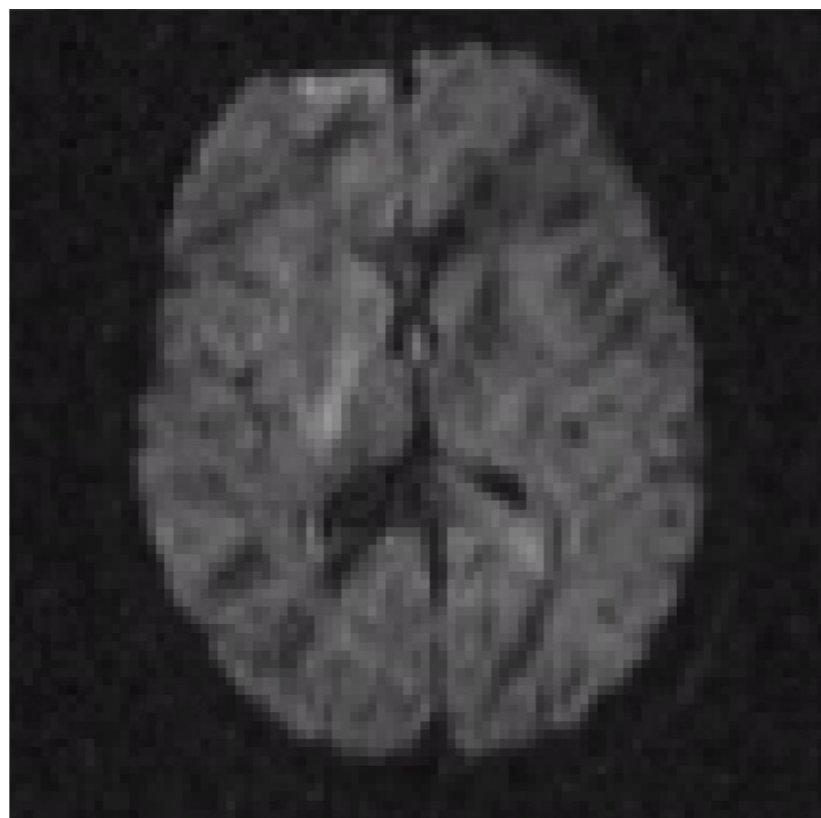
S_0



Diffusion-weighted
Image

弥散加权图像

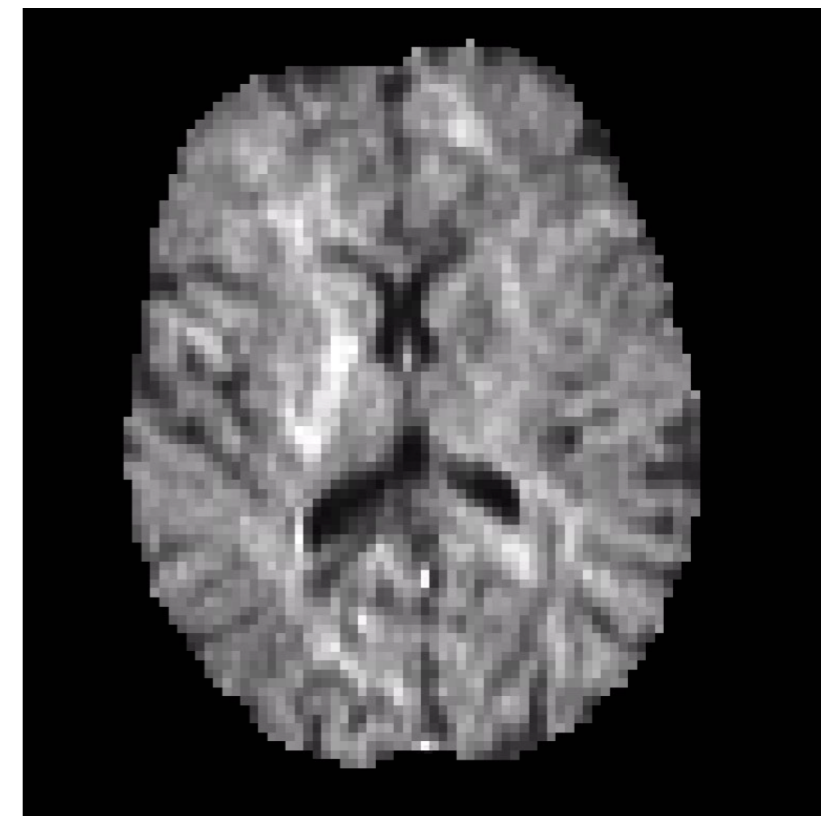
S



Ratio

比值

S/S_0



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Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

Diffusion contrast can be modulated by: 扩散对比可以通过以下方式调节

A) **Diffusion weighting:** Gradient **strength**, Diffusion **time**

扩散加权：梯度强度，扩散时间

$$\mathbf{b\ value} \sim G^2 \cdot \text{DiffTime} \quad (\text{units in s/mm}^2)$$



Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

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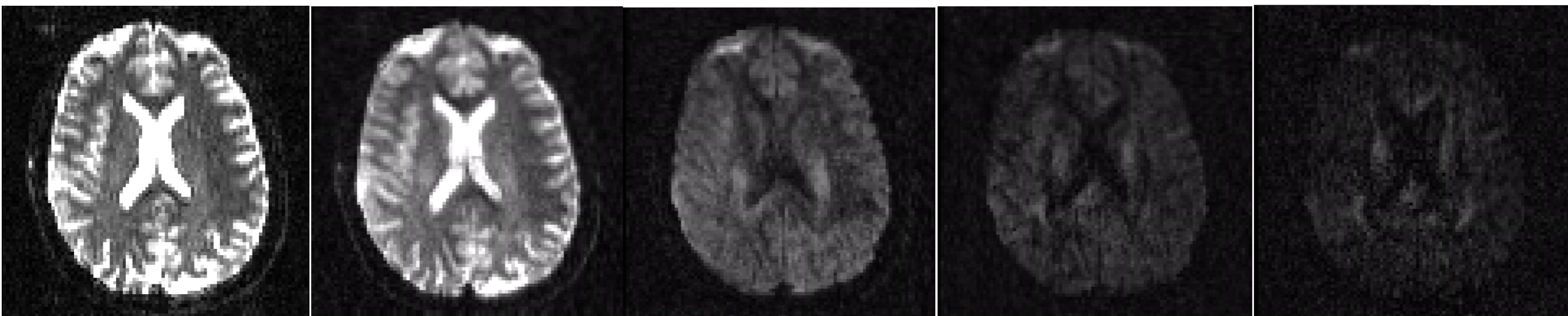
b=0

b=300

b=1000

b=2000

b=3000



More diffusion contrast with higher b :)
...But less signal left - exponential decay :(

b更高的扩散对比度
但剩下的信号减少 - 指数衰减



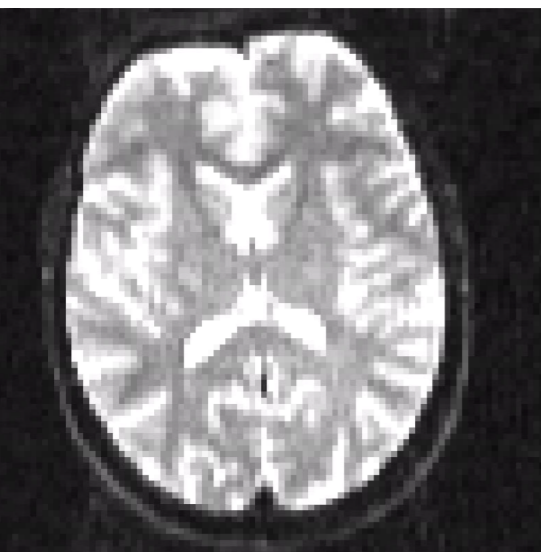
Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

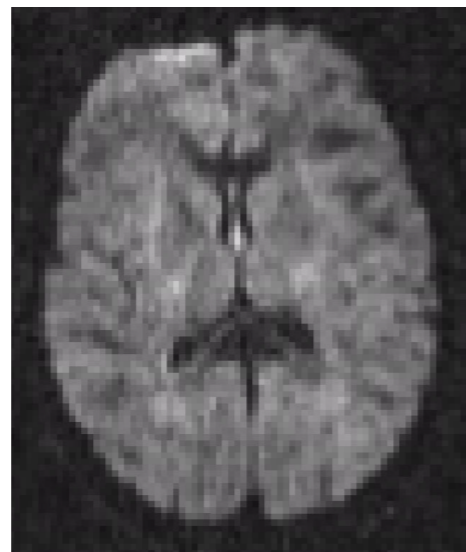
Diffusion contrast can be modulated by
B) Gradient Direction

扩散对比可以通过以下方式调节
x的梯度方向

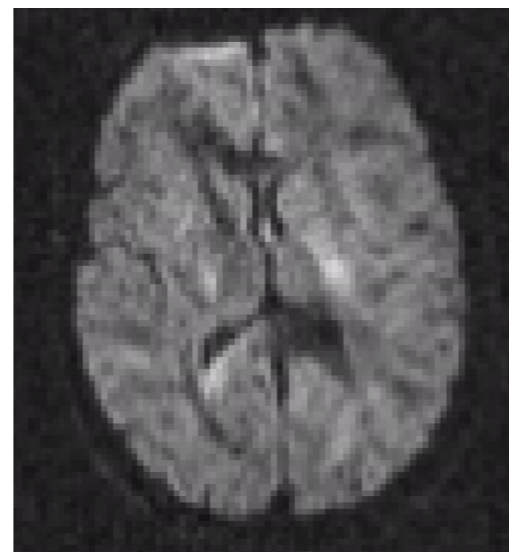
b=0



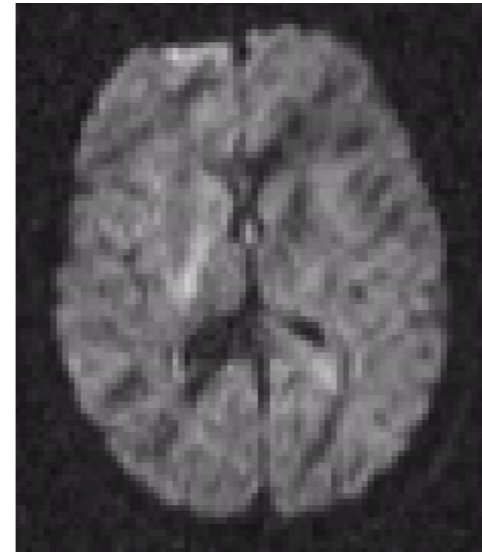
b=1000



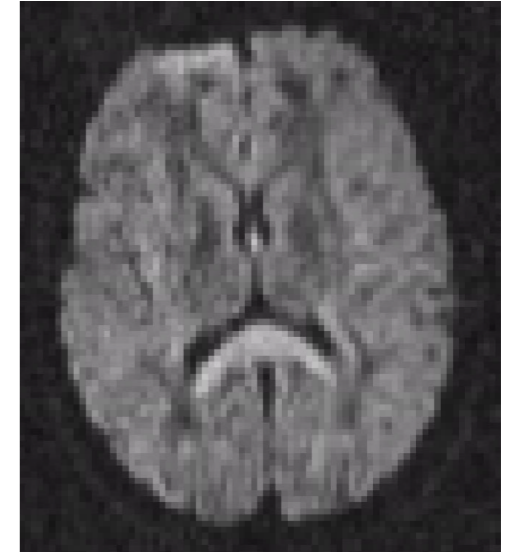
b=1000



b=1000



b=1000



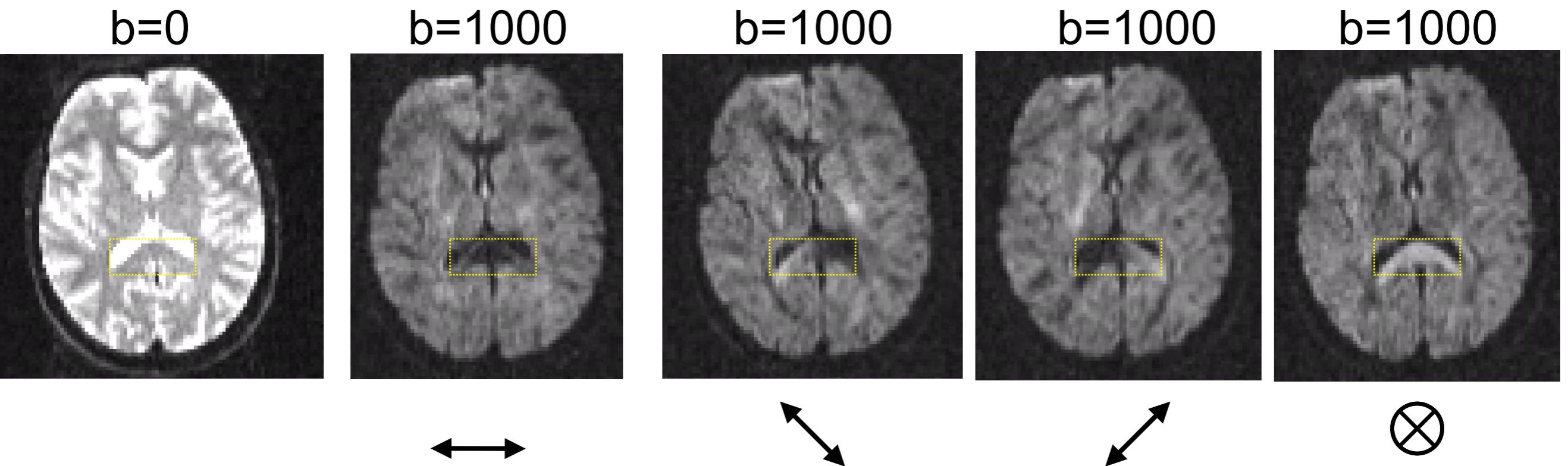


Measuring Diffusion with MRI: Diffusion-Weighted Imaging (DWI)

使用MRI测量扩散：扩散加权成像 (DWI)

Diffusion contrast can be modulated by
B) Gradient Direction

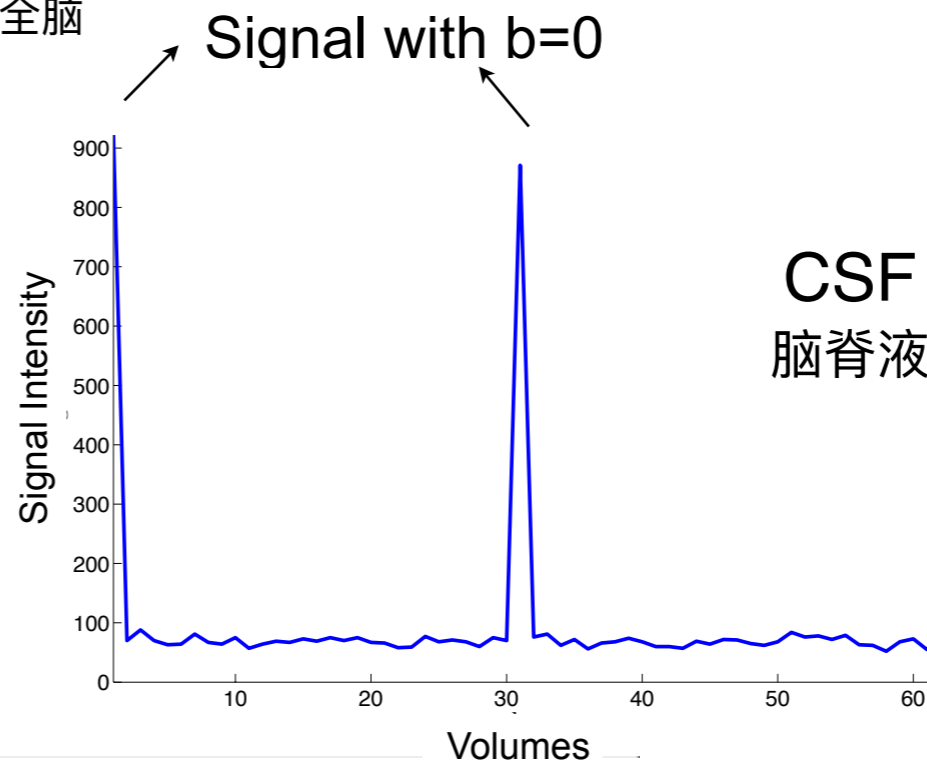
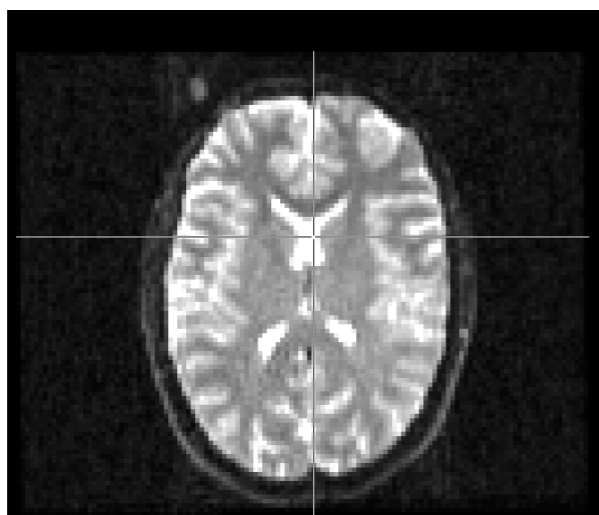
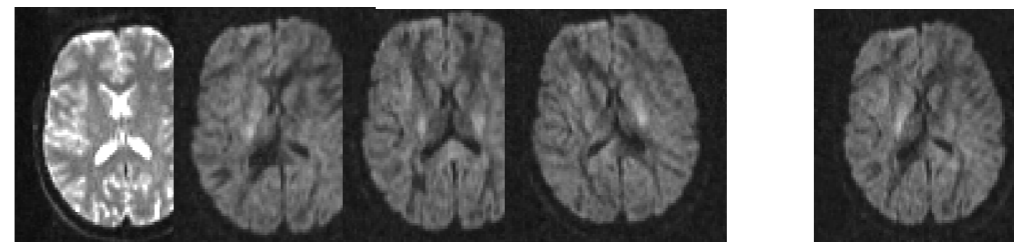
扩散对比可以通过以下方式调节
x的梯度方向





A Typical dMRI Protocol 典型的dMRI流程

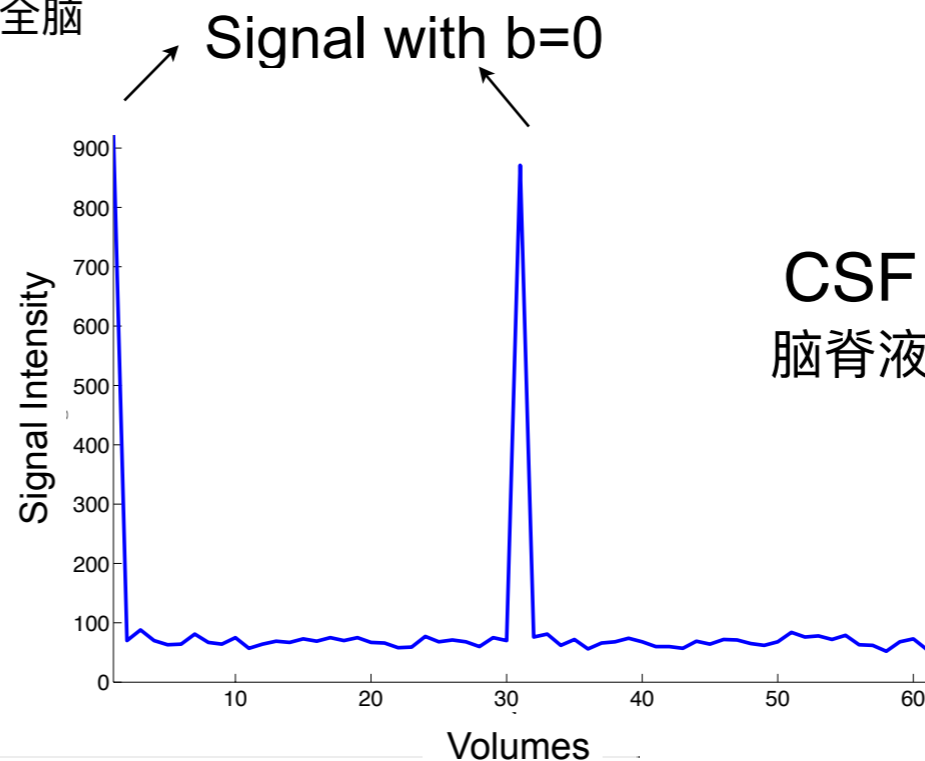
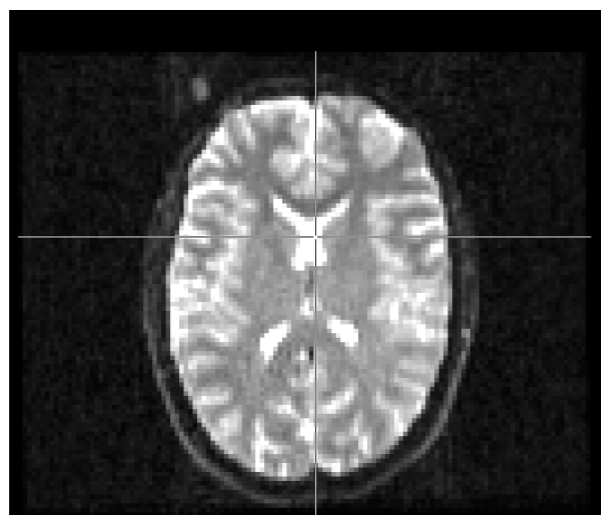
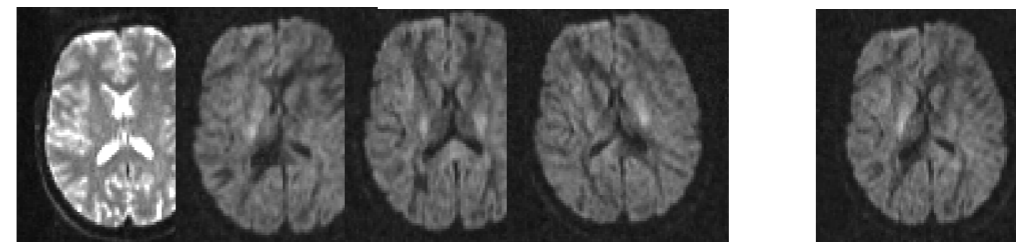
- Normally a few (at least one) $b=0$ volumes acquired, along with shells at higher b (~ 1000 s/mm²).
通常获得一些（至少一个） $b = 0$ 全脑，以及更高 b (~ 1000 s /mm²) 的壳
- A shell is a set of volumes acquired with the same b -value, but different gradient orientation
壳是使用相同的 b 值但不同的梯度方向获取的一组全脑



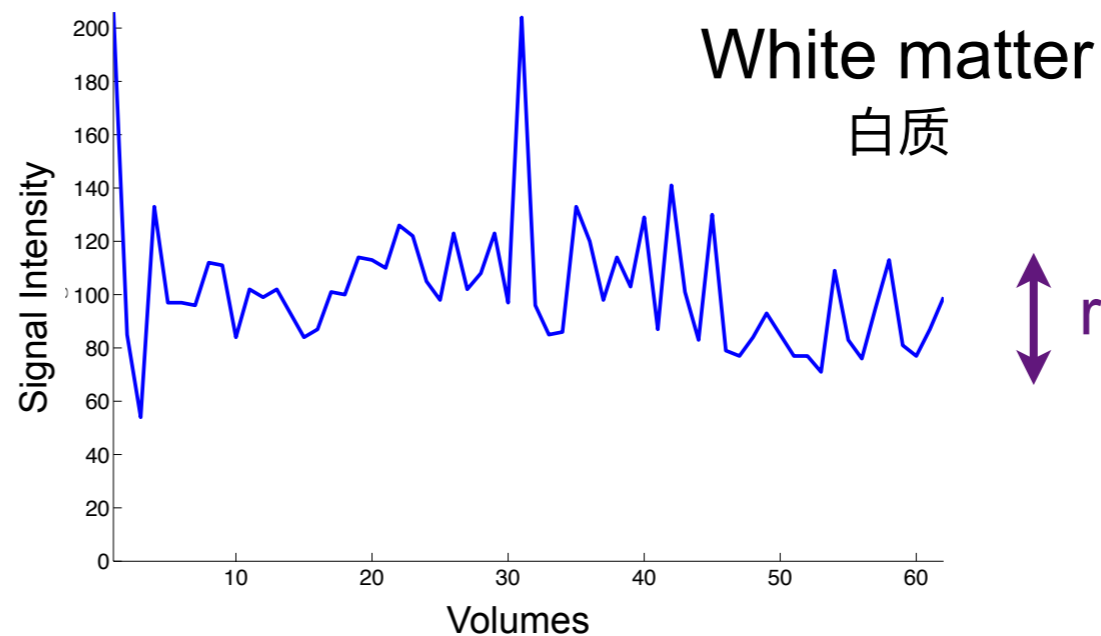


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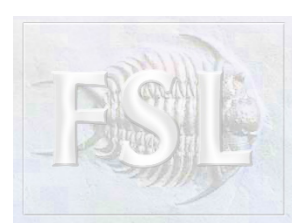
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relates to ADC
与ADC有关



relates to anisotropy
与各向异性有关



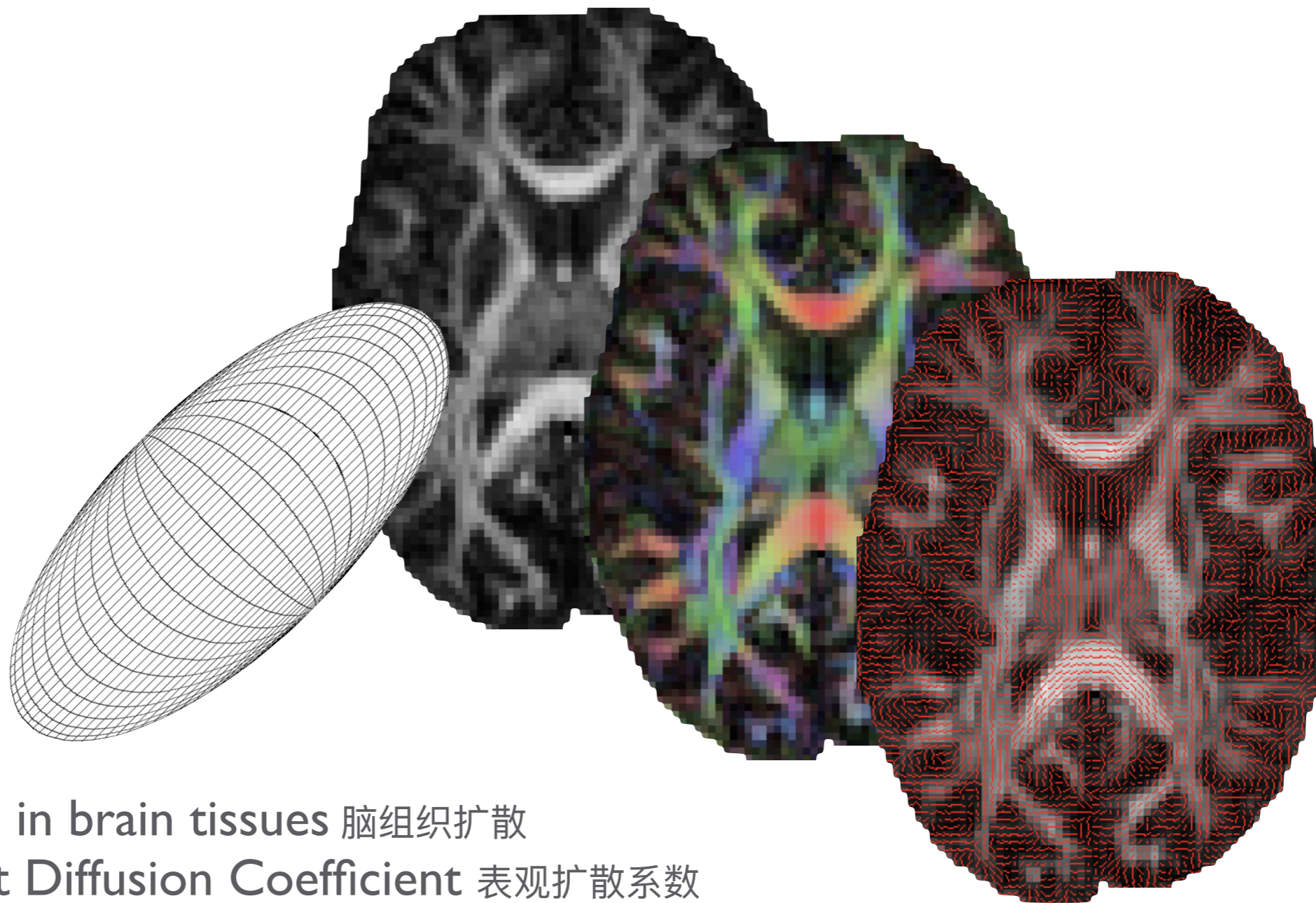
dMRI Summary 总结

- Images acquired with a Gradient along x , have contrast that is sensitive to diffusion of water molecules along x .
沿着 x 的梯度获得的图像具有对水分子沿 x 的扩散敏感的对比度。
- When diffusion occurs, signal is attenuated compared to the one with no diffusion-weighting.
当发生扩散时，与没有扩散加权的信号相比，信号衰减。
- In WM, measurements are anisotropic.
在白质中，测量是各向异性的。
- In GM and CSF, measurements are roughly isotropic.
在灰质和脑脊液中，测量大致是各向同性的。



Diffusion Tensor Imaging - basic principles

扩散张量成像 - 基本原理



- Diffusion in brain tissues 脑组织扩散
- Apparent Diffusion Coefficient 表观扩散系数
- Diffusion Tensor model 扩散张量模型
- Tensor-derived measures 张量导出的度量



Diffusion Tensor Imaging (DTI)

弥散张量成像

Diffusion Tensor Model. In each voxel:

扩散张量模型。在每个体素中：

梯度j的b值
(已知的)

b-value for gradient j
(known)

Unit vector representing the
direction of gradient j (known)

表示梯度j方向的单位向量 (已知)

$$S_j = S_0 \exp(-b_j \mathbf{x}_j^T \mathbf{D} \mathbf{x}_j)$$

Signal measured after applying
a Gradient j with direction \mathbf{x}_j and
b-value b_j (measured)

3x3 Diffusion Tensor (unknown)

3x3扩散张量 (未知)

Signal measured with no
diffusion gradient applied

测量信号，未施加扩散梯度

应用具有方向 \mathbf{x}_j 和b值 b_j (测量) 的梯度j后测量的信号

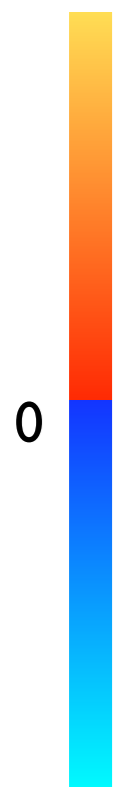


The Elements of the Diffusion Tensor

扩散张量的要素

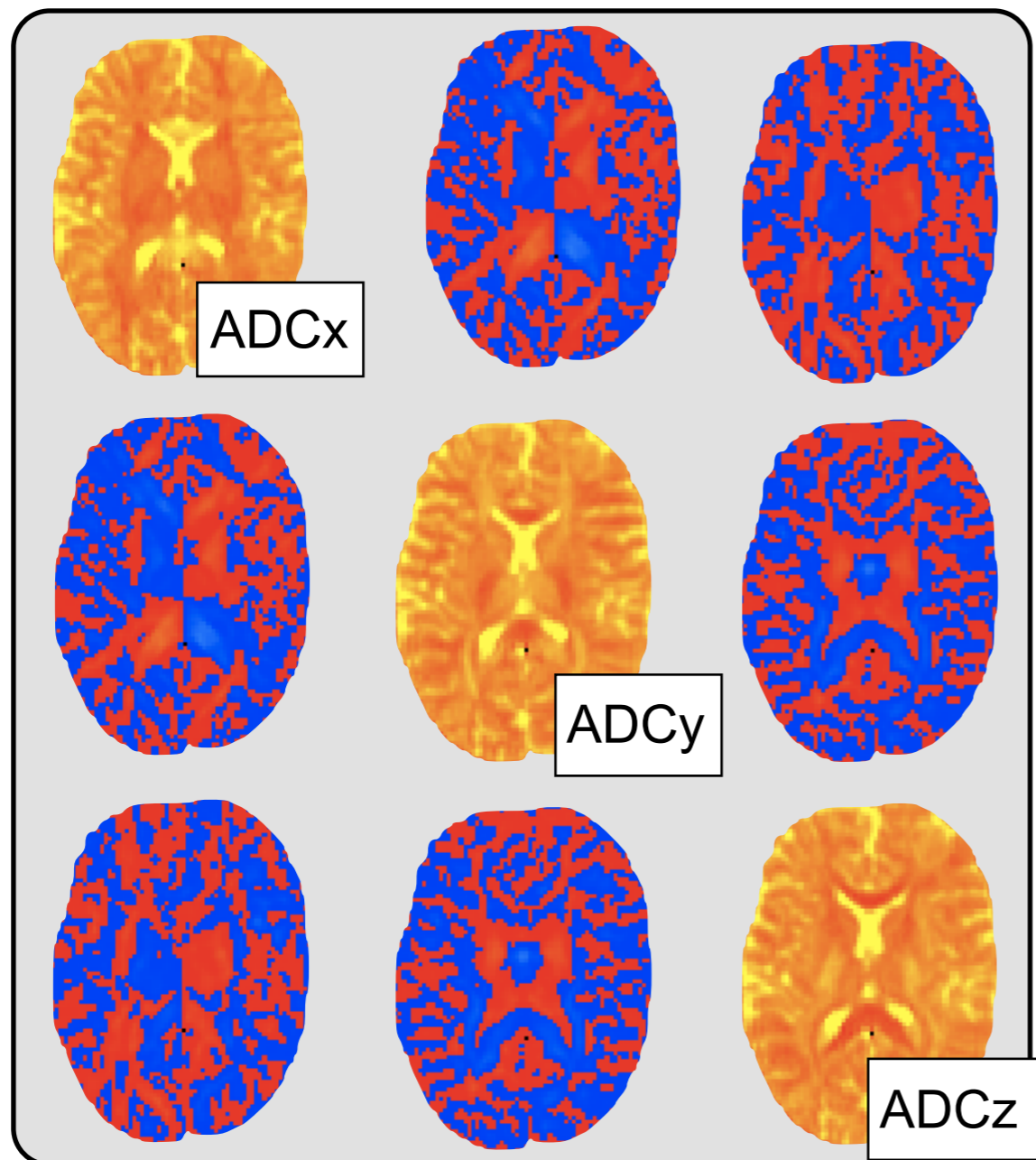
$$\mathbf{D} = \begin{bmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{bmatrix}$$

$2 \cdot 10^{-3}$
 mm^2/s



0

$-2 \cdot 10^{-3}$
 mm^2/s



- Tensor is **symmetric** (6 unknowns)
张量是对称的 (6个未知数)

- **Diagonal Elements** are proportional to the diffusion displacement variances (**ADCs**) along the three directions of the experiment coordinate system
对角线元素与沿实验坐标系的三个方向的扩散位移方差 (ADC) 成比例

- **Off-diagonal Elements** are proportional to the **correlations** (covariances) of displacements along these directions

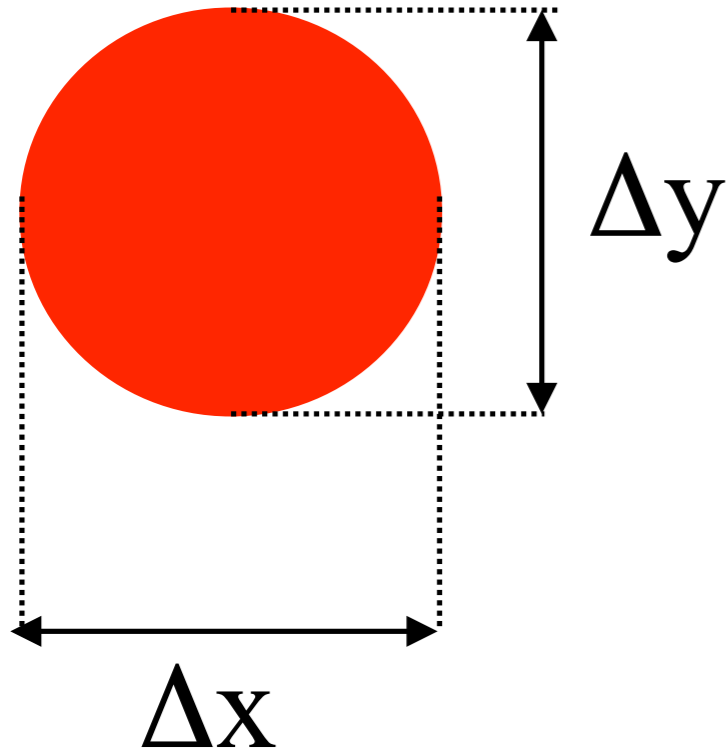
非对角线元素与沿这些方向的位移的相关性 (协方差) 成比例

$N_3(0, 2t\mathbf{D})$



Why do we need a tensor?

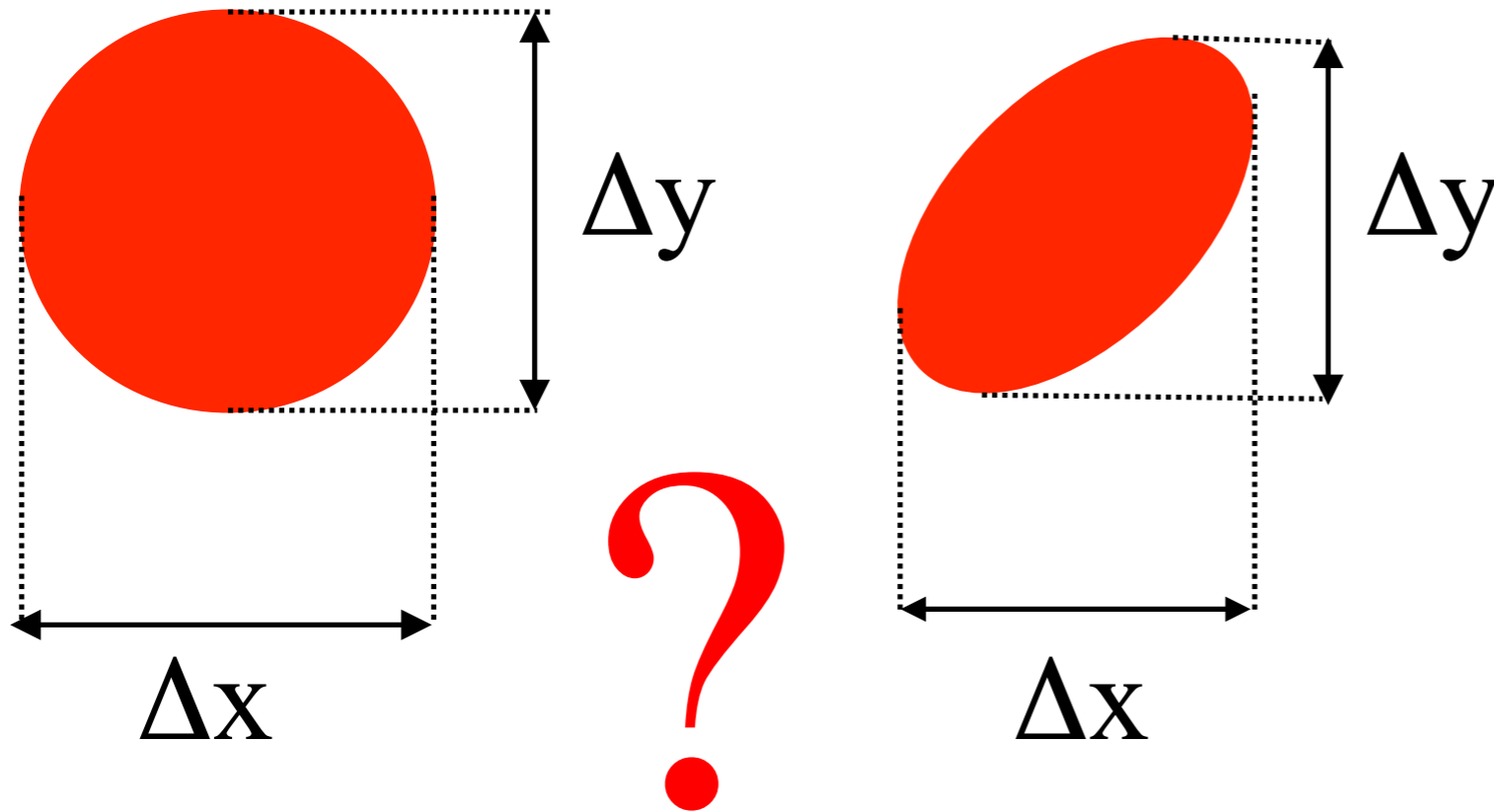
为什么我们需要张量?





Why do we need a tensor?

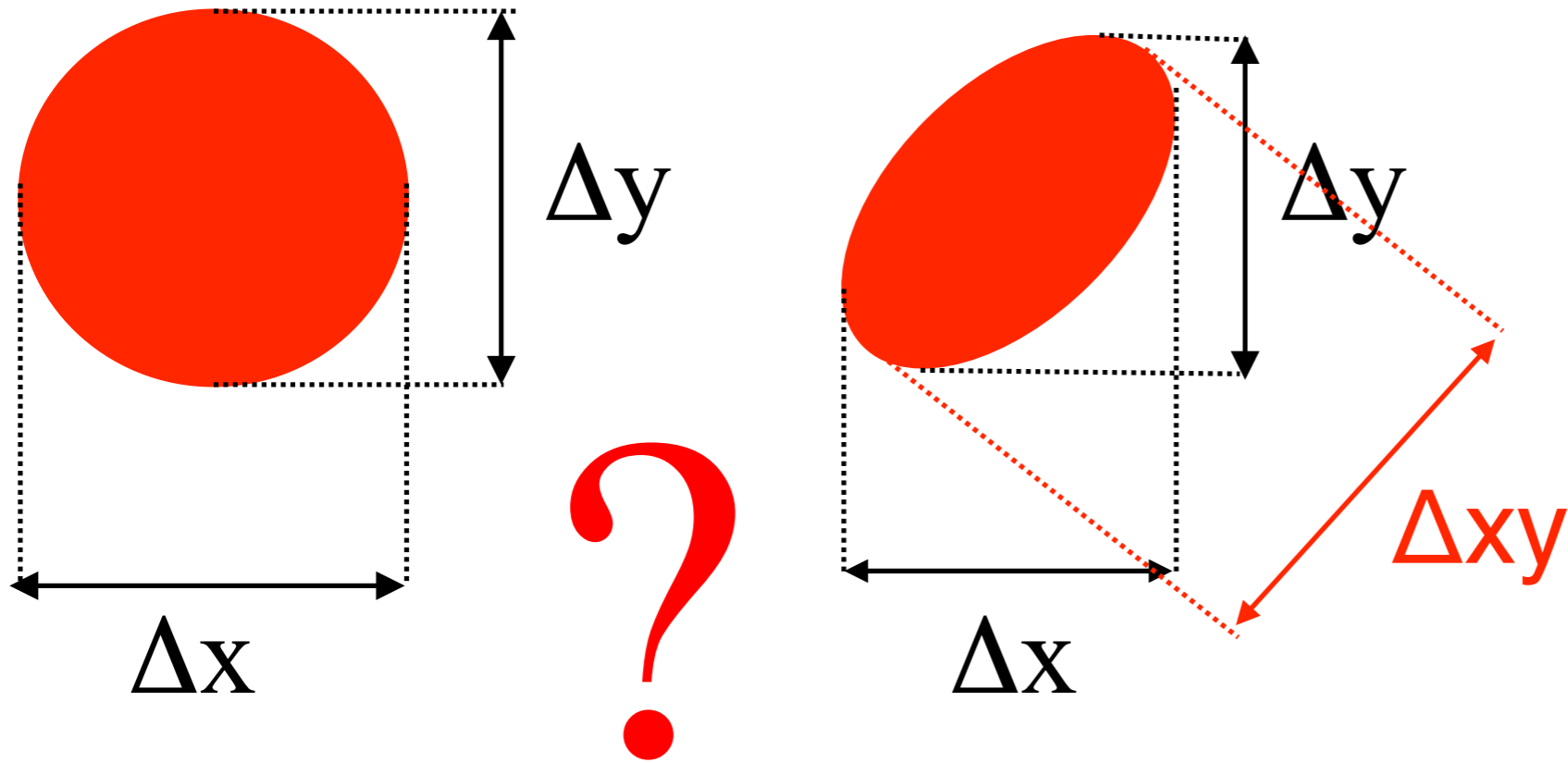
为什么我们需要张量?





Why do we need a tensor?

为什么我们需要张量?



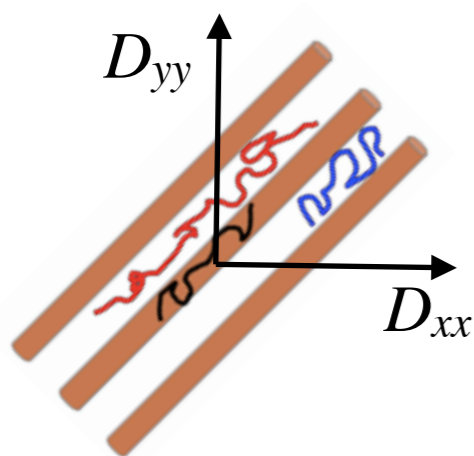
$$\begin{bmatrix} D_x & D_{xy} \\ D_{xy} & D_y \end{bmatrix}$$



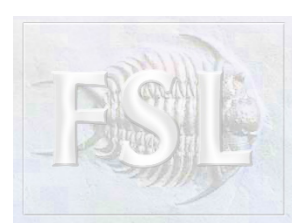
The Diffusion Tensor Eigenspectrum

弥散张量特征谱

$$\mathbf{D} = \begin{bmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{bmatrix}$$



Once \mathbf{D} is estimated, we get ADCs along the scanner's coordinate system. But we want ADCs along a local coordinate system in each voxel, determined by the anatomy. 一旦 \mathbf{D} 被估计, 我们就可以沿着扫描仪的坐标系得到ADC。但我们希望ADC沿着每个体素的局部坐标系, 由解剖学决定

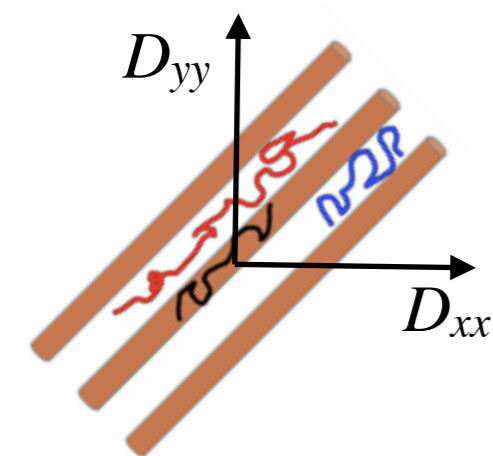
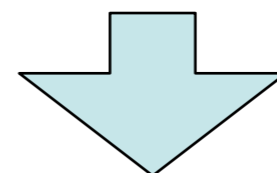


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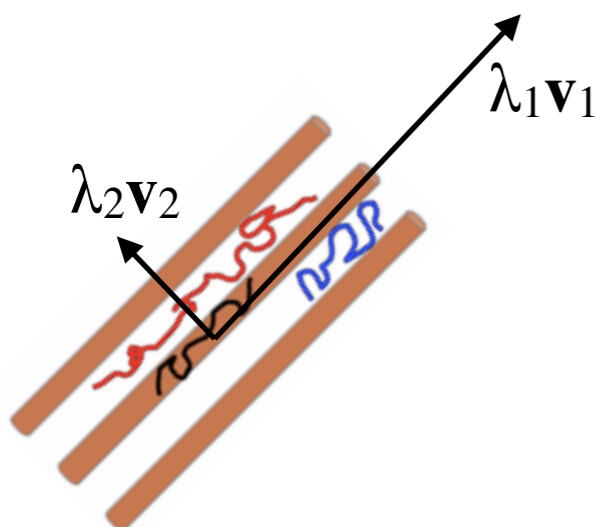
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Diagonalize the estimated tensor in each voxel

对角化每个体素中的估计张量

$$\mathbf{D} = [\mathbf{v}_1 | \mathbf{v}_2 | \mathbf{v}_3]^T \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} [\mathbf{v}_1 | \mathbf{v}_2 | \mathbf{v}_3]$$



eigenvalues: ADCs along $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ 特征值: 沿 $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ 的 ADC

eigenvectors - \mathbf{v}_1 =direction of max diffusivity 特征向量 值- \mathbf{v}_1 =最大扩散方向



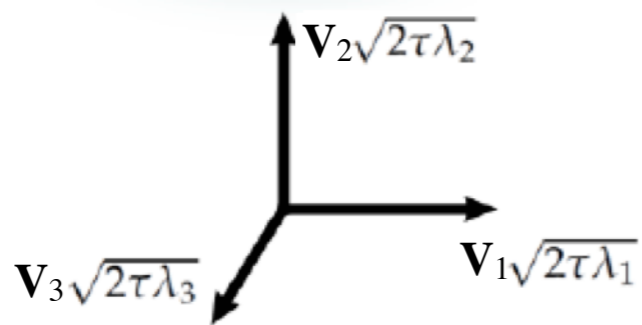
The Diffusion Tensor Ellipsoid

扩散张量椭球

Isotropic voxel

各向同性体素

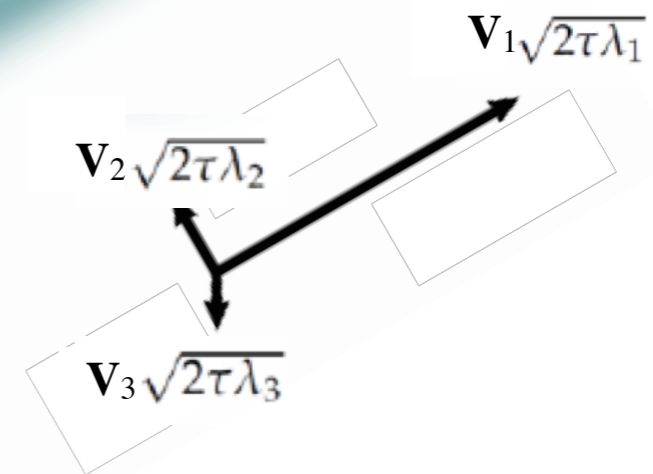
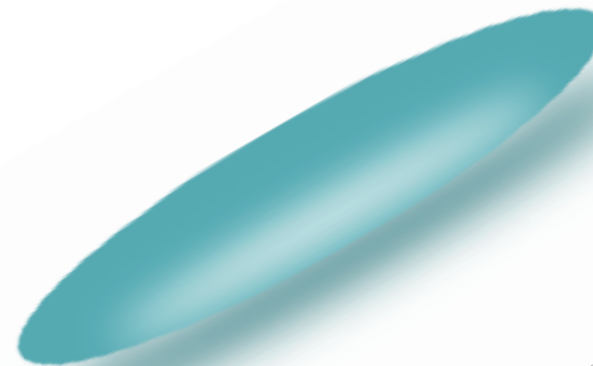
$$\lambda_1 \approx \lambda_2 \approx \lambda_3$$



Anisotropic voxel

各向异性体素

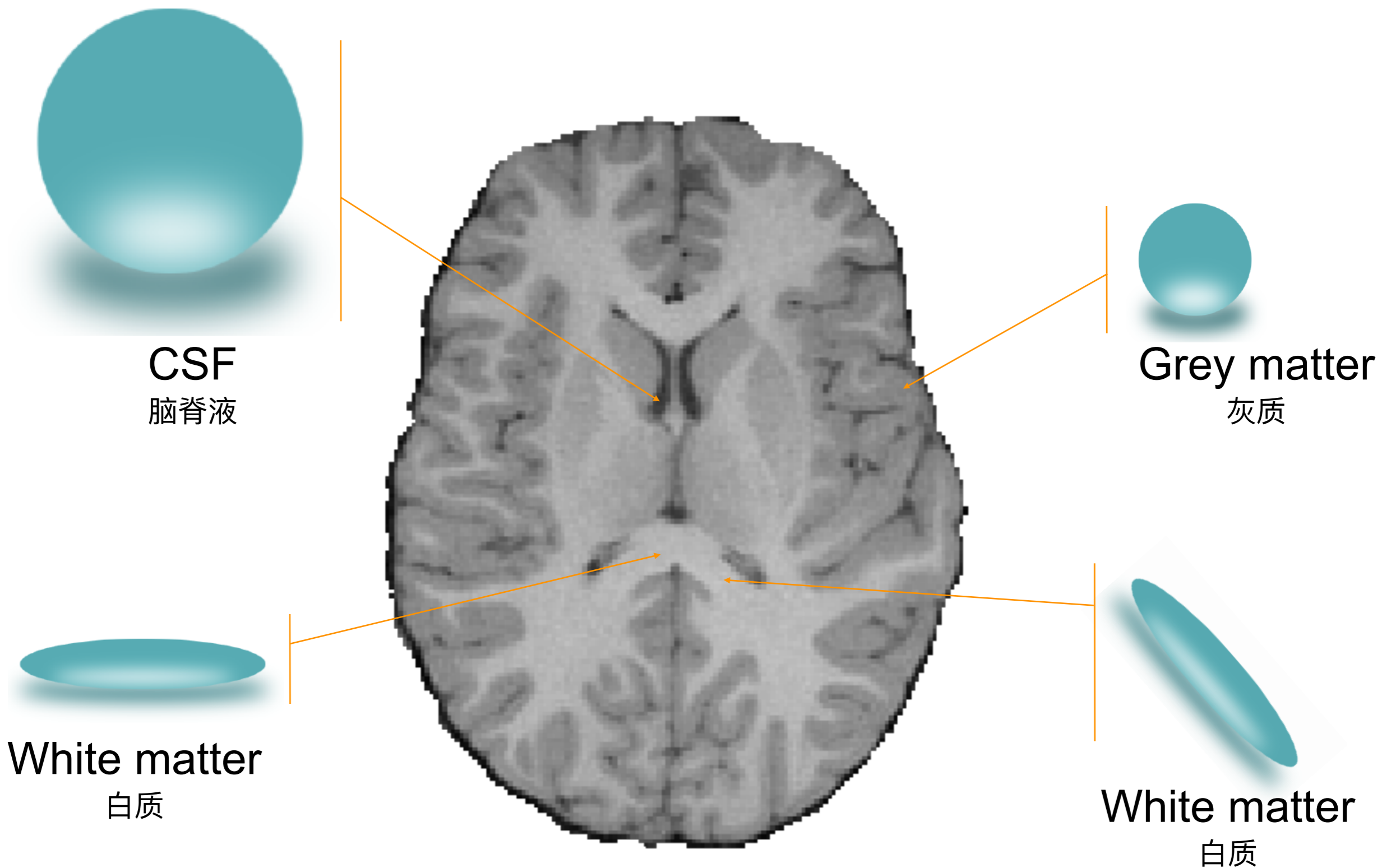
$$\lambda_1 \gg \lambda_2, \lambda_3$$





The Diffusion Tensor Ellipsoid

扩散张量椭球





Quantitative Diffusion Maps 定量扩散图

Fractional Anisotropy (FA) ~ Eigenvalues Variance (normalised)

Mean Diffusivity (MD) = Eigenvalues Mean

分数各向异性 (FA) ~ 特征值方差 (归一化)

平均扩散率 (MD) = 特征值均值

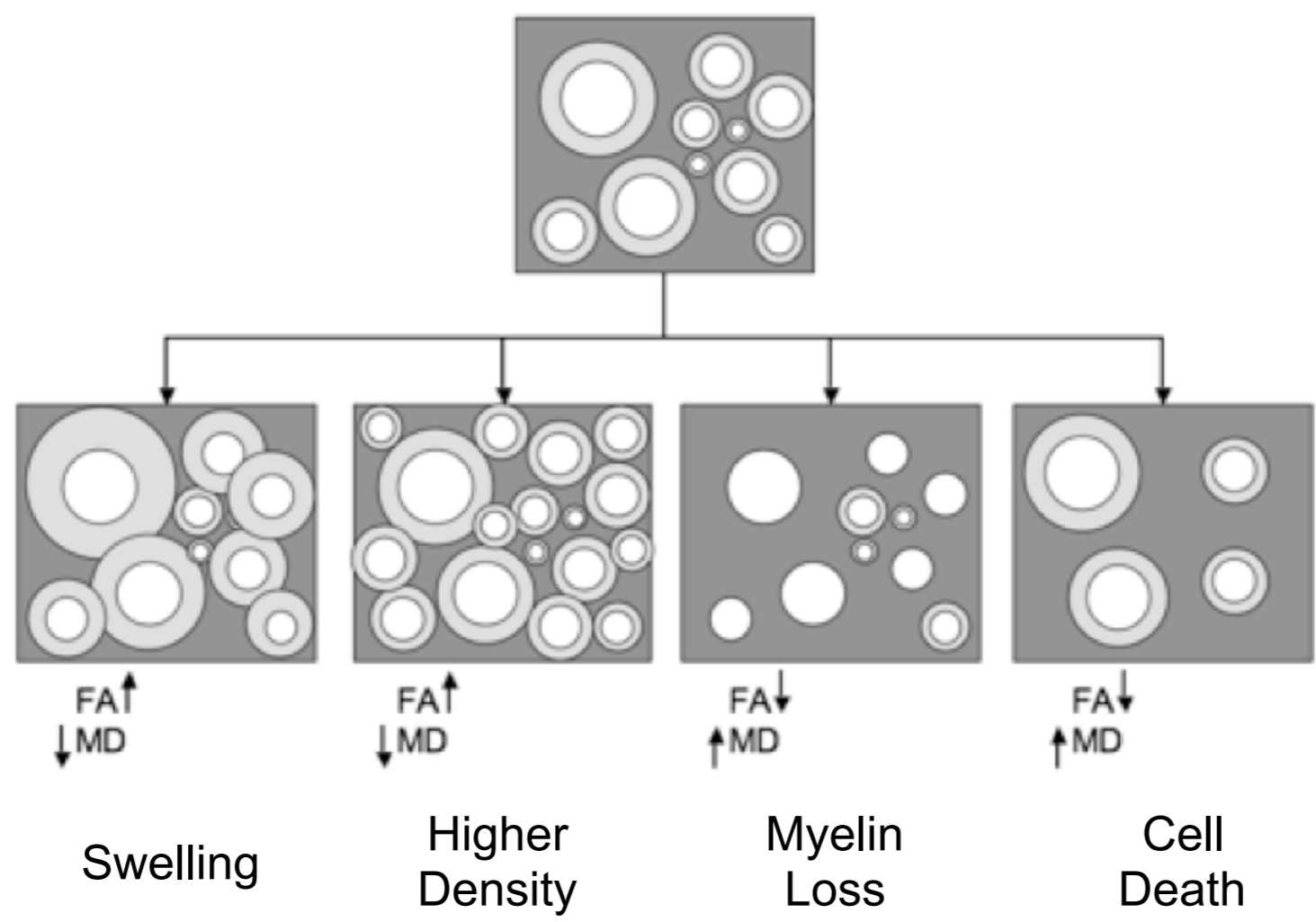
$$FA = \sqrt{\frac{3 \sum_{i=1}^3 (\lambda_i - \bar{\lambda})^2}{2 \sum_{i=1}^3 \lambda_i^2}}, \quad FA \text{ in } [0,1]$$

$$MD = \frac{D_{xx} + D_{yy} + D_{zz}}{3} = \frac{\lambda_1 + \lambda_2 + \lambda_3}{3}$$



Quantitative Diffusion Maps 定量扩散图

Different scenarios can have same effect on FA, MD
不同的场可以对FA, MD产生相同的影响

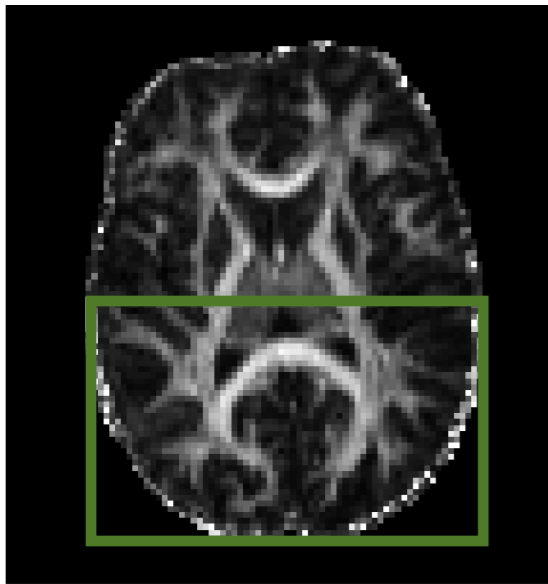




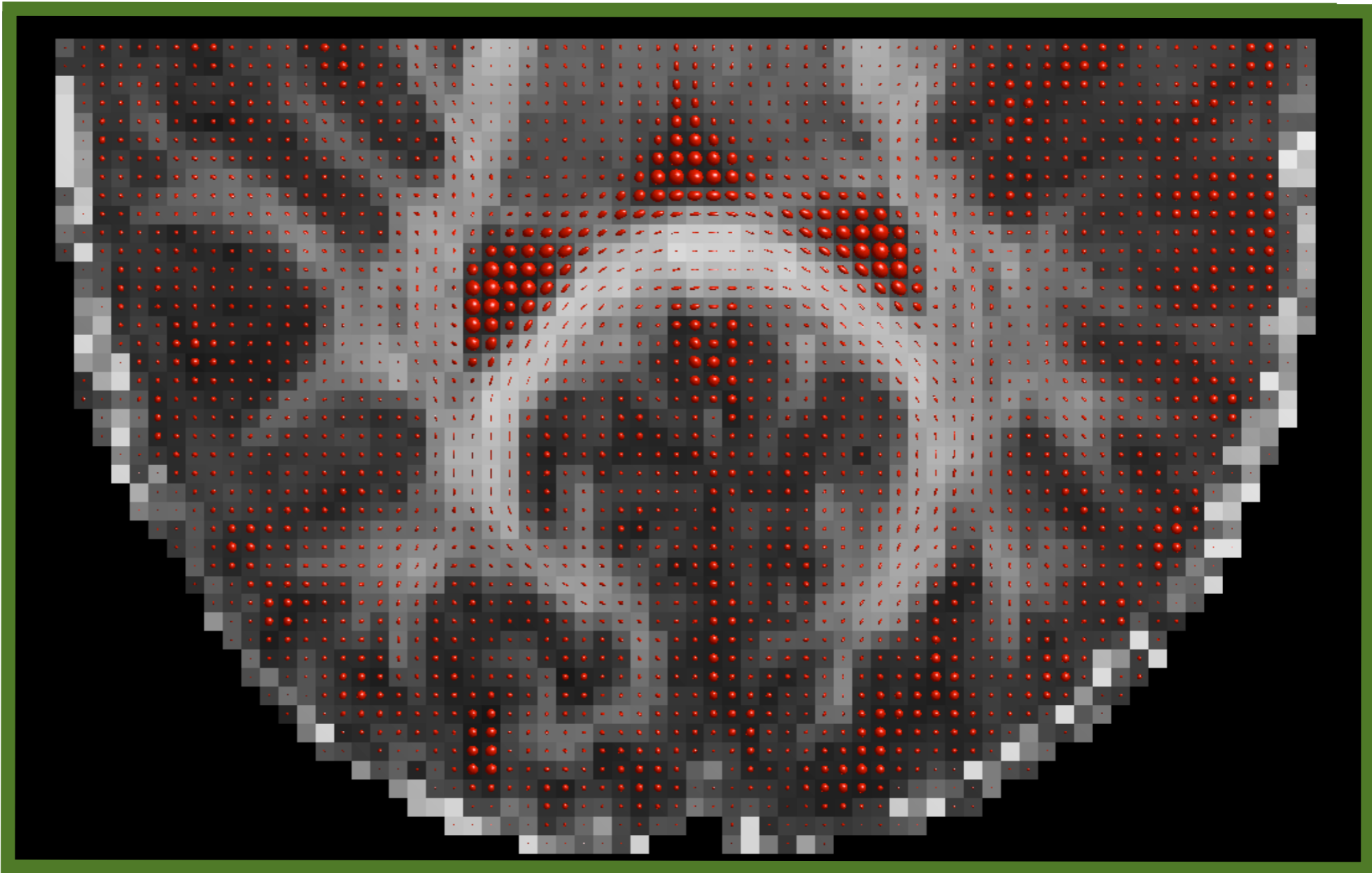
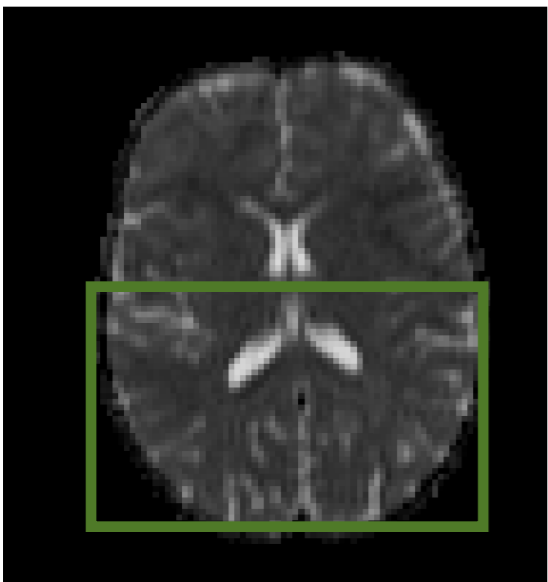
Diffusion Tensor Ellipsoids

扩散张量椭圆体

分数各向异性
Fractional anisotropy



Mean diffusion 平均弥散

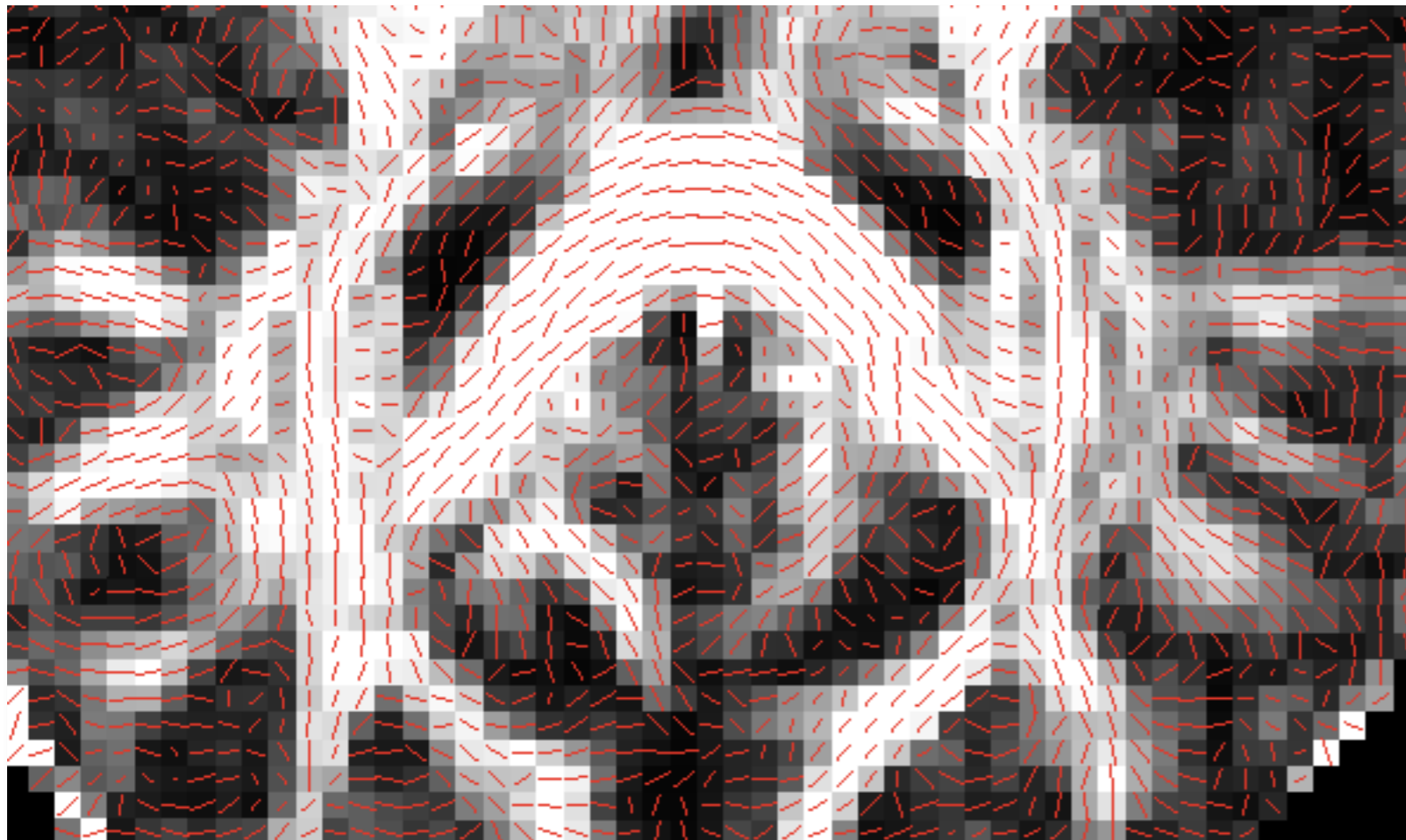




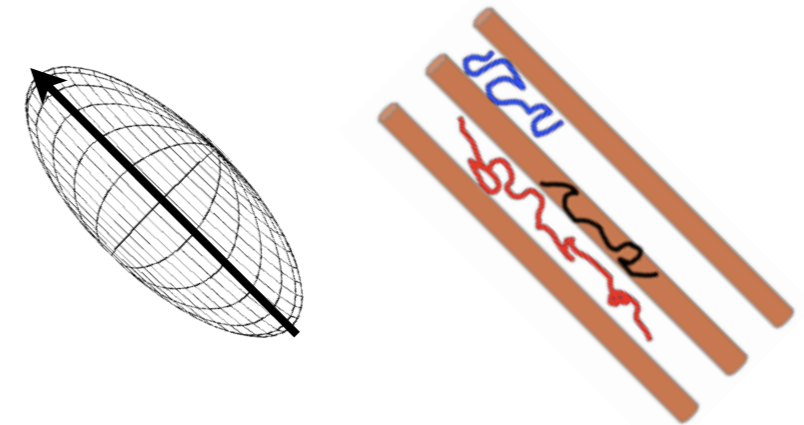
Estimates of Principal Fibre Orientation in WM

WM中主要纤维取向的估算

v_1 map
Principal Diffusion Direction
主扩散方向



Principal Diffusion
Direction
主扩散方向



Assumption!! 假设!

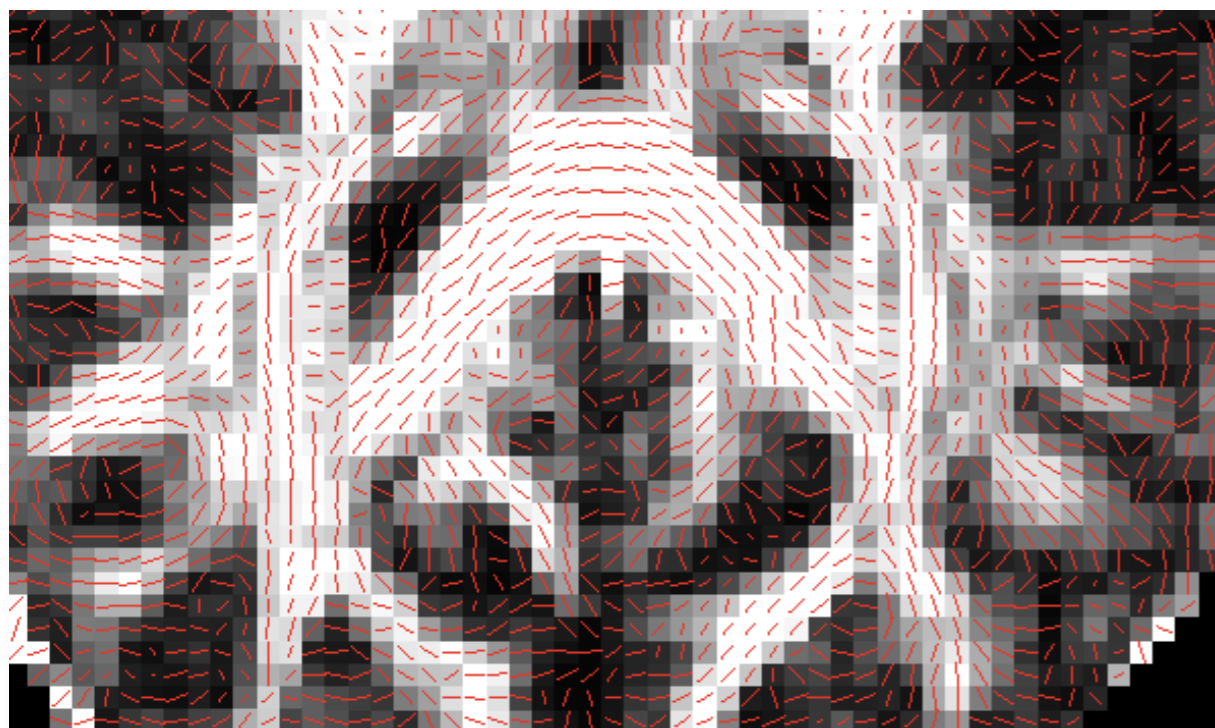
Direction of maximum diffusivity in voxels with anisotropic profile is an estimate of the major fibre orientation.

具有各向异性轮廓的体素中的最大扩散率的方向是主要纤维取向的估计。



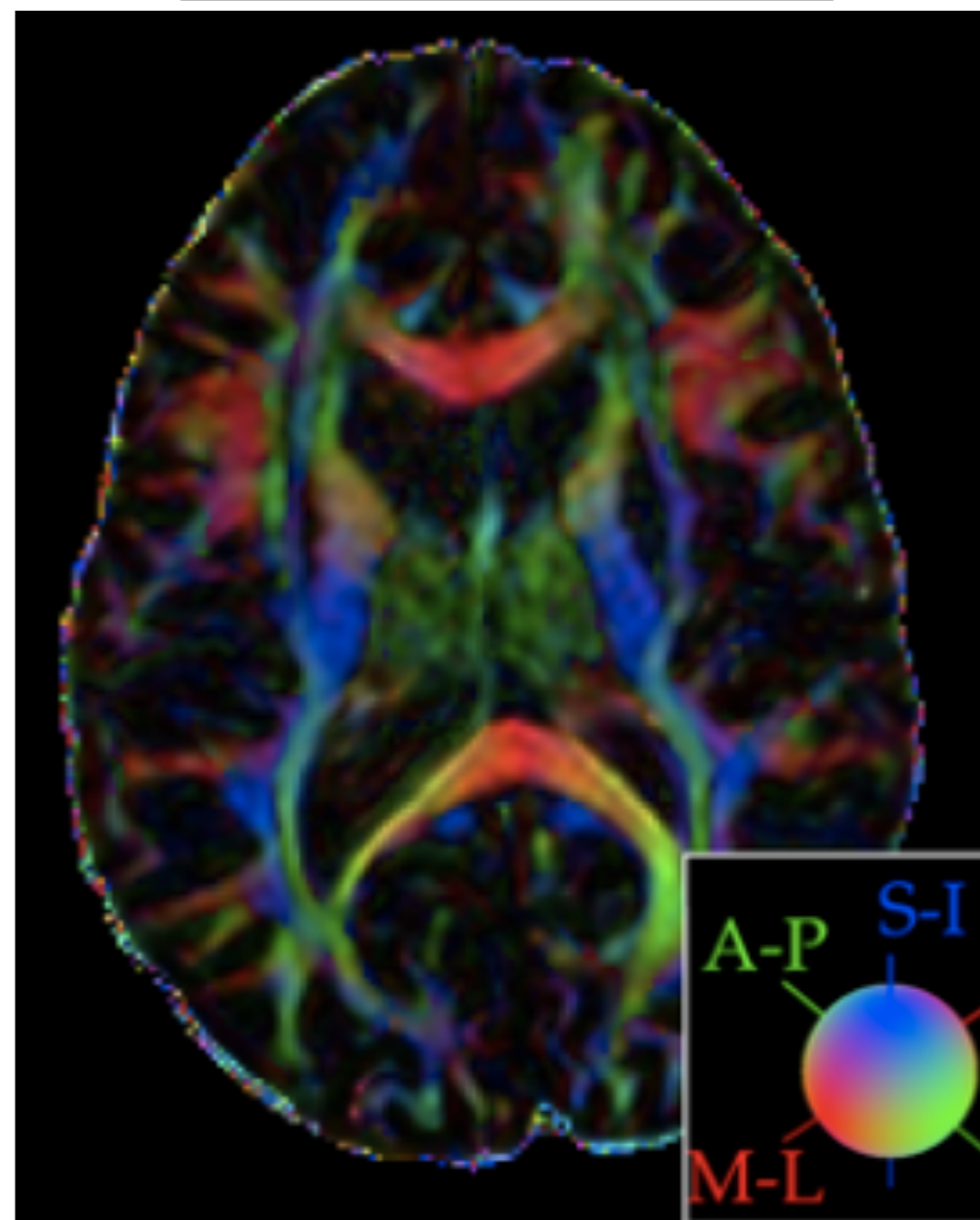
Estimates of Principal Fibre Orientation in WM

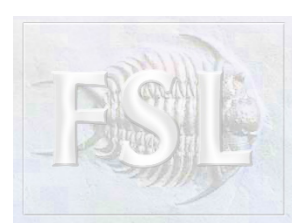
WM中主要纤维取向的估算



彩色编码的v1地图

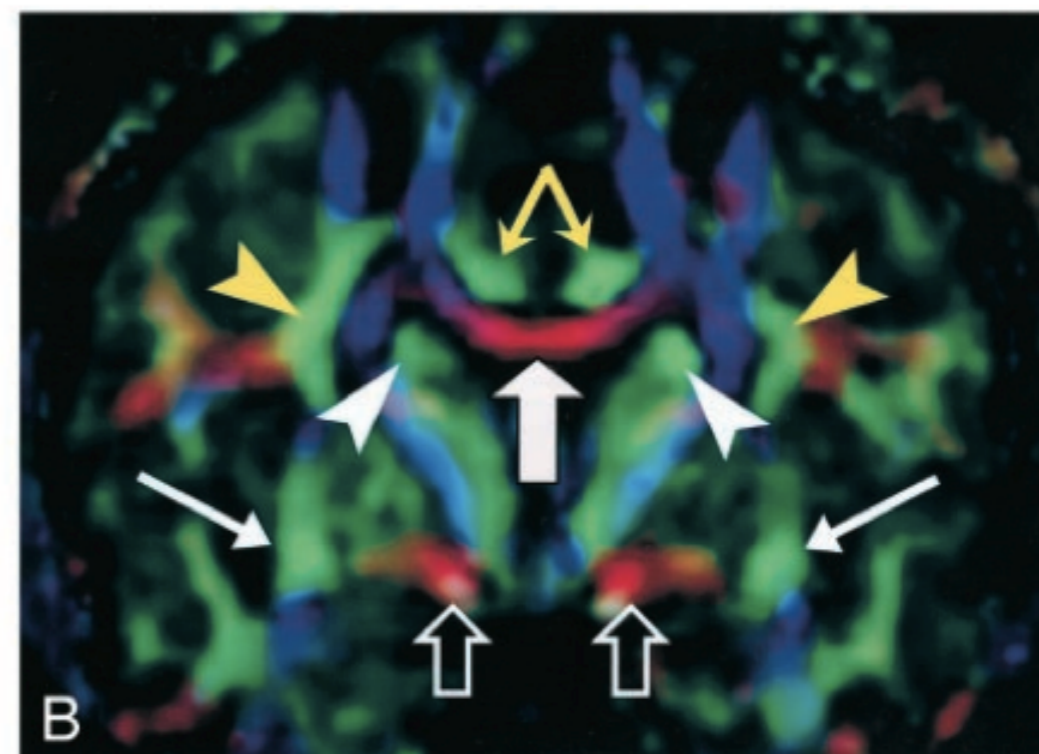
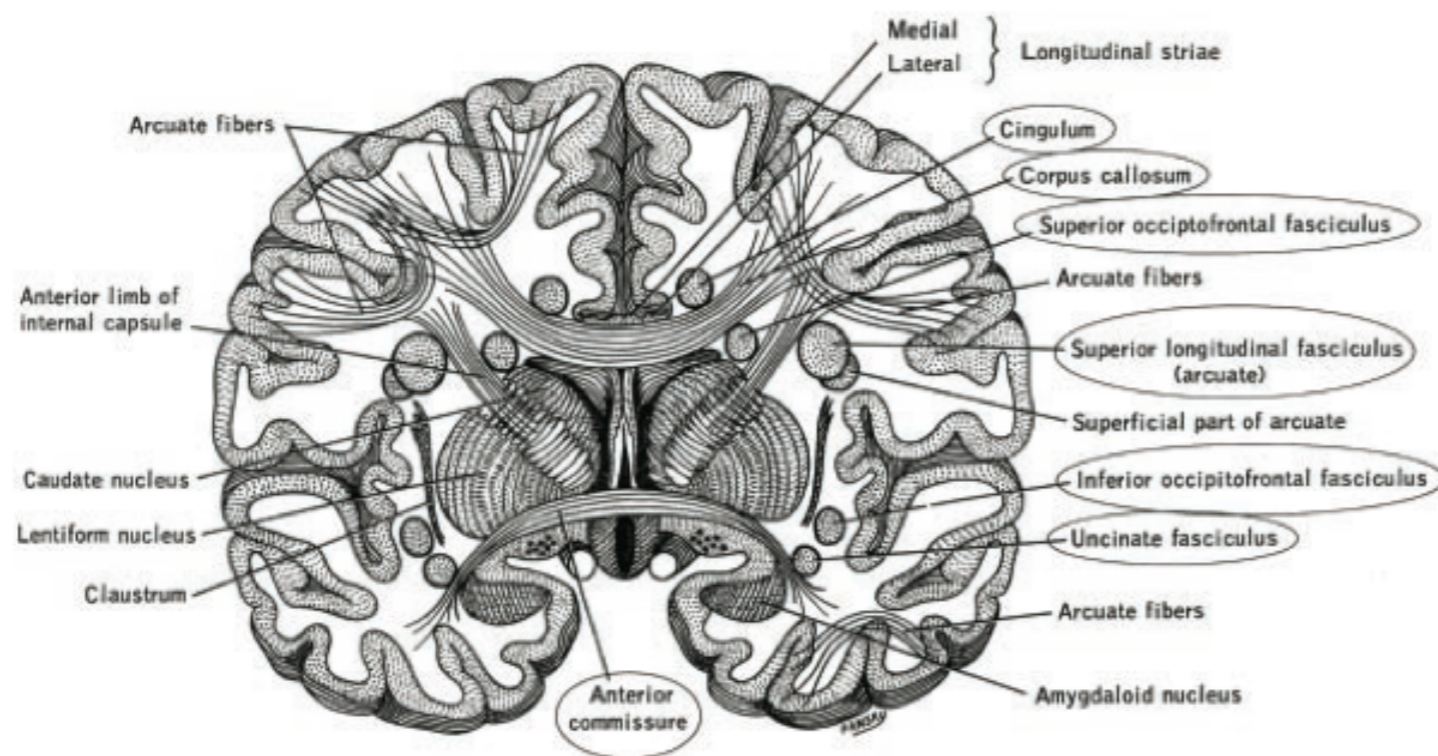
Colour-coded v_1 map





Estimates of Principle Fibre Orientation in WM

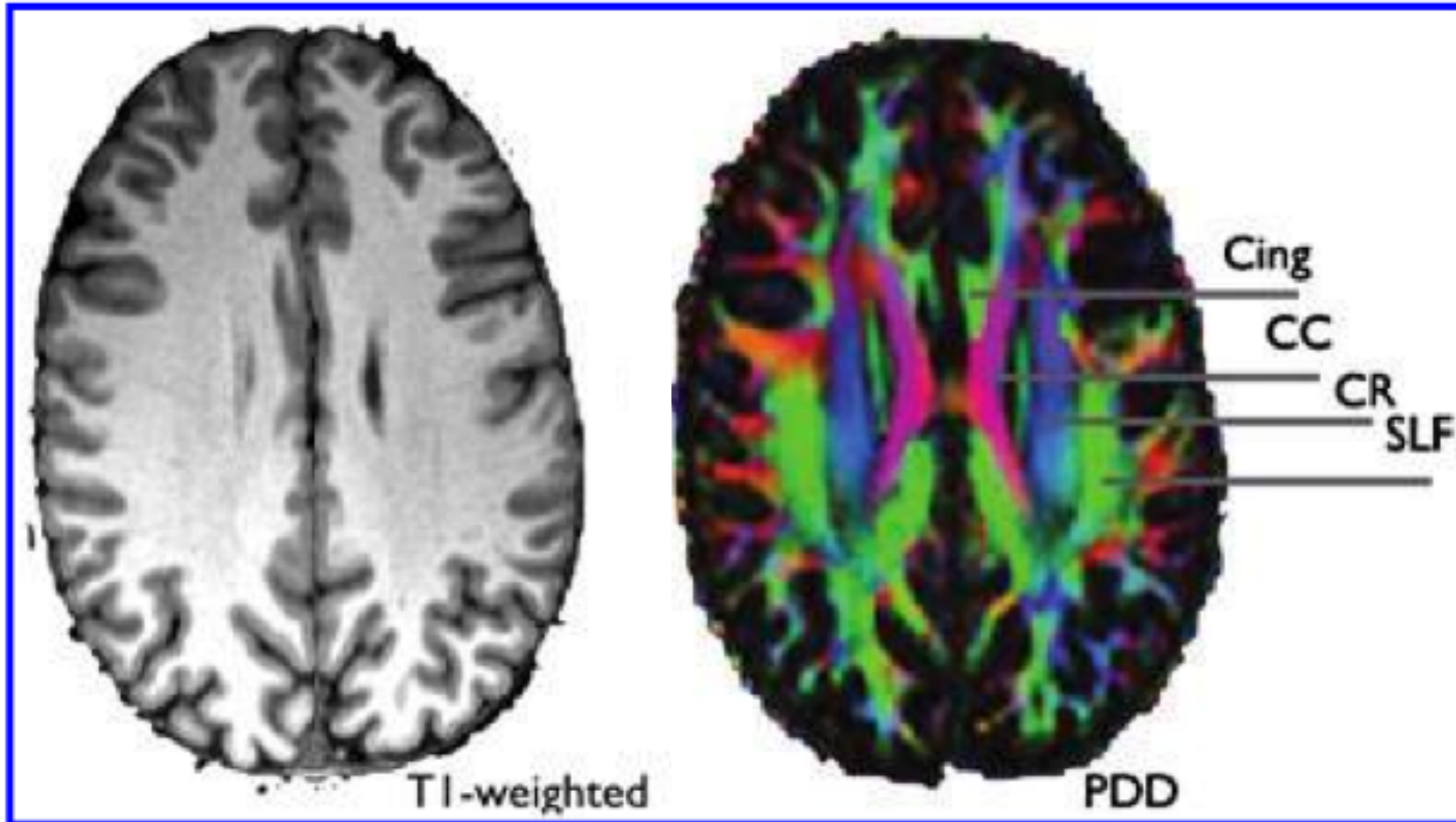
WM中原理纤维取向的估算





Directional contrast in DTI

DTI中的方向对比



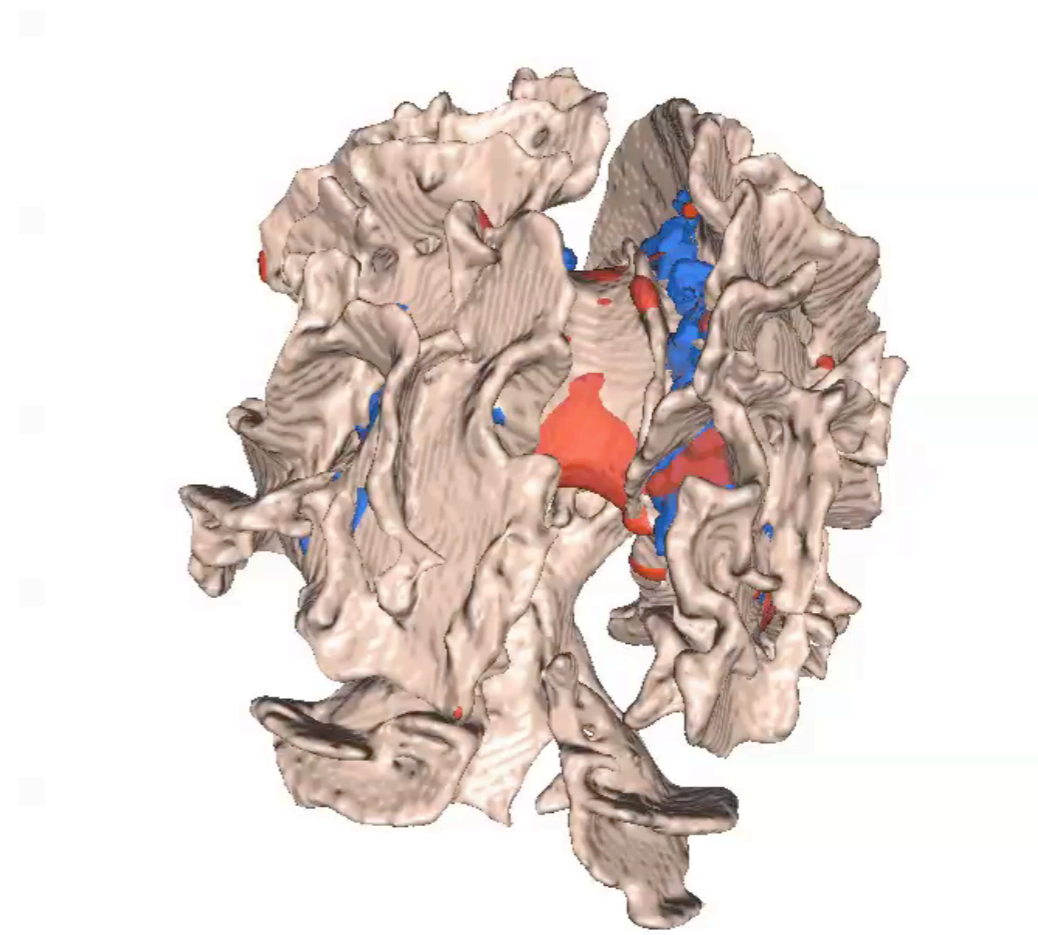
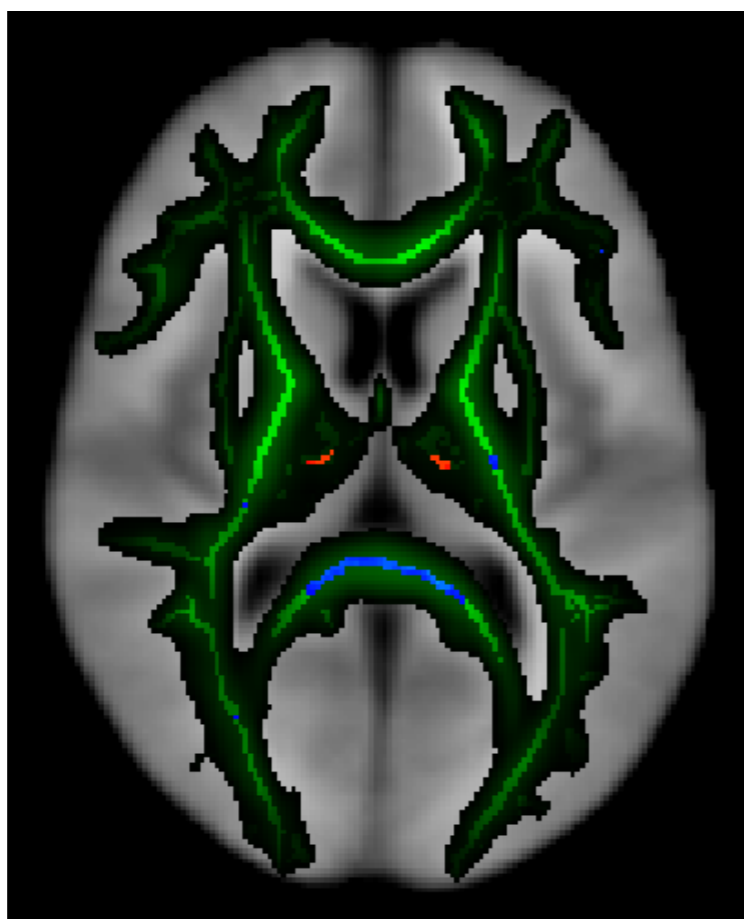


TBSS : Tract-Based Spatial Statistics

TBSS: 基于白质纤维束骨架的空间统计分析

Robust “voxelwise” cross-subject stats
on diffusion-derived measures

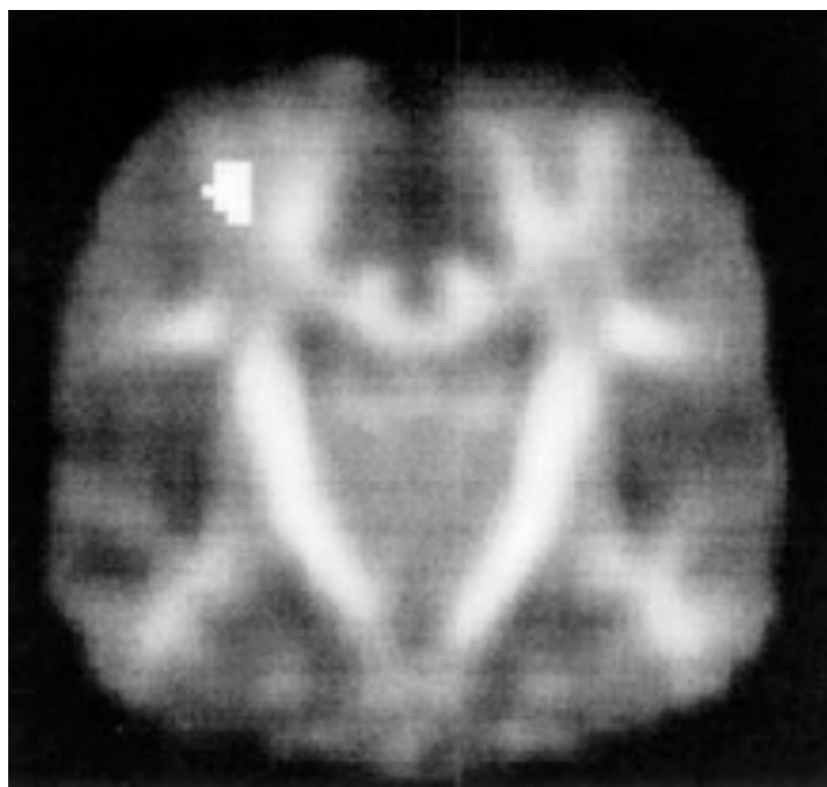
被试间基于体素的稳健的扩散统计方法



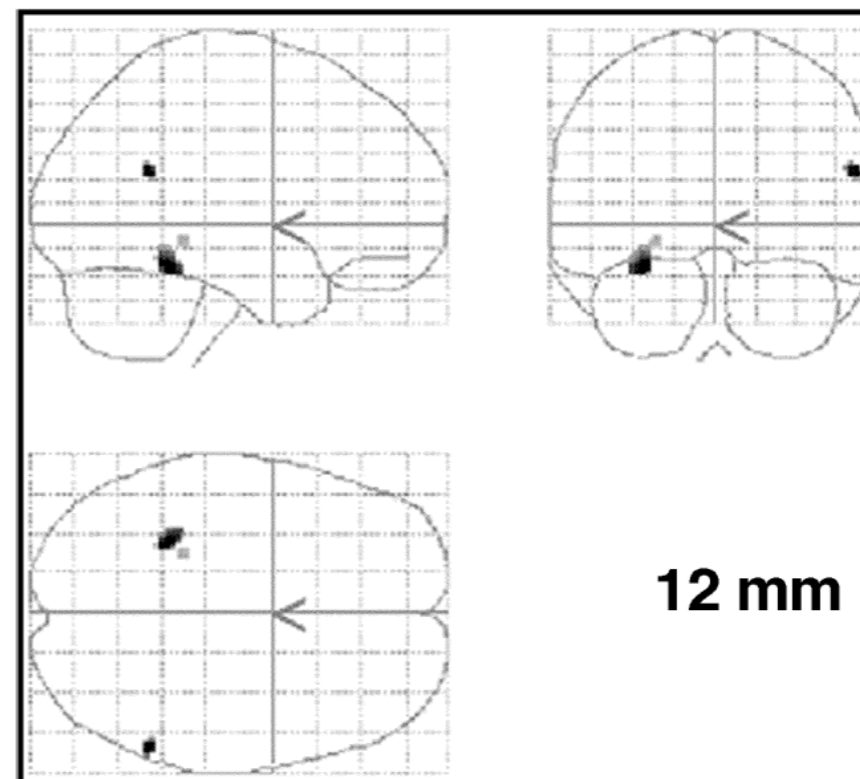


VBM-style Analysis of FA 基于VBM的FA分析

- VBM [Ashburner 2000, Good 2001]
- Align all subjects' data to standard space 所有被试配到标准空间
- Segment -> grey matter segmentation 分割-灰质分割
- Smooth GM 灰质平滑
- Do voxelwise stats (e.g. controls-patients) 体素统计
- VBM on FA [Rugg-Gunn 2001, Büchel 2004, Simon 2005]
- Like VBM but no segmentation needed 像VBM一样但不需要分割



Büchel 2004

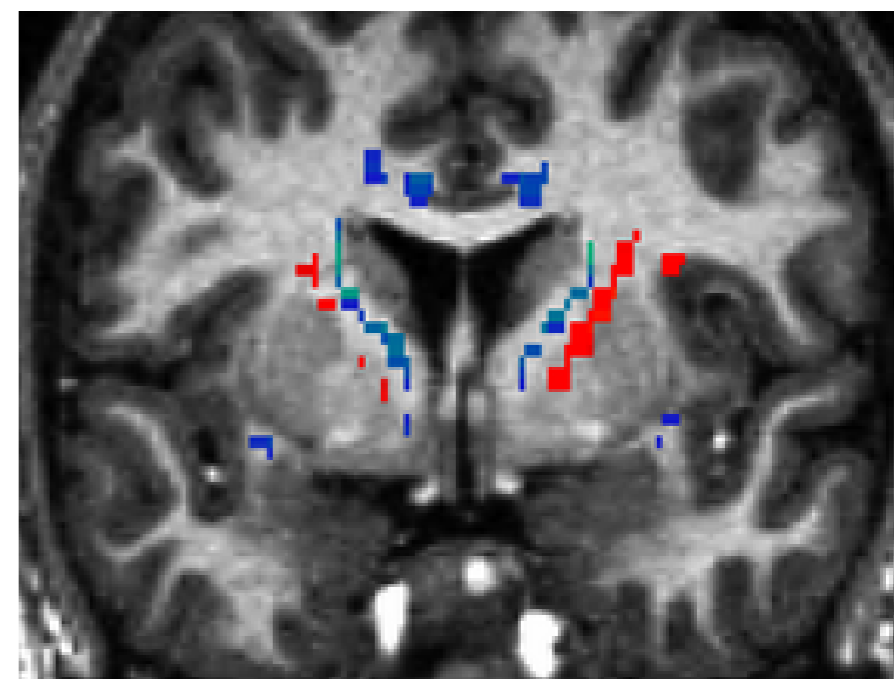
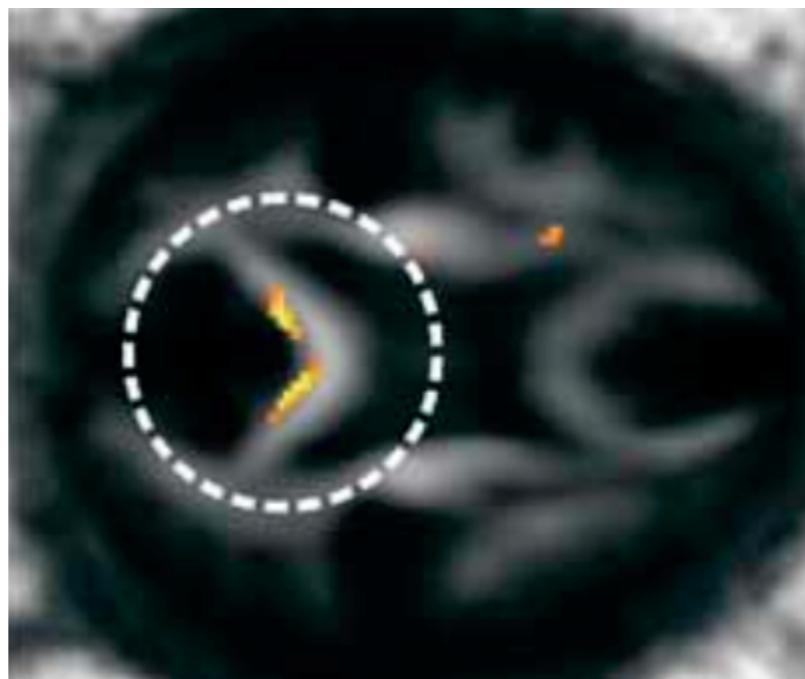
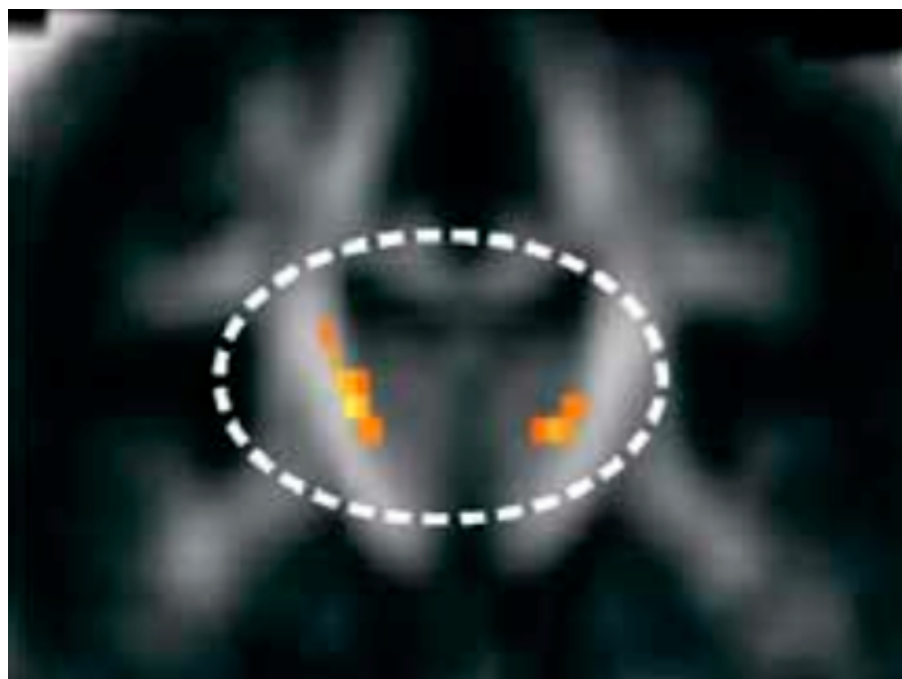


Jones 2005



VBM-style Analysis of FA 基于VBM的FA分析

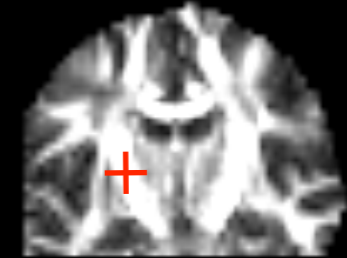
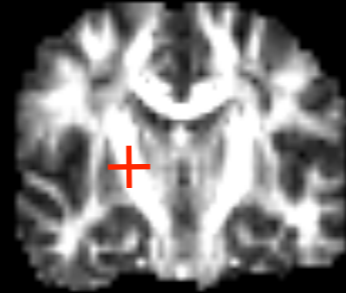
- Strengths 优点
 - Fully automated & quick 完全自动化和快速
 - Investigates whole brain 全脑分析
- Problems [Bookstein 2001, Davatzikos 2004, Jones 2005] 缺陷
 - Alignment difficult; smallest systematic shifts between groups can be incorrectly interpreted as FA change
对齐困难;组间最小的系统偏移可能被错误地解释为FA变化
 - Needs smoothing to help with registration problems 需要平滑来解决配准问题
 - No objective way to choose smoothing extent 没有客观的方法来选择平滑程度





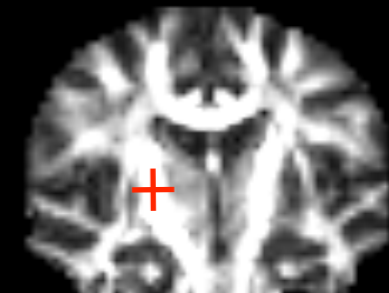
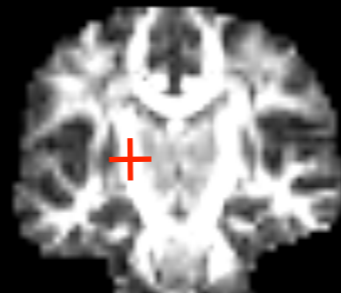
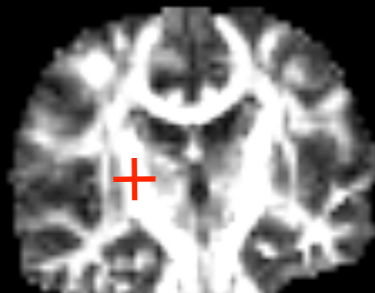
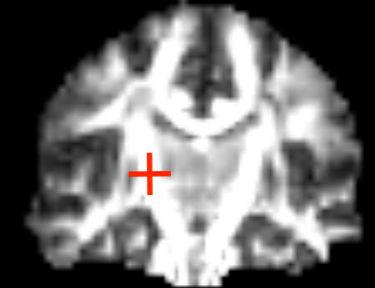
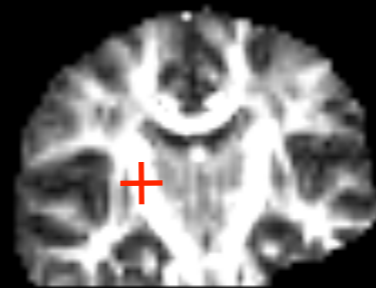
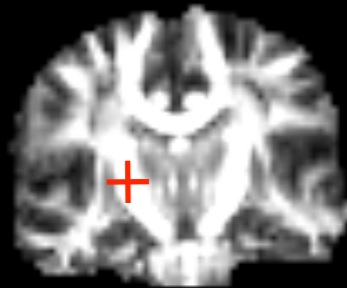
Hand-placed voxel/ROI-based FA Comparison

基于手动绘制的体素/ROI FA 比较



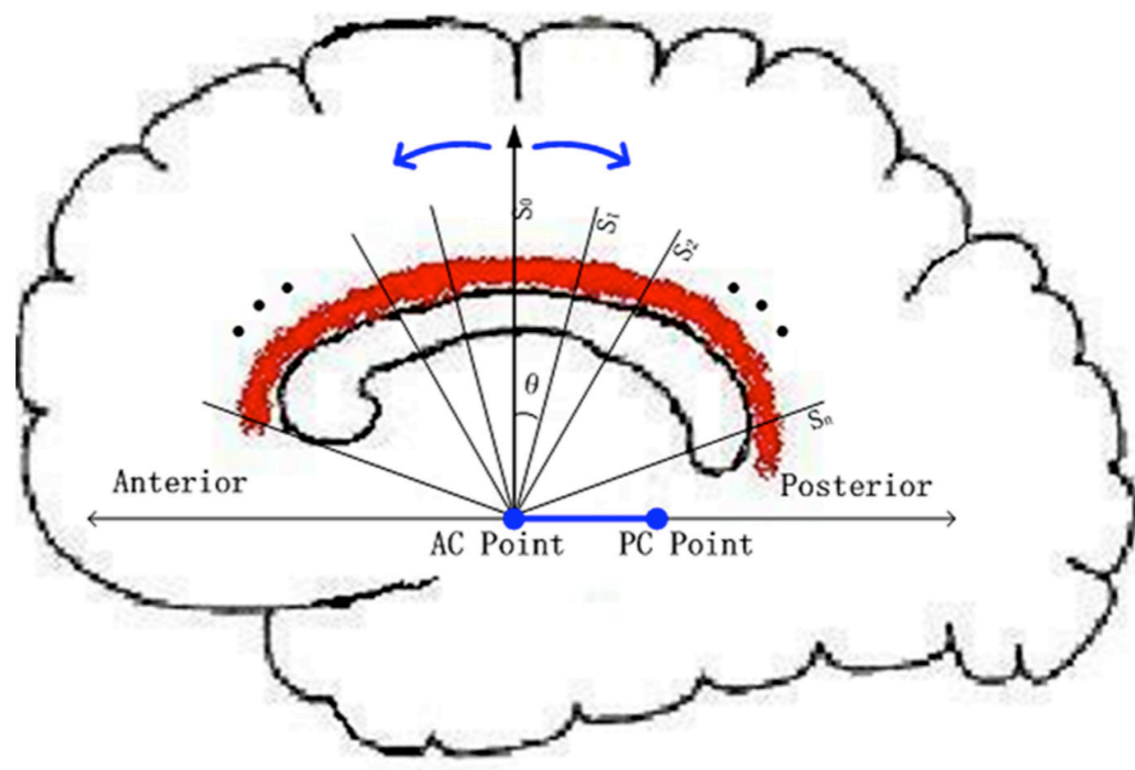
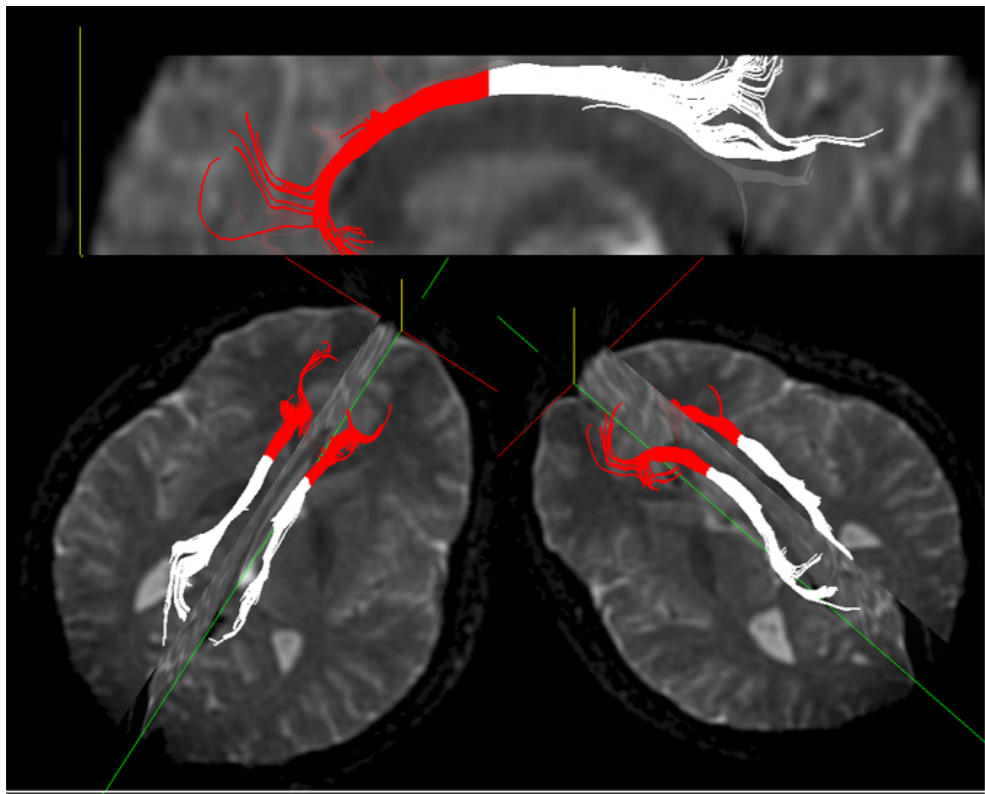
labour-intensive, subjective, potentially inaccurate, doesn't investigate whole brain

劳动密集型，主观的，可能不准确，不考察整个大脑





Tractography-Based FA Comparison 基于追踪的FA比较

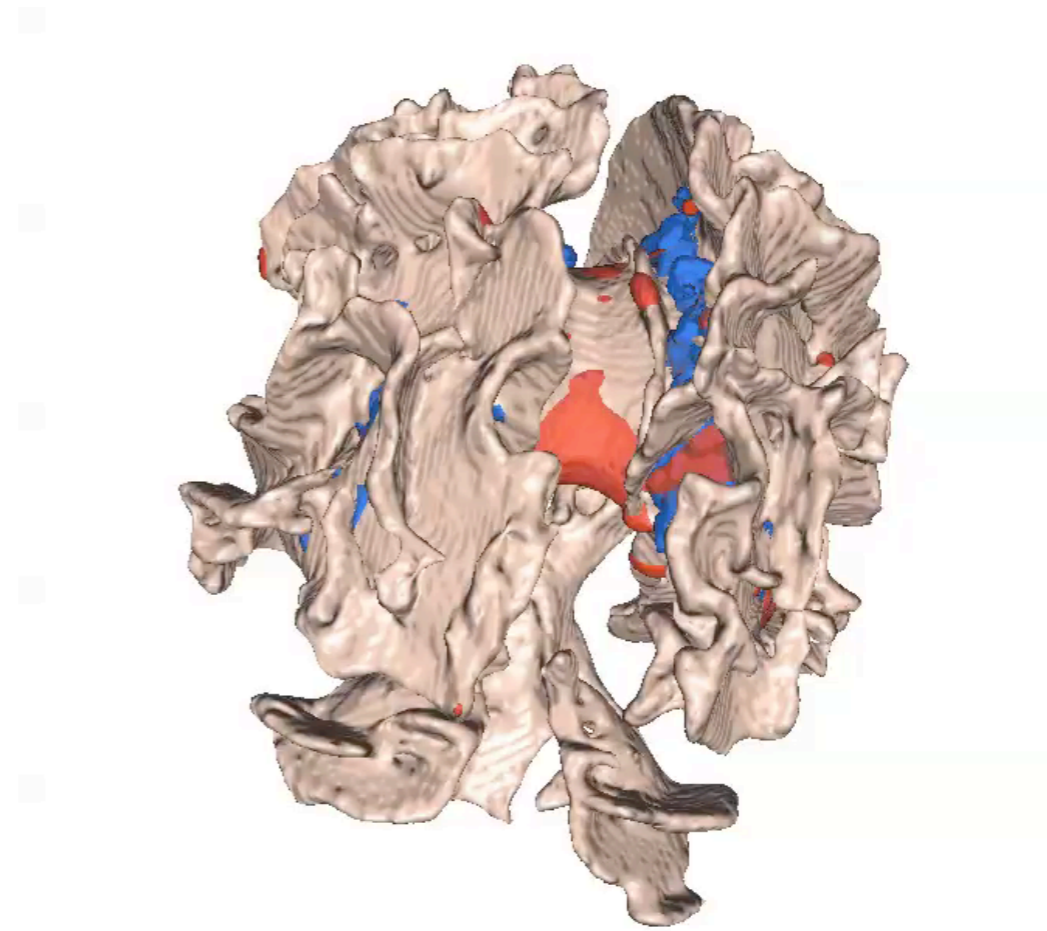
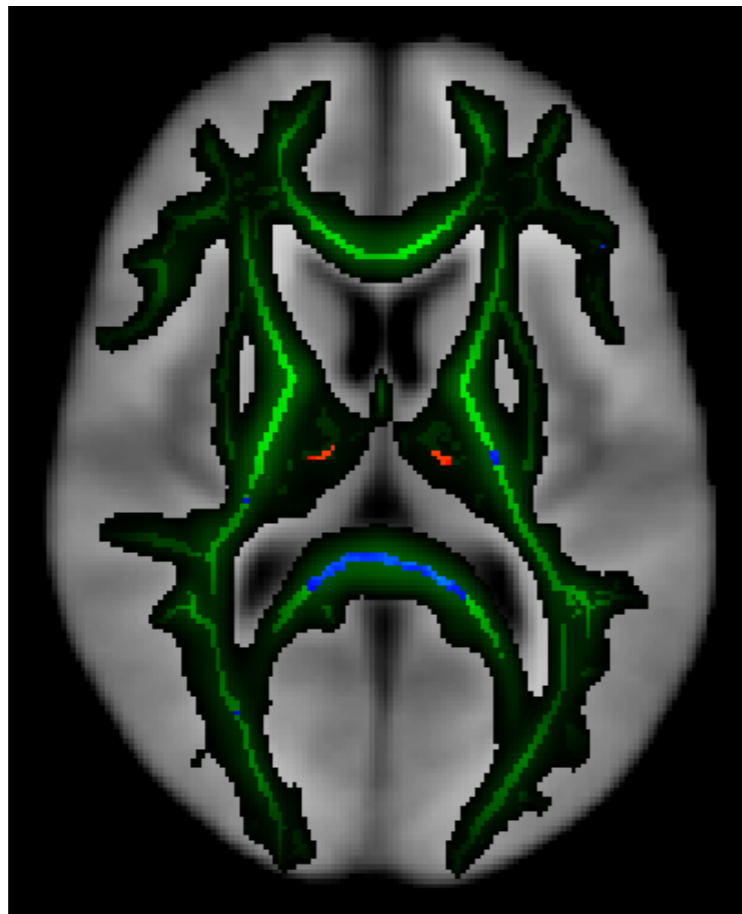


- Method [Gong 2005, Corouge 2006] 方法
 - Define a given tract in all subjects 根据所有被试定义一个纤维束
 - Parameterise FA along tract 沿着纤维束参数化FA
 - Compare between subjects 被试间比较
- Strength: correspondence issue hopefully resolved 优点: 通路问题有望解决
- Problems 问题
 - Currently requires manual intervention to specify tract 目前需要人工干预来指定纤维束
 - Hence doesn't investigate whole brain 因此不考查整个大脑
 - Projection of FA onto tract needs careful thought FA在纤维束上的投射需要仔细考虑



TBSS : Tract-Based Spatial Statistics

基于白质纤维束骨架的空间统计分析

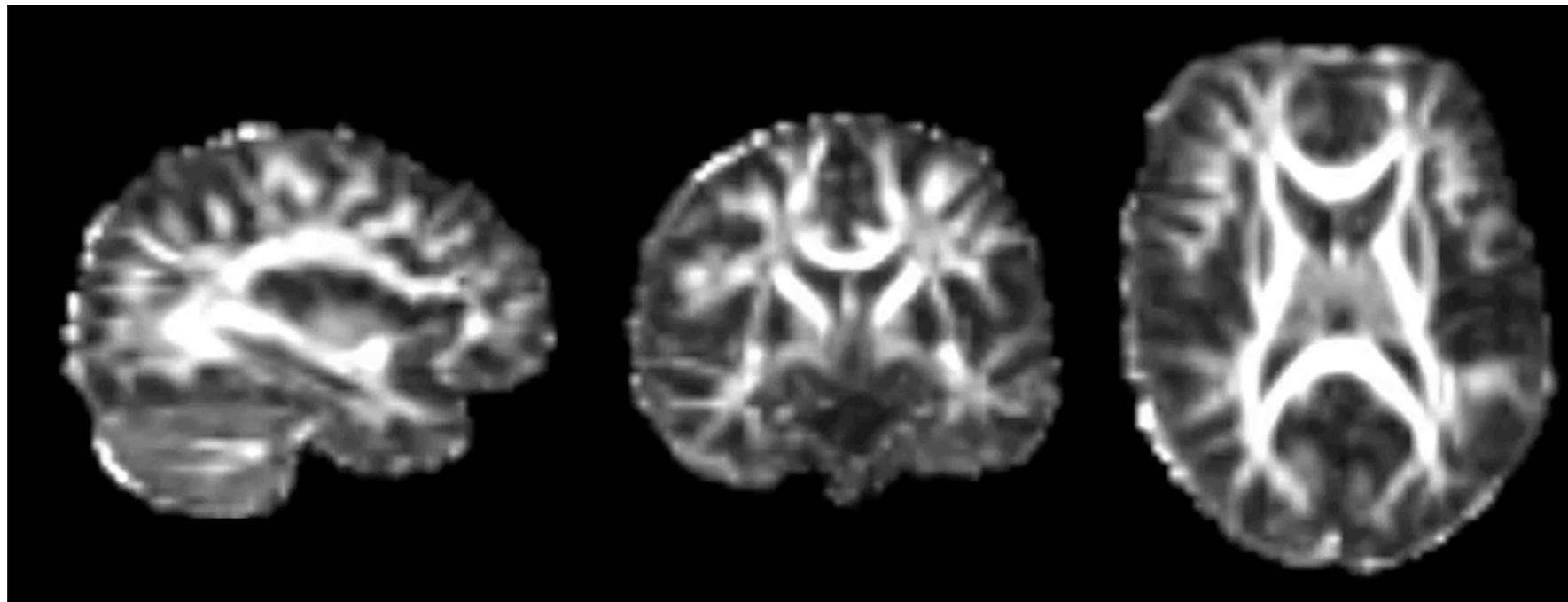


- Need: robust “voxelwise” cross-subject stats on DTI
需要：DTI的强大基于“体素”的被试间统计数据
- Problem: alignment issues confound valid local stats
问题：对齐问题会混淆有效的统计数据
- TBSS: solve alignment using alignment-invariant features:
TBSS：使用对齐不变特征解决对齐：
- Compare FA taken from tract centres (via skeletonisation)
比较从纤维束中取得的FA（通过骨架化）

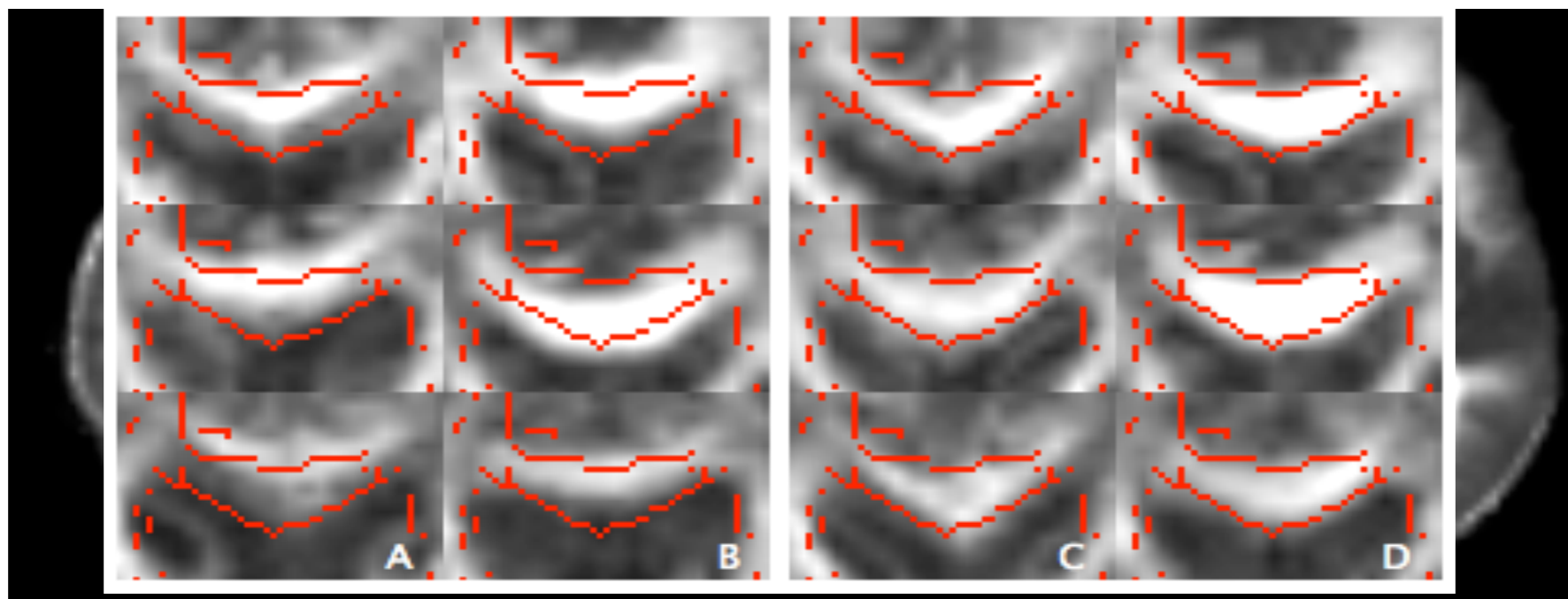


1. Use medium-DoF nonlinear reg to pre-align all subjects' FA (nonlinear reg: FNIRT)

使用中心-自由度非线性配准预先对准所有受试者的FA
(非线性配准: FNIRT)

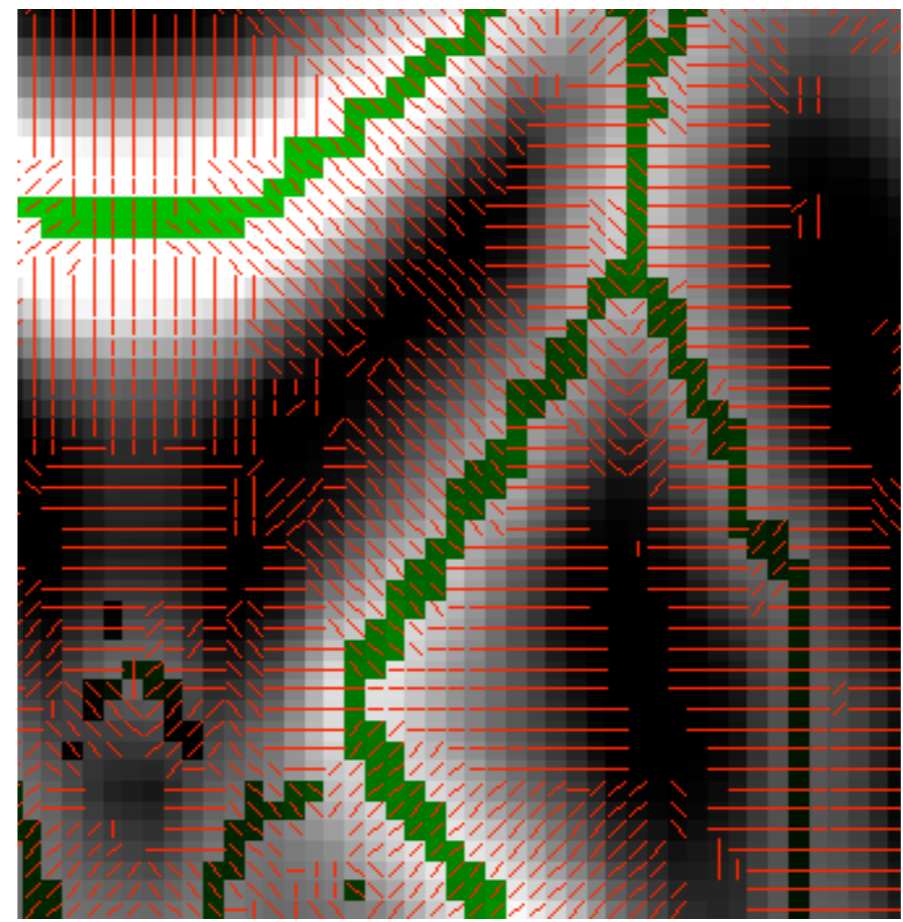
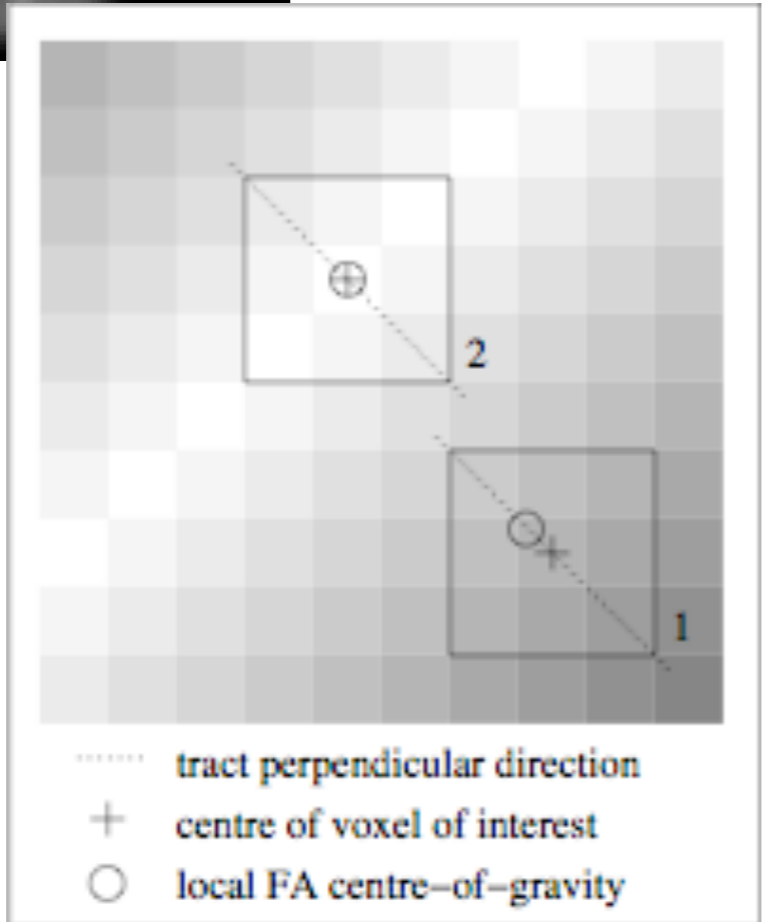
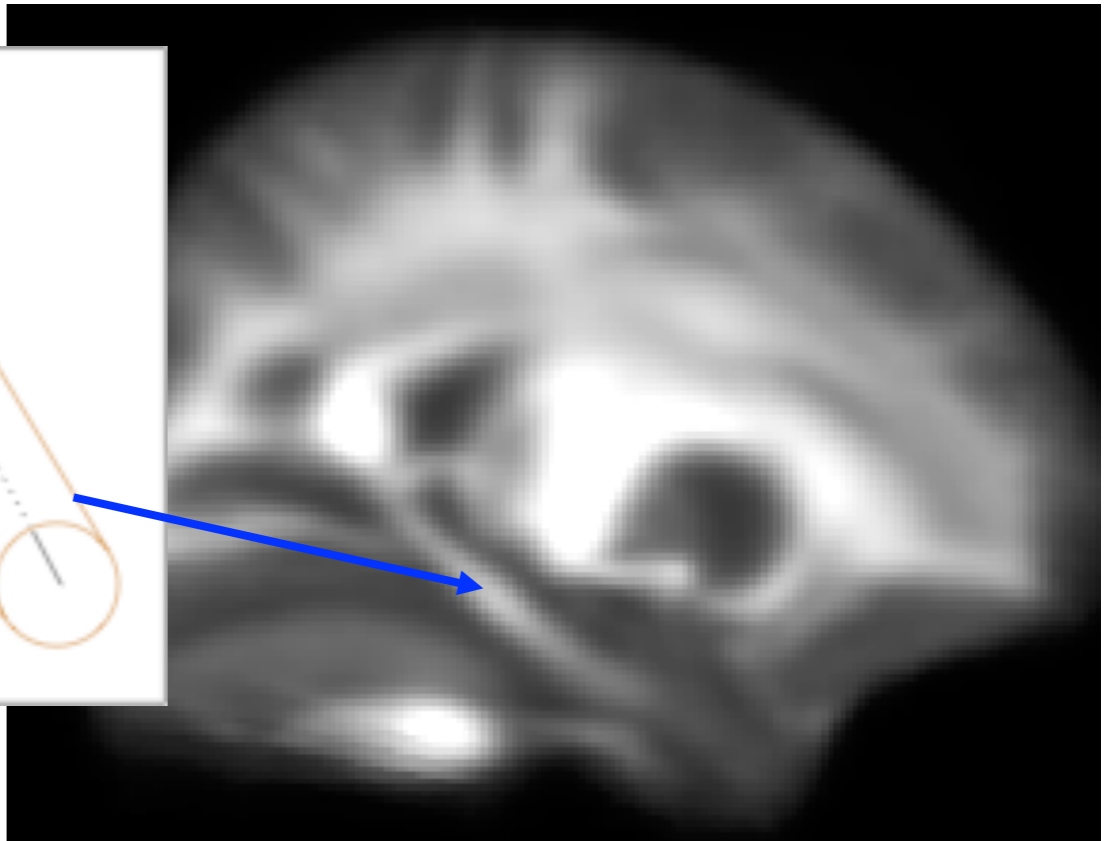
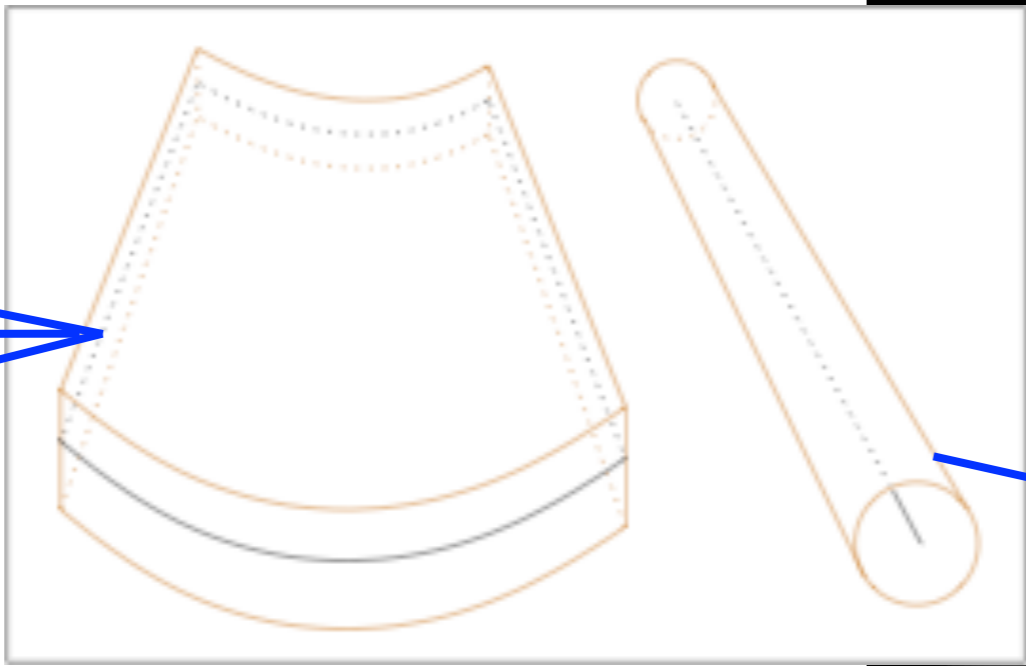
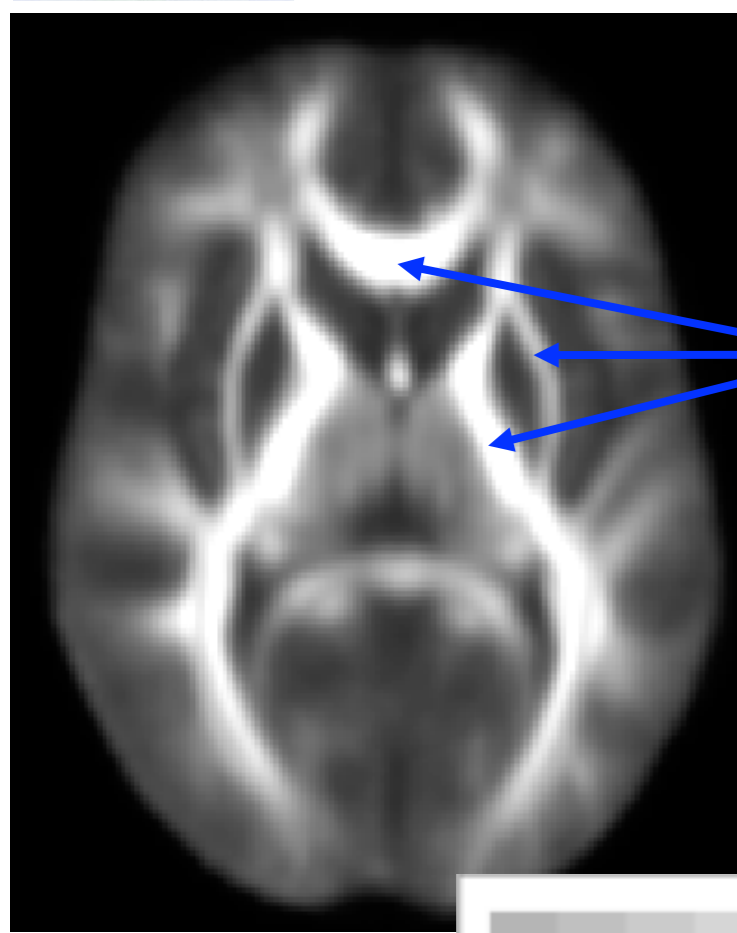


2. Create mean FA image (no smoothing) 生成FA平均图像 (无平滑)





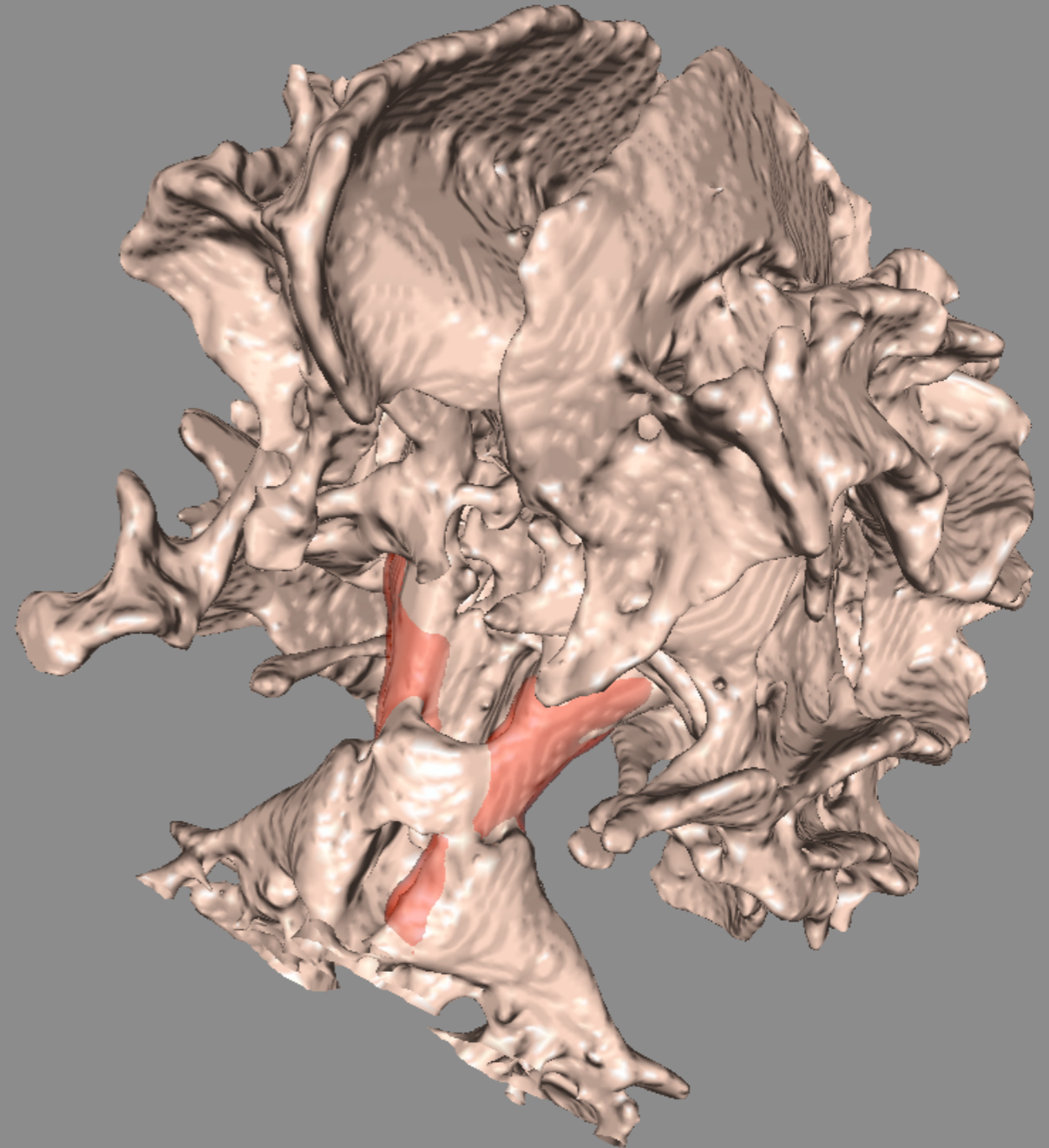
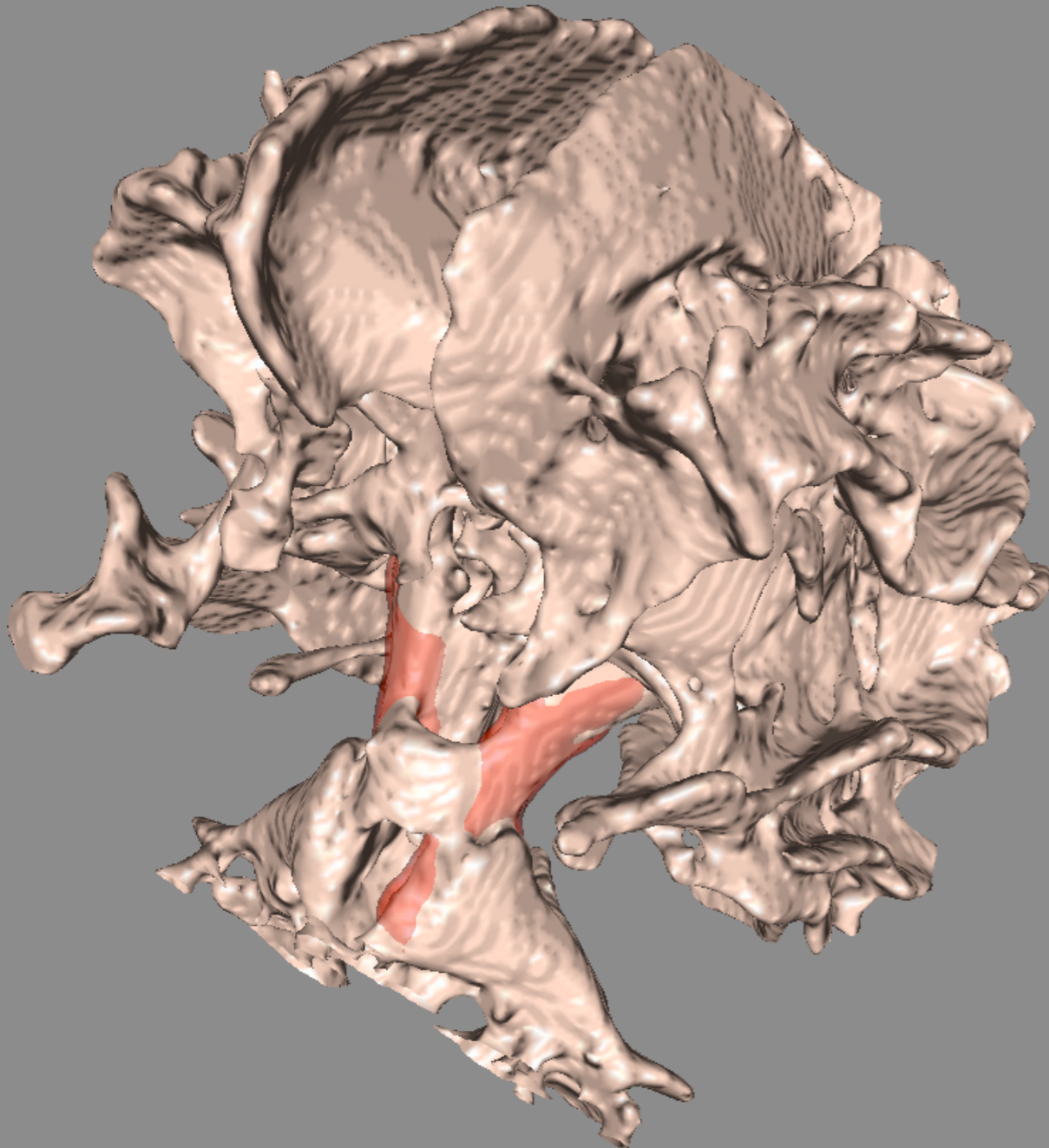
2. "Skeletonise" Mean FA 骨架平均FA





3. Threshold Mean FA Skeleton 阈值均值FA骨架

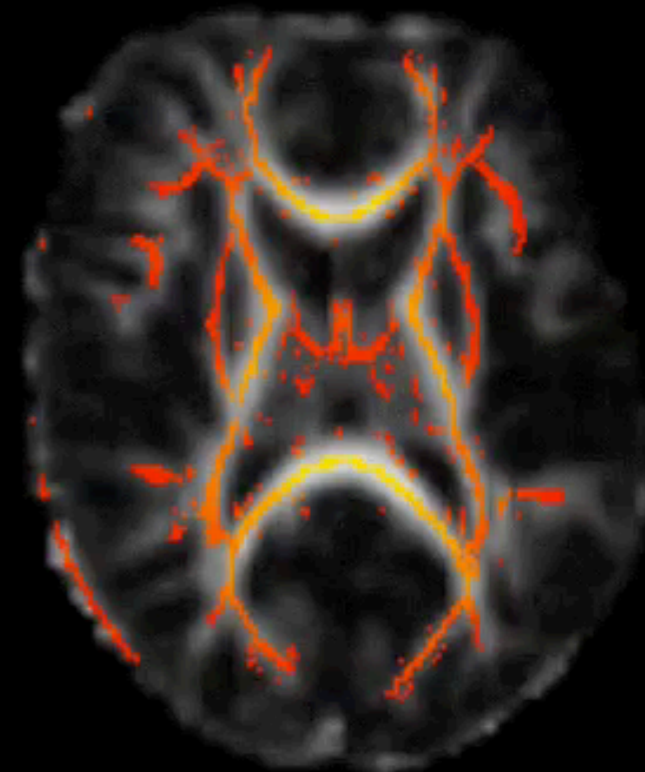
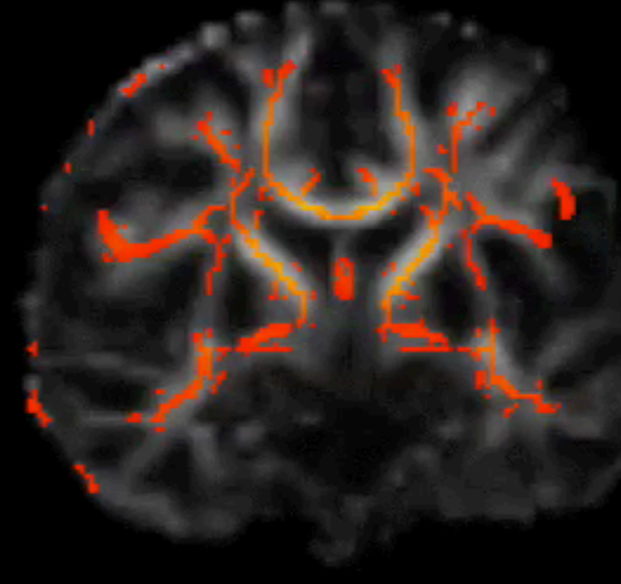
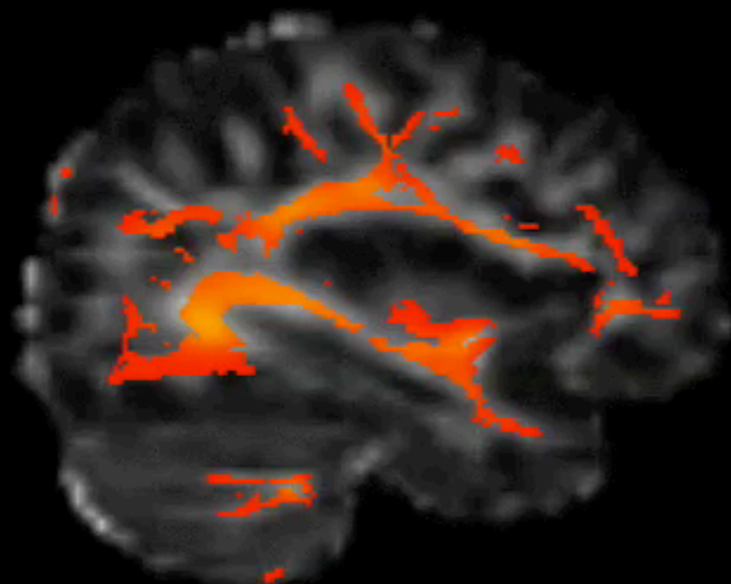
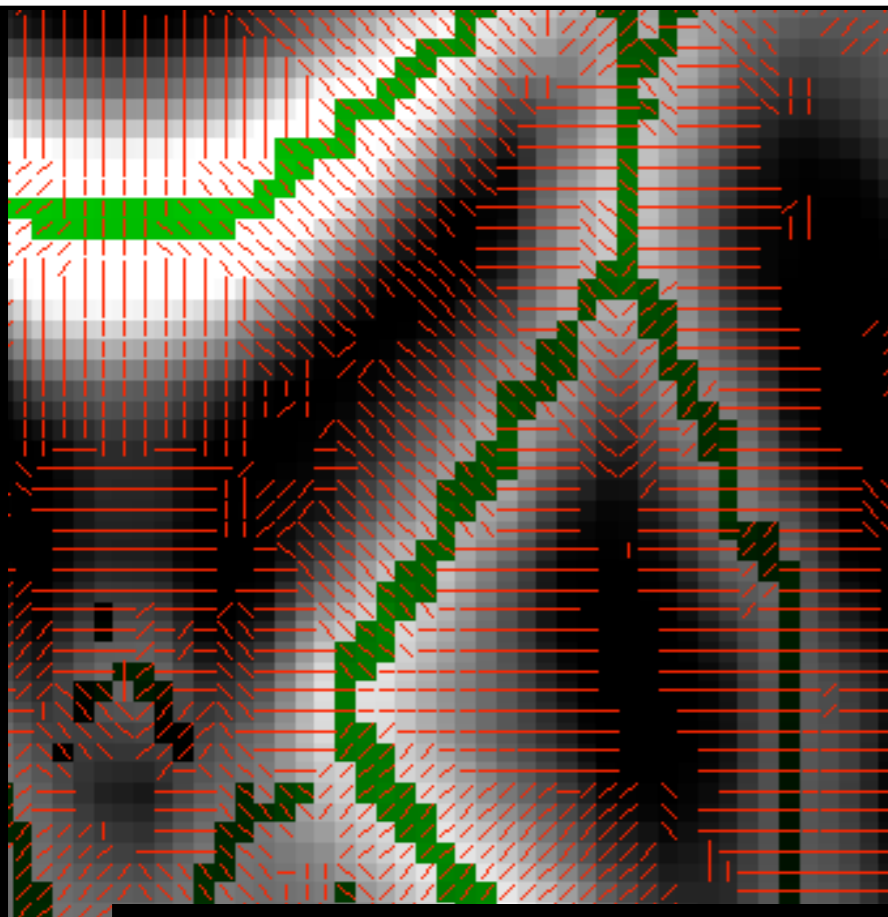
giving “objective” tract map 给出“客观”的纤维束图





3. Threshold Mean FA Skeleton 阈值均值FA骨架

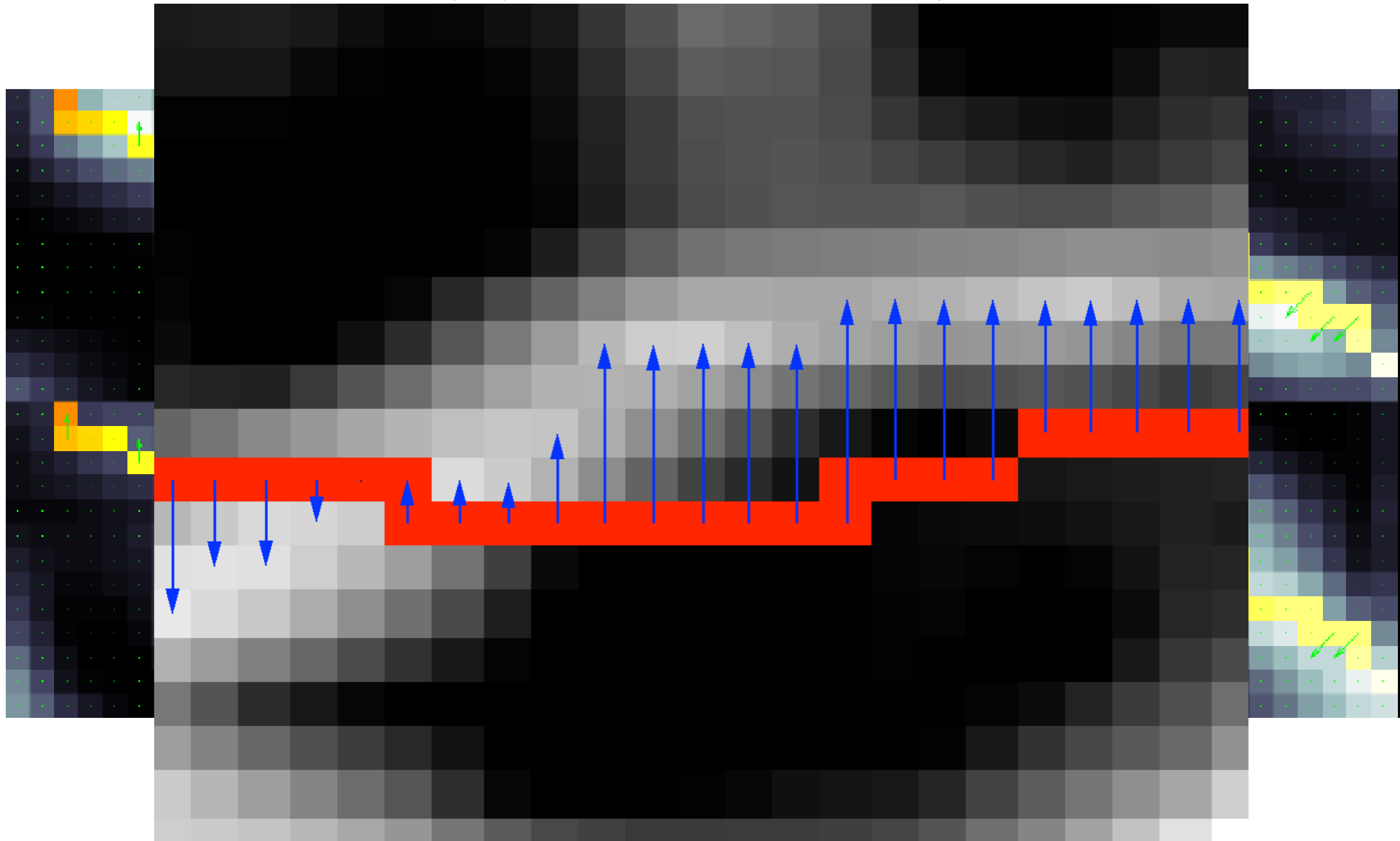
giving "objective" tract map 给出“客观”的纤维束图





4. For each subject's warped FA, fill each point on the mean-space skeleton with nearest maximum FA value (i.e., from the centre of the subject's nearby tract)

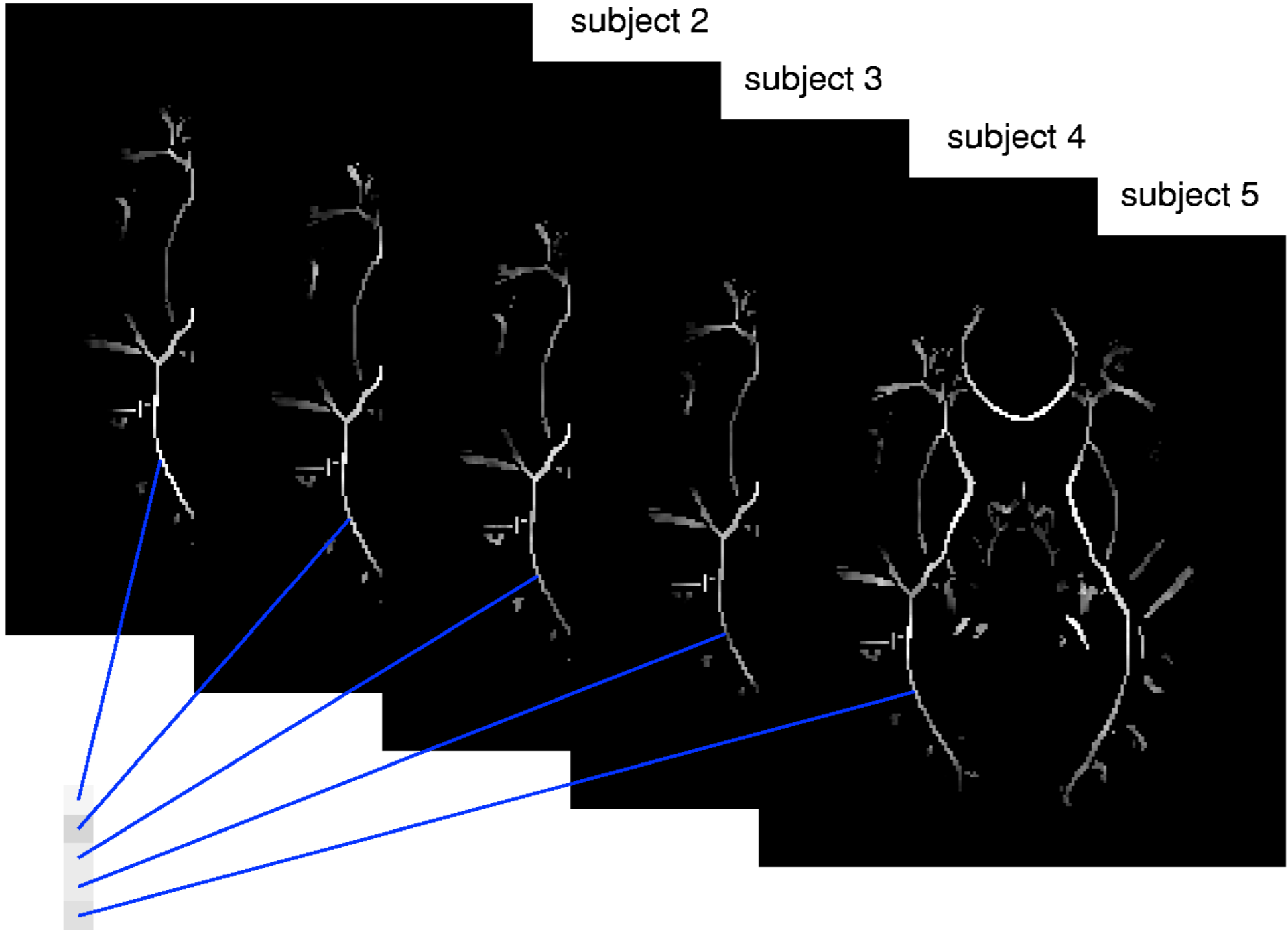
对于每个受试者的扭曲FA，用最接近的最大FA值（即，从受试者的附近区域的中心）填充平均空间骨架上的每个点。



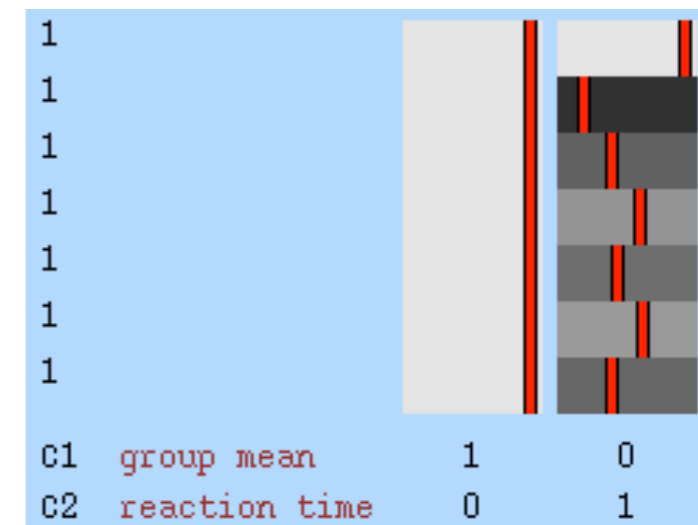
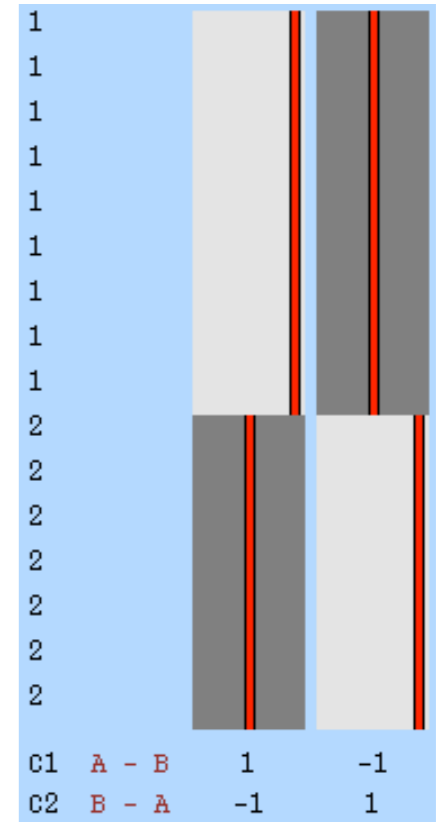


5. Do cross-subject voxelwise stats on skeleton-projected FA and Threshold, (e.g., permutation testing, including multiple comparison correction)

在骨架投射的FA上进行被试间体素统计和阈值, (例如, 置换测试, 包括多重比较校正)



one skeleton voxel's data vector (to be fed into GLM)

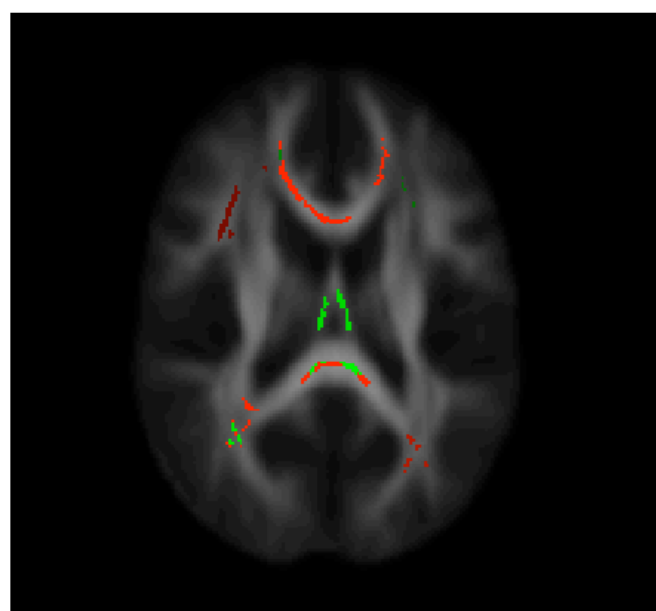
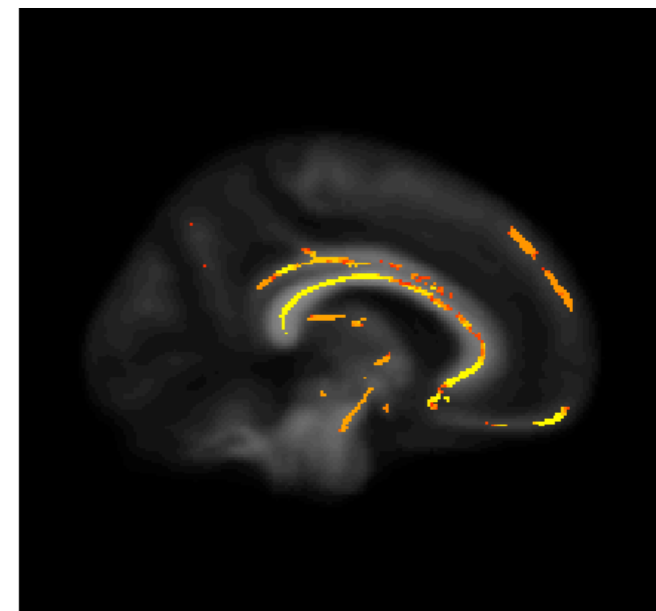
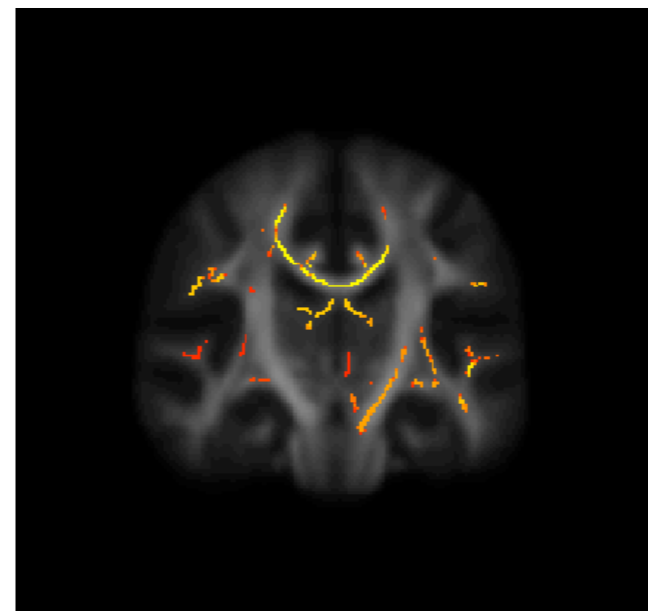
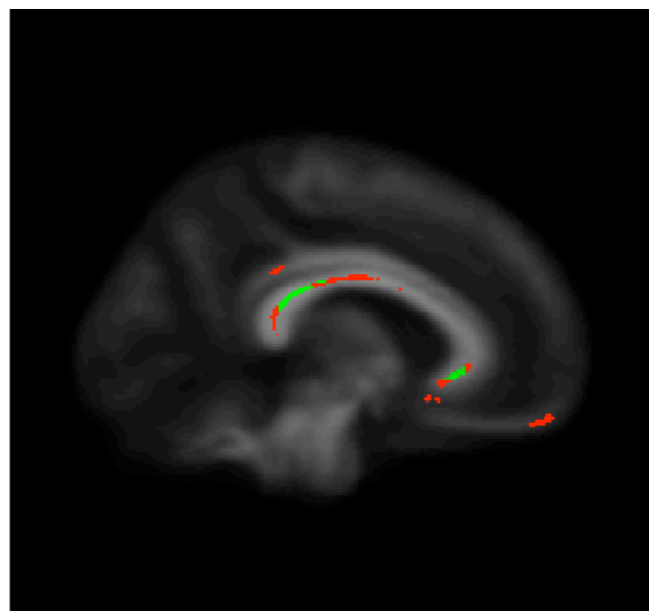
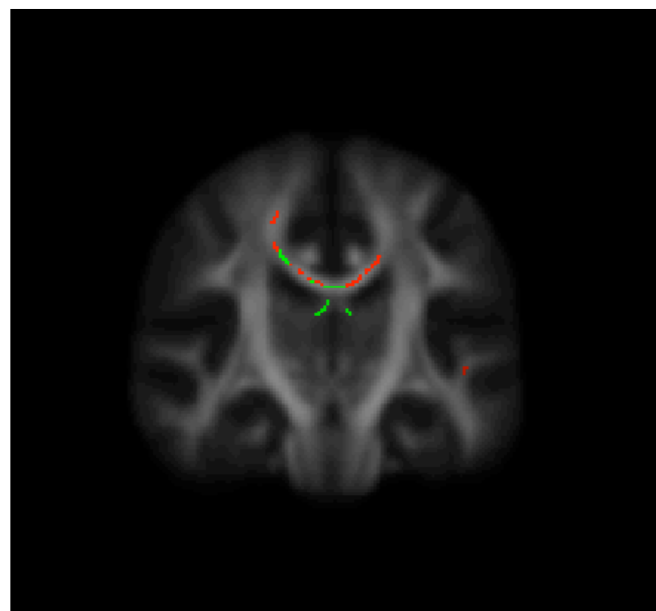




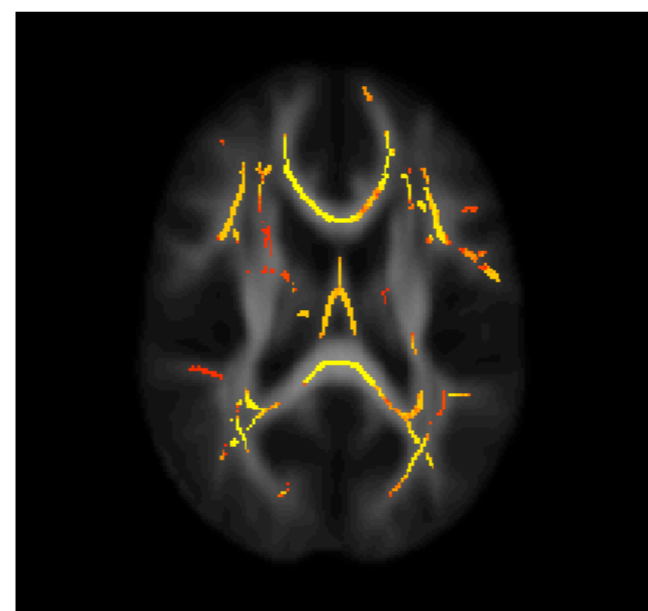
TFCE for TBSS

controls > schizophrenics

$p < 0.05$ corrected for multiple comparisons across space,
using randomise



cluster-based:
cluster-forming
threshold =
2 or 3



TFCE



Schizophrenia (Mackay) 精神分裂症

TBSS & VBM show reduced FA in corpus callosum & fornix

TBSS和VBM显示胼胝体和穹窿中的FA降低

VBM shows spurious result in thalamus due to increased ventricles in schiz.

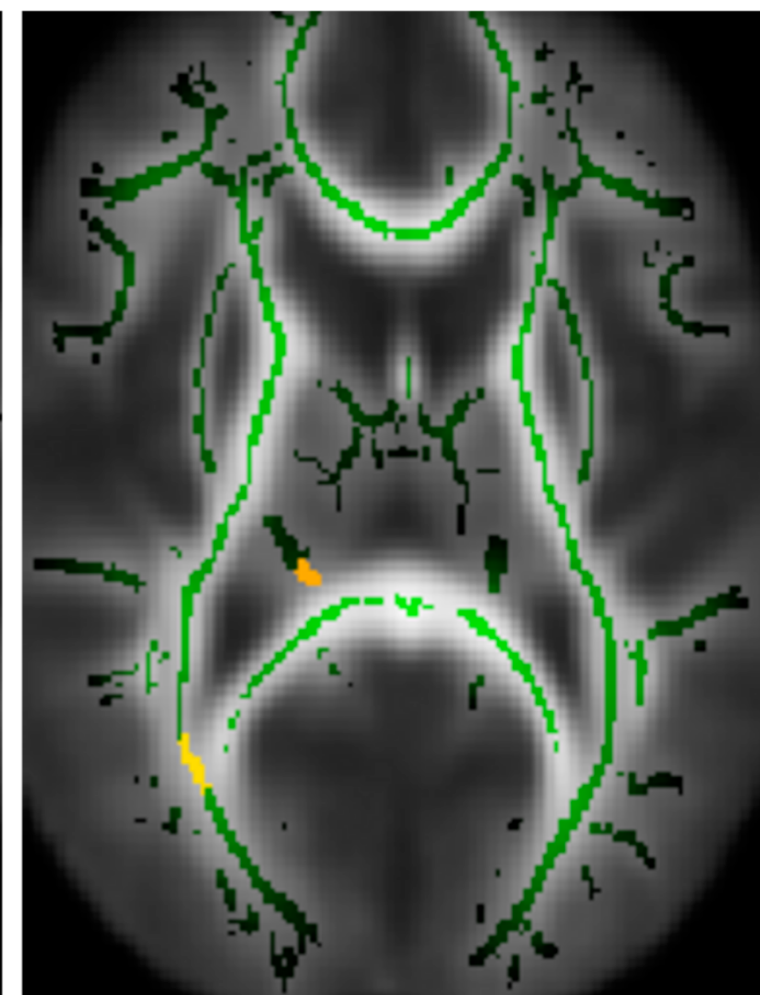
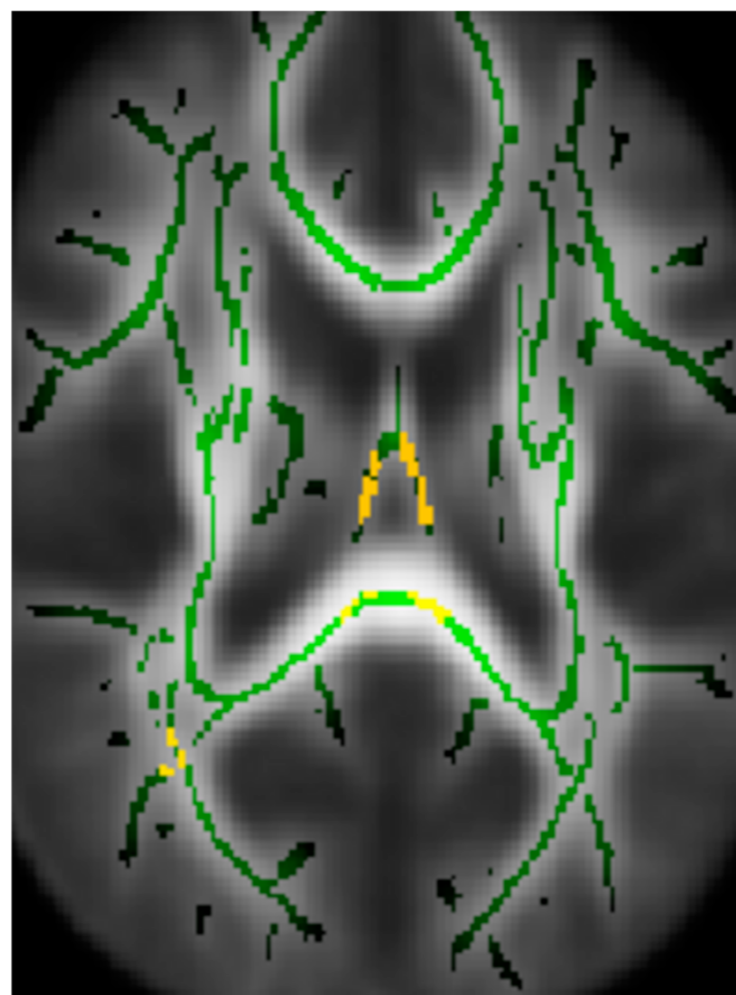
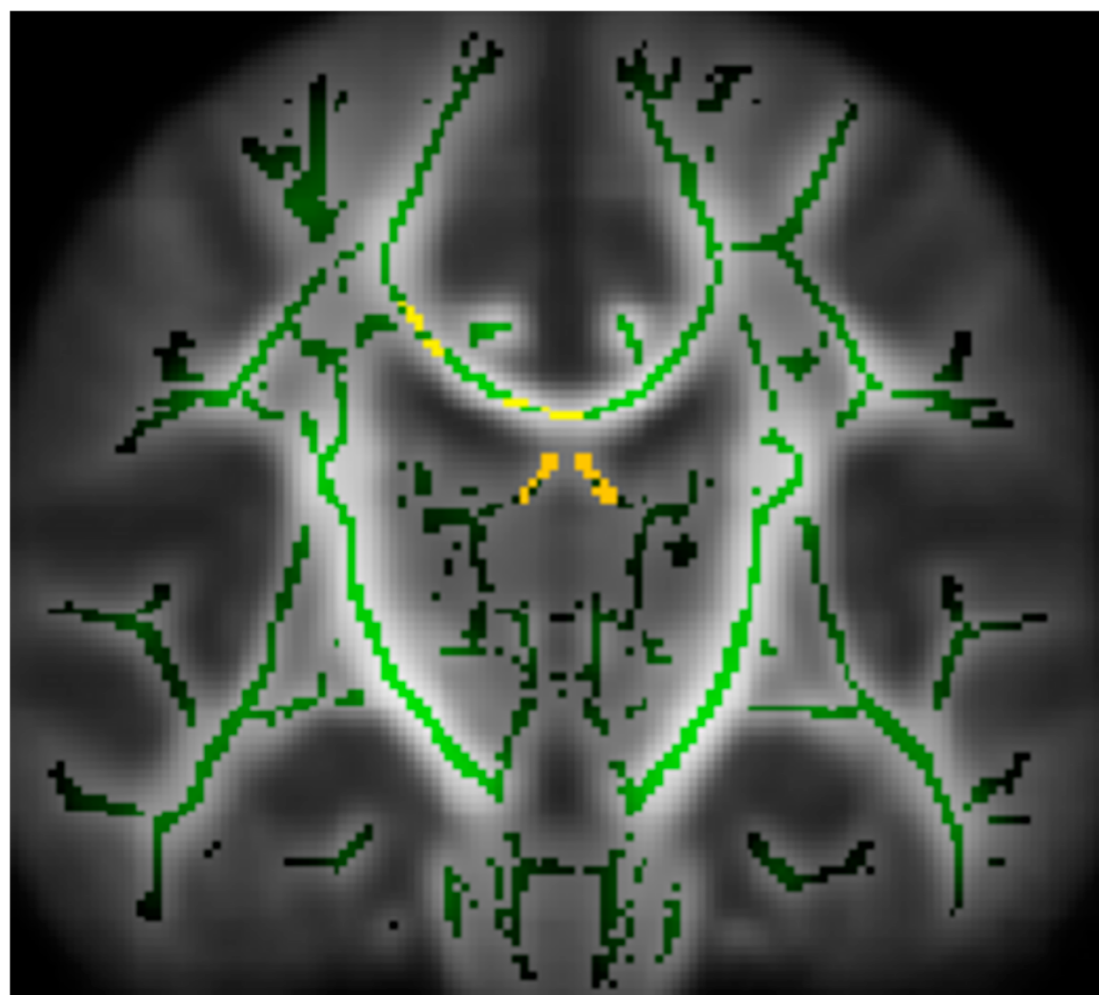
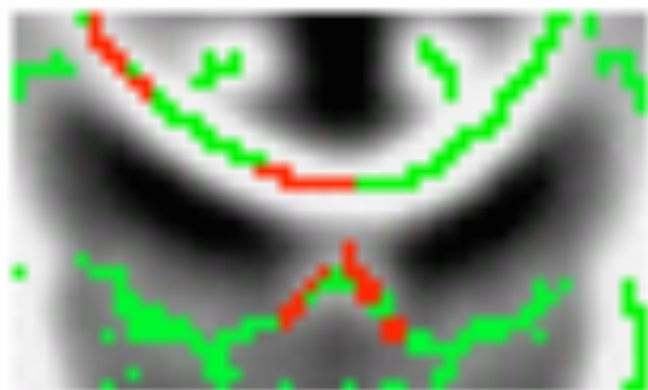
VBM在丘脑中显示虚假结果，原因是schiz的心室增加

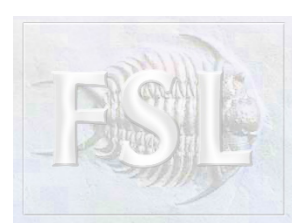
TBSS

VBM

mean FA (controls)

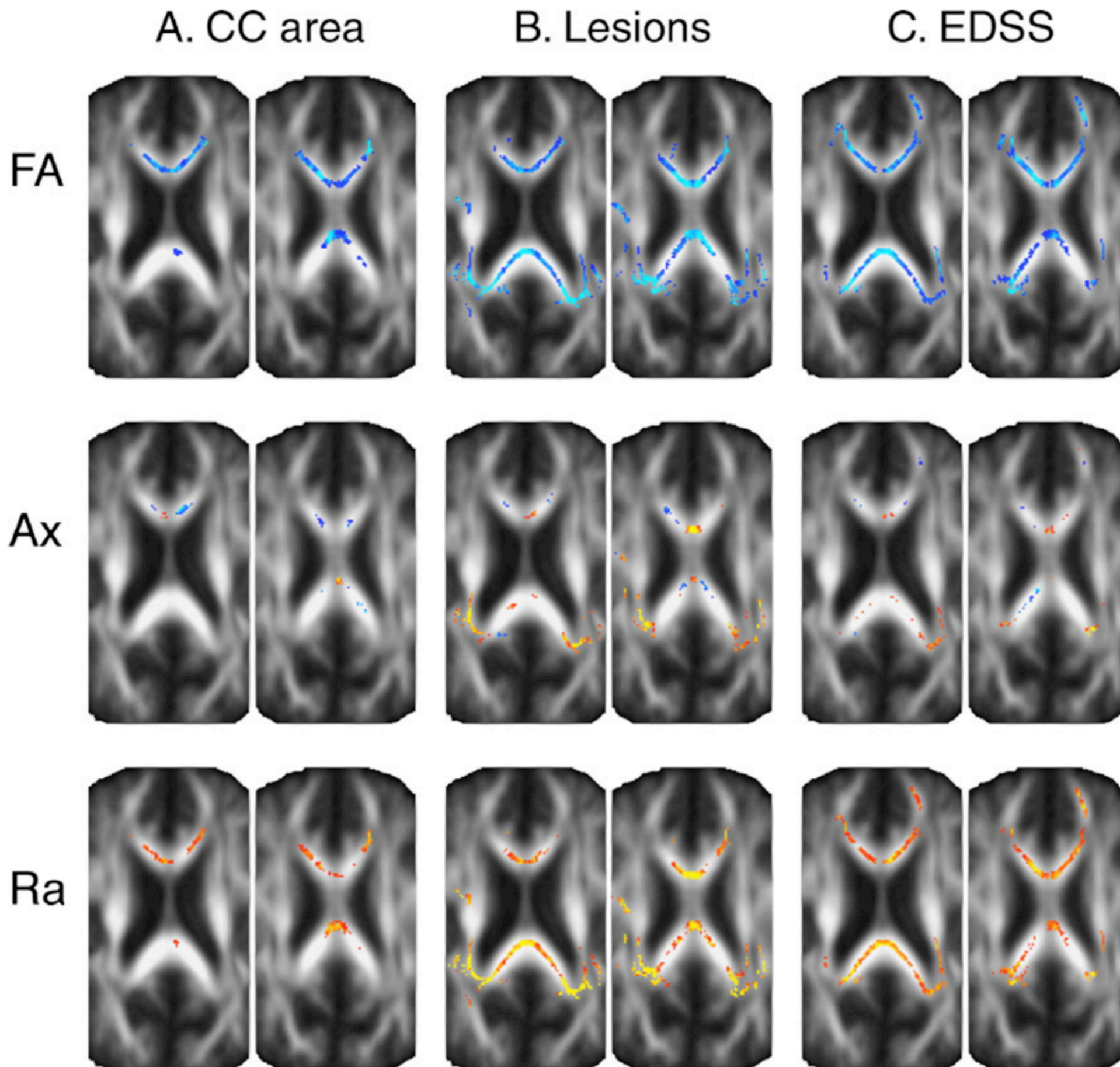
mean FA (schiz.)





Multiple Sclerosis (Cader, Johansen-Berg & Matthews)

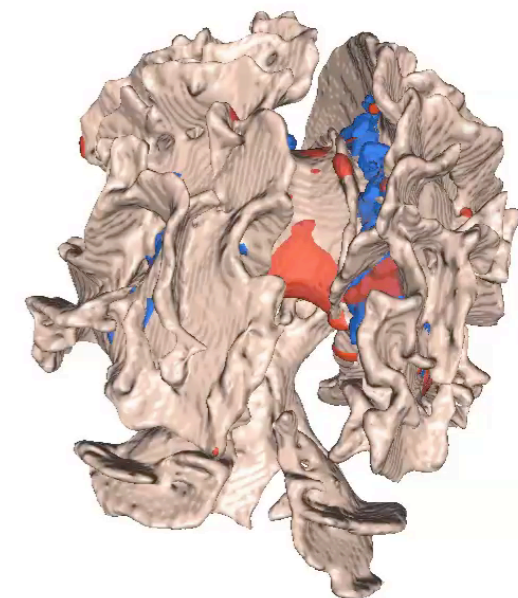
多发性硬化症





TBSS - Conclusions 结论

- Attempting to solve correspondence/smoothing problems
试图解决对应/平滑问题
- Less ambiguity of interpretation / spurious results than VBM
与VBM相比，解释/虚假结果的含糊性较小
- Easier to test whole brain than ROI / tractography
比种子点/概率纤维束追踪法更容易测试整个大脑
- Limitations & Dangers 局限性和坑
 - Interpretation of partial volume tracts still an issue 部分体素的解释仍然是一个问题
 - Crossing tracts? 纤维束之间?
- Future work 未来工作
 - Use full tensor (for registration and test statistic)
使用完整张量 (用于配准和统计测试)
 - Use other test statistics (MD, PDD, width) 使用其他统计方法
 - Multivariate stats (across voxels and/or different diffusion measures) & discriminant (ICA, SVM)
多元统计信息 (跨体素和/或不同扩散方法) 和分类法 (ICA, SVM)





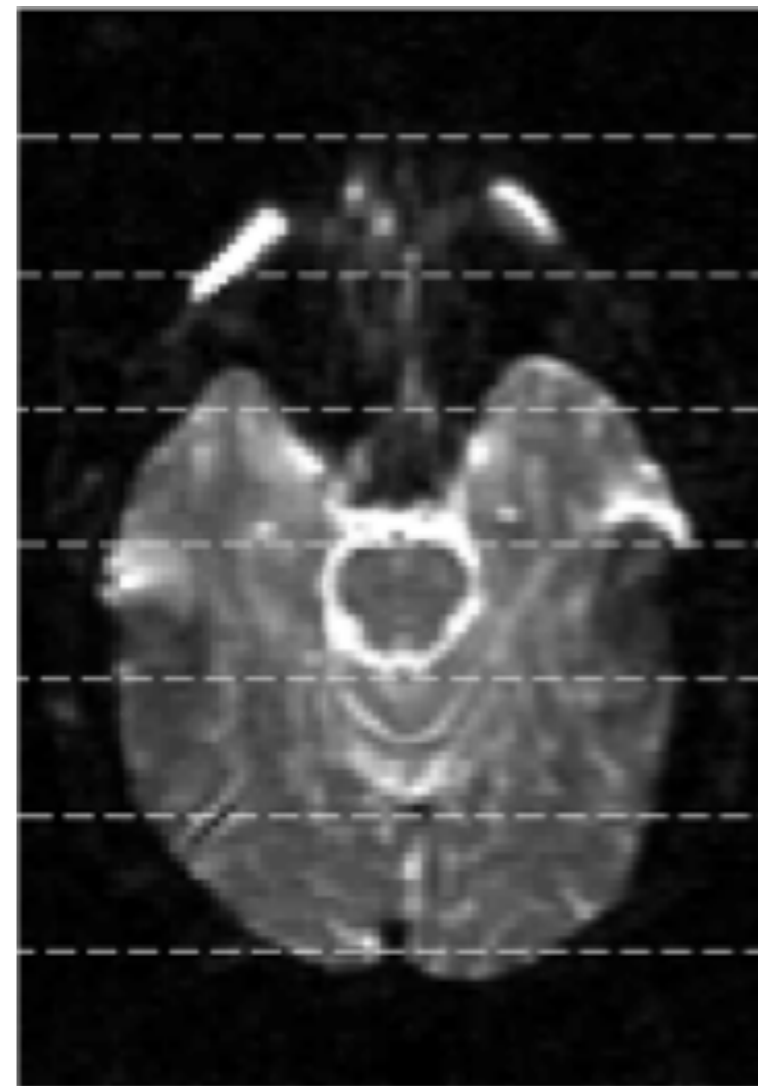
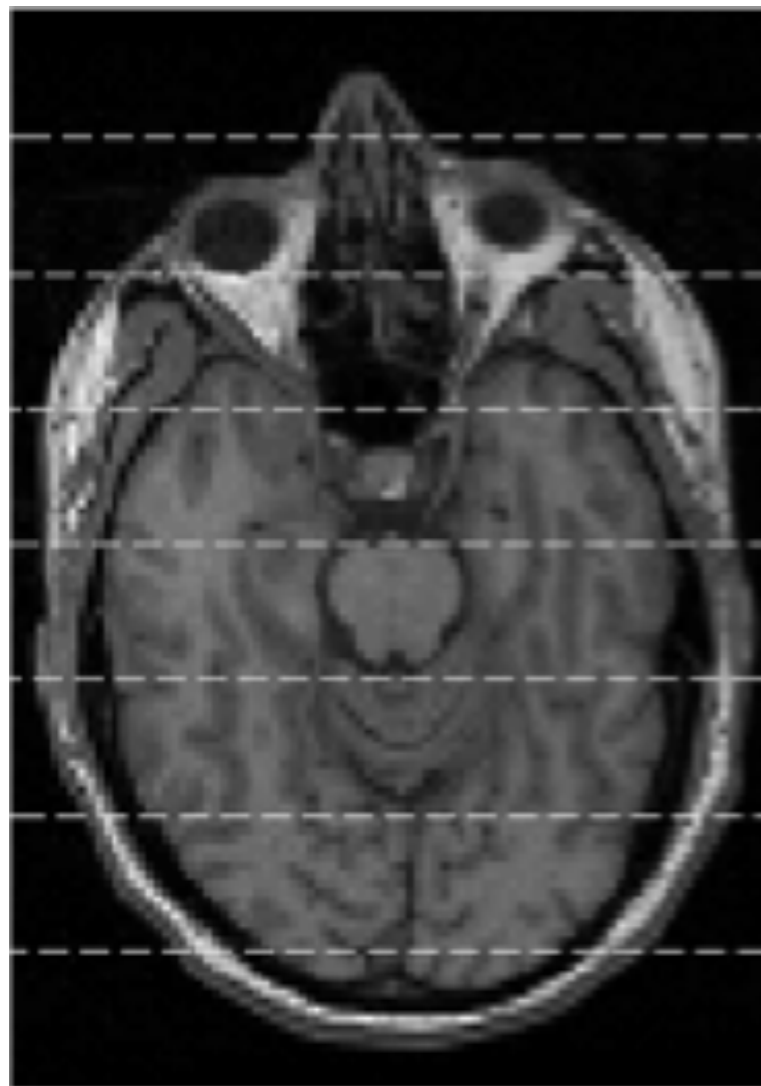
Outline of the talk 大纲

- **What is the problem with diffusion data?** 扩散数据有什么问题?
 - Off-resonance field 非共振场
 - How does it cause distortions? 它如何引起失真?
 - Where does it come from? 它从何而来?
 - Registering diffusion data 弥散数据的配准
 - How topup works topup topup如何起作用补满的?
 - How eddy works eddy eddy实现涡流矫正?
 - Practicalities 实用性
 - Some results 一些结果
 - Quality control 质控
 - New eddy features 新的涡流功能



What is the problem with diffusion data?

扩散数据有什么问题？



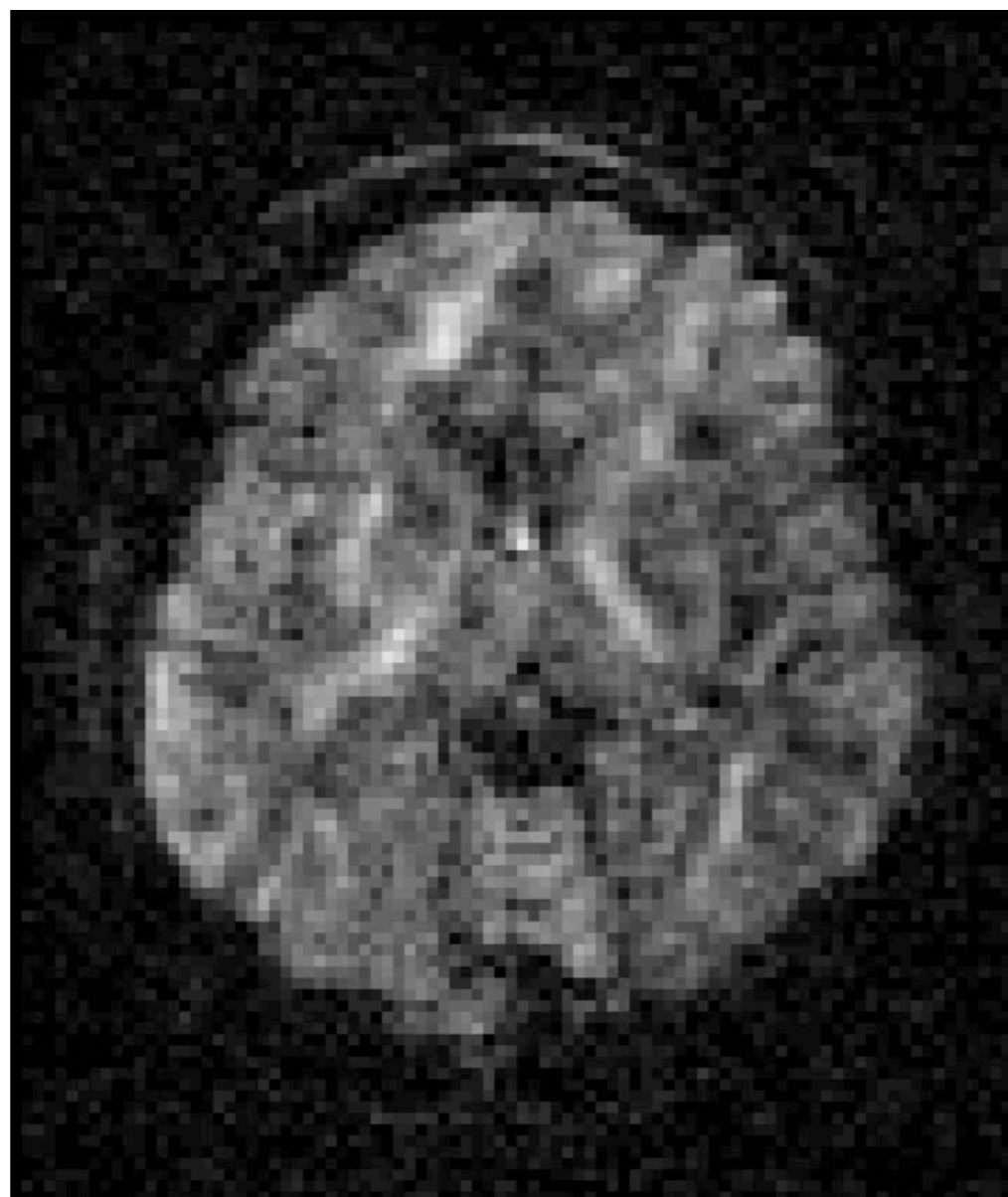
Well, it isn't very anatomically faithful

嗯，这在解剖学上不是很准确可靠



What is the problem with diffusion data?

扩散数据有什么问题？



In fact, it isn't even internally consistent

实际上，它甚至在内部都不是一致的



Outline of the talk 大纲

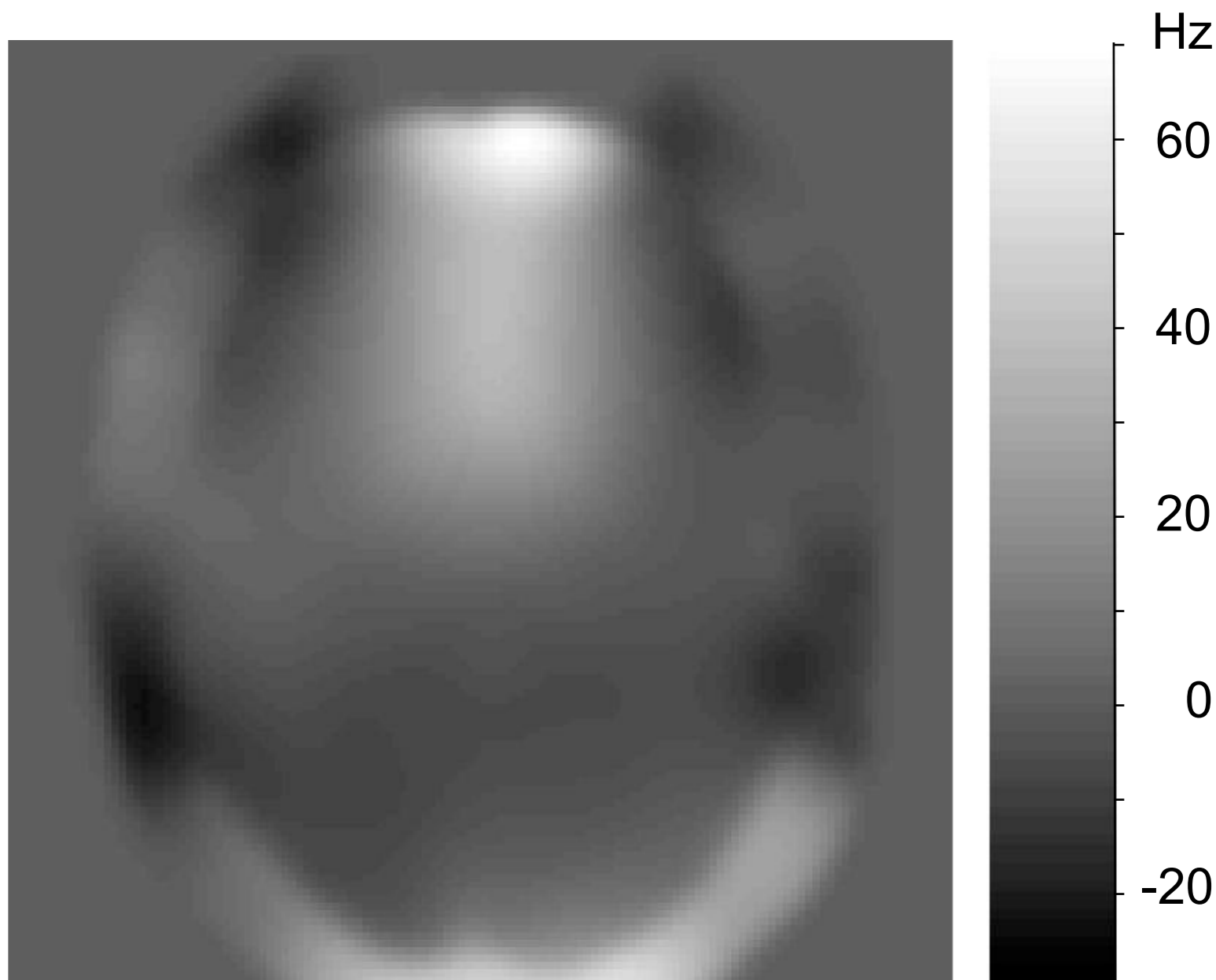
- What is the problem with diffusion data? 扩散数据有什么问题?
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- Quality control 质控
- New eddy features 新的涡流功能



Off-resonance field \Rightarrow Distortions

非共振场 \Rightarrow 失真

An “off-resonance” field is a map of the difference between what we think the field is and what it really is.
“非共振”场是我们认为该场与实际场之间的差异的映射。

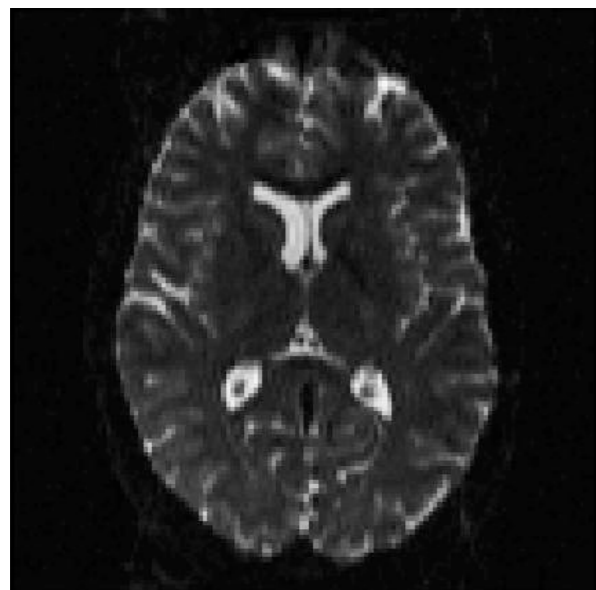


It is all caused by an “off-resonance” field
这都是由“共振”场引起的



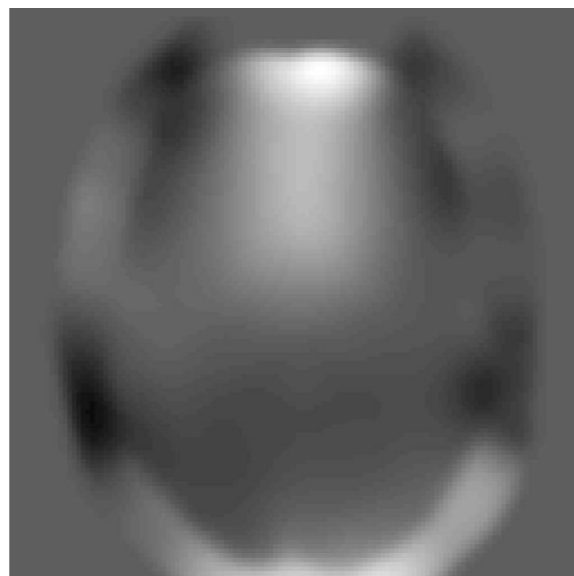
Off-resonance field \Rightarrow Distortions

非共振场 \Rightarrow 失真



But this object

这个对象

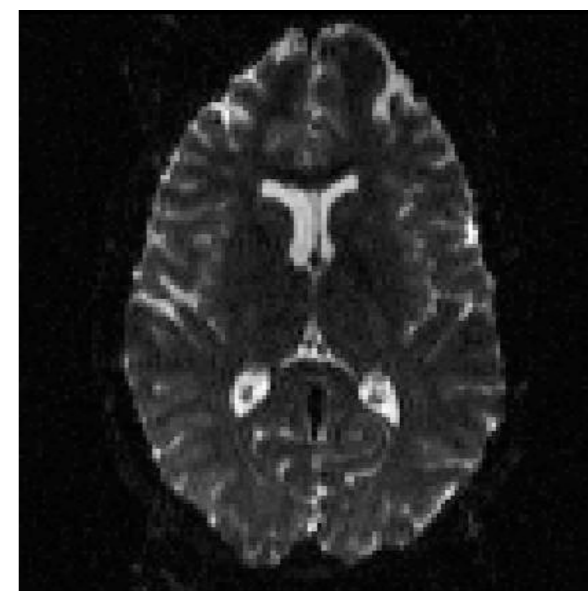
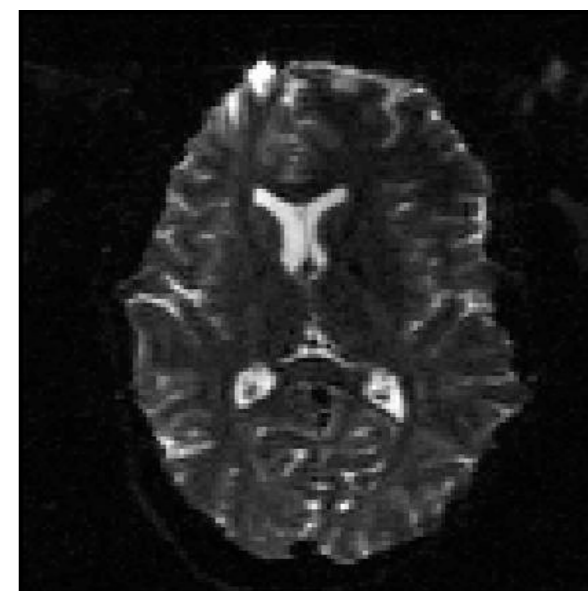


scanned in
this field

在此场中扫描

or this
可能是这样

Can yield this
也可能生成这个



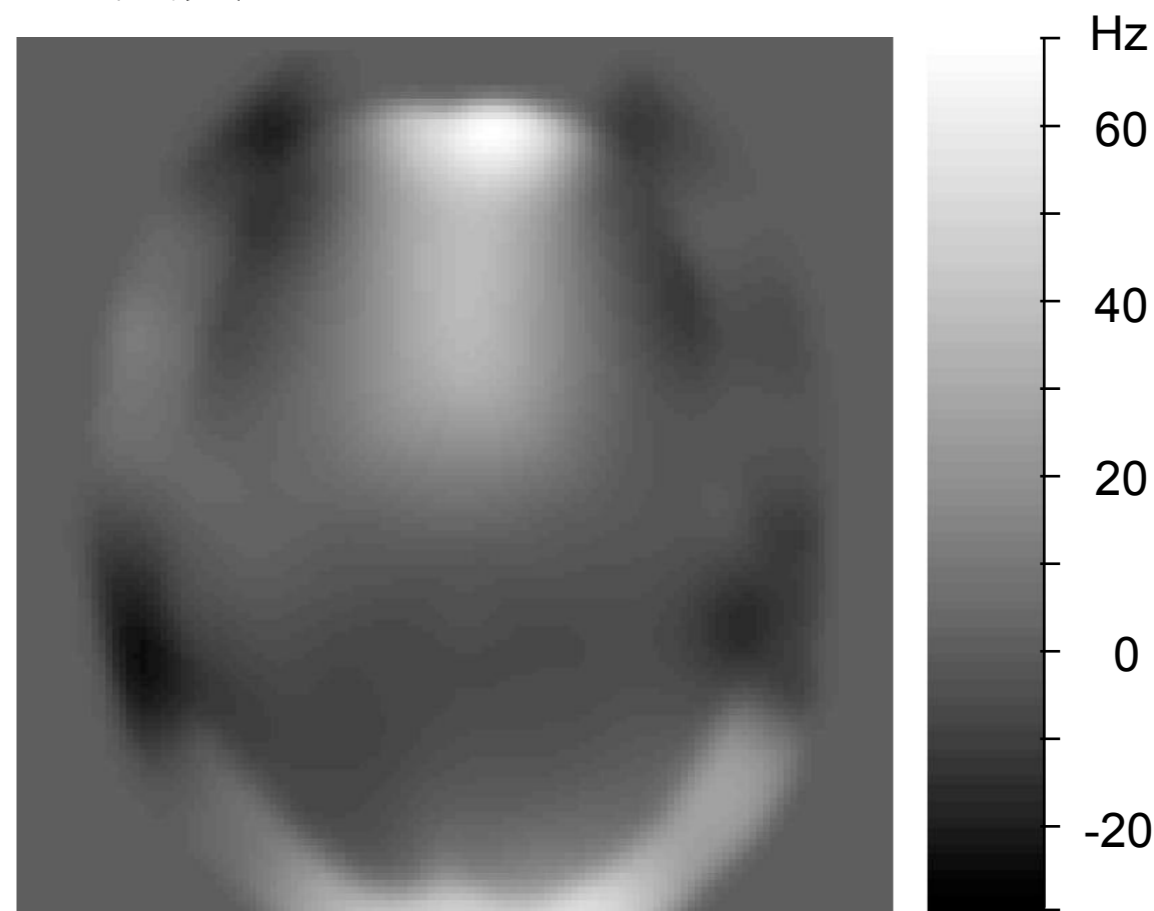
So there is clearly more to this story...

因此，这个故事显然还有更多.....



Off-resonance field \Rightarrow Distortions

非共振场 \Rightarrow 失真



An off-resonance field is effectively a scaled voxel-displacement map.

非共振场实际上是缩放的体素位移图。

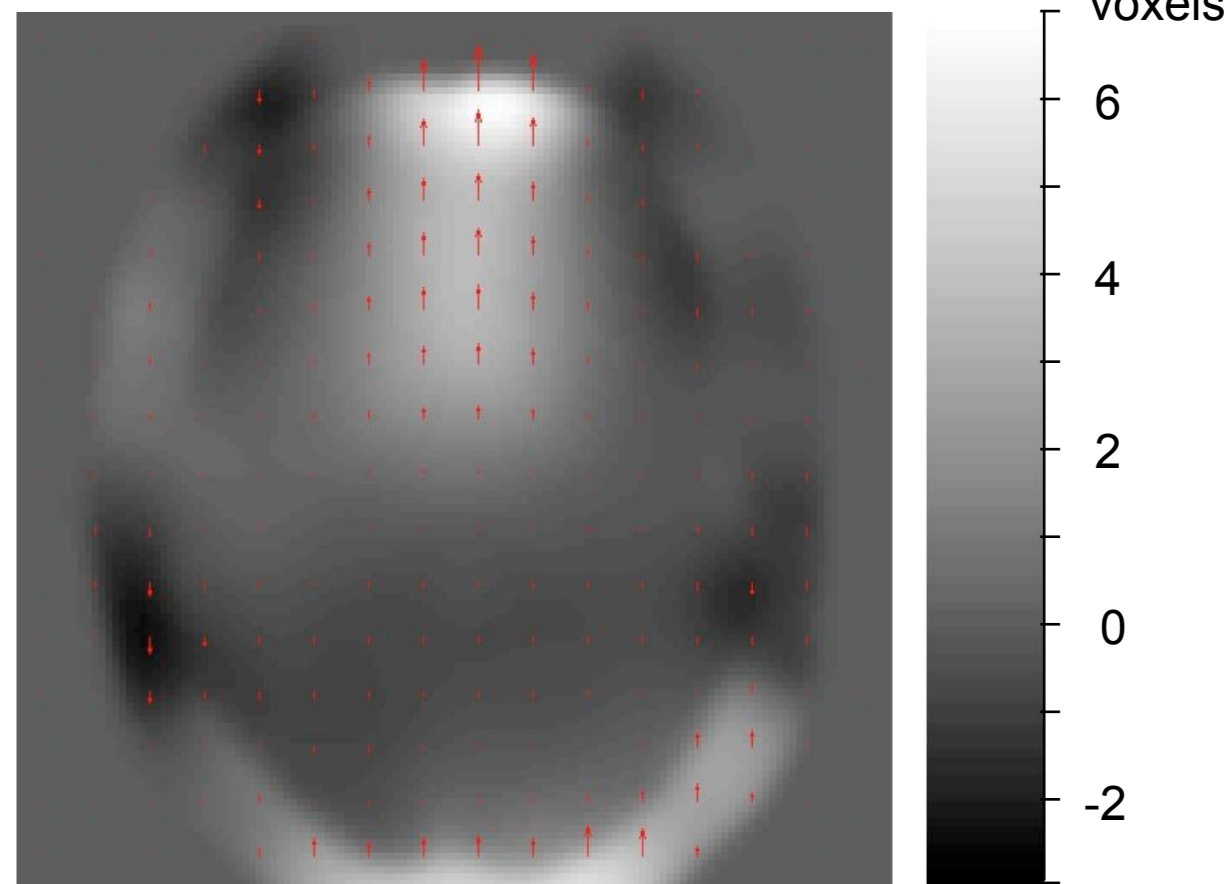
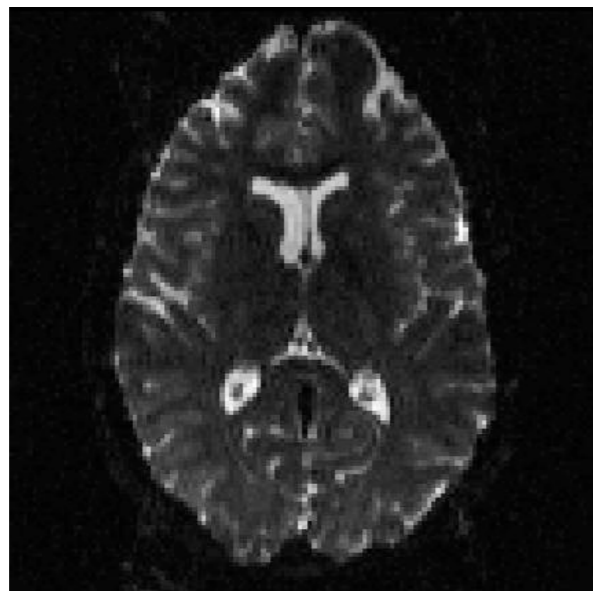
If we know the imaging parameters we can do the translation.

如果我们知道成像参数，就可以进行位移变换



Off-resonance field \Rightarrow Distortions

非共振场 \Rightarrow 失真



And know what to expect

并且知道会发生什么

An off-resonance field is effectively a scaled voxel-displacement map.

非共振场实际上是缩放的体素位移图。

If we know the imaging parameters we can do the translation.

如果我们知道成像参数，就可以进行位移变换

$$BW/voxel = 10\text{Hz}, \mathbf{p} = [0 \ 1 \ 0]$$



Outline of the talk 大纲

- What is the problem with diffusion data? 扩散数据有什么问题?
- Off-resonance field 非共振场
 - How does it cause distortions? 它如何引起失真?
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Where does the off-resonance field come from?

非共振场来自哪里?

- There are two sources 有两个来源
- The first is the object (head) itself. 第一个是对象 (头部) 本身。

(CT of) Human head CT脑图

$B_0 \odot$



Resulting field 结果场



PPMs

Must fulfil $\begin{cases} \nabla \times \mathbf{H} = 0 \\ \nabla \cdot \mathbf{B} = 0 \end{cases}$ (still)



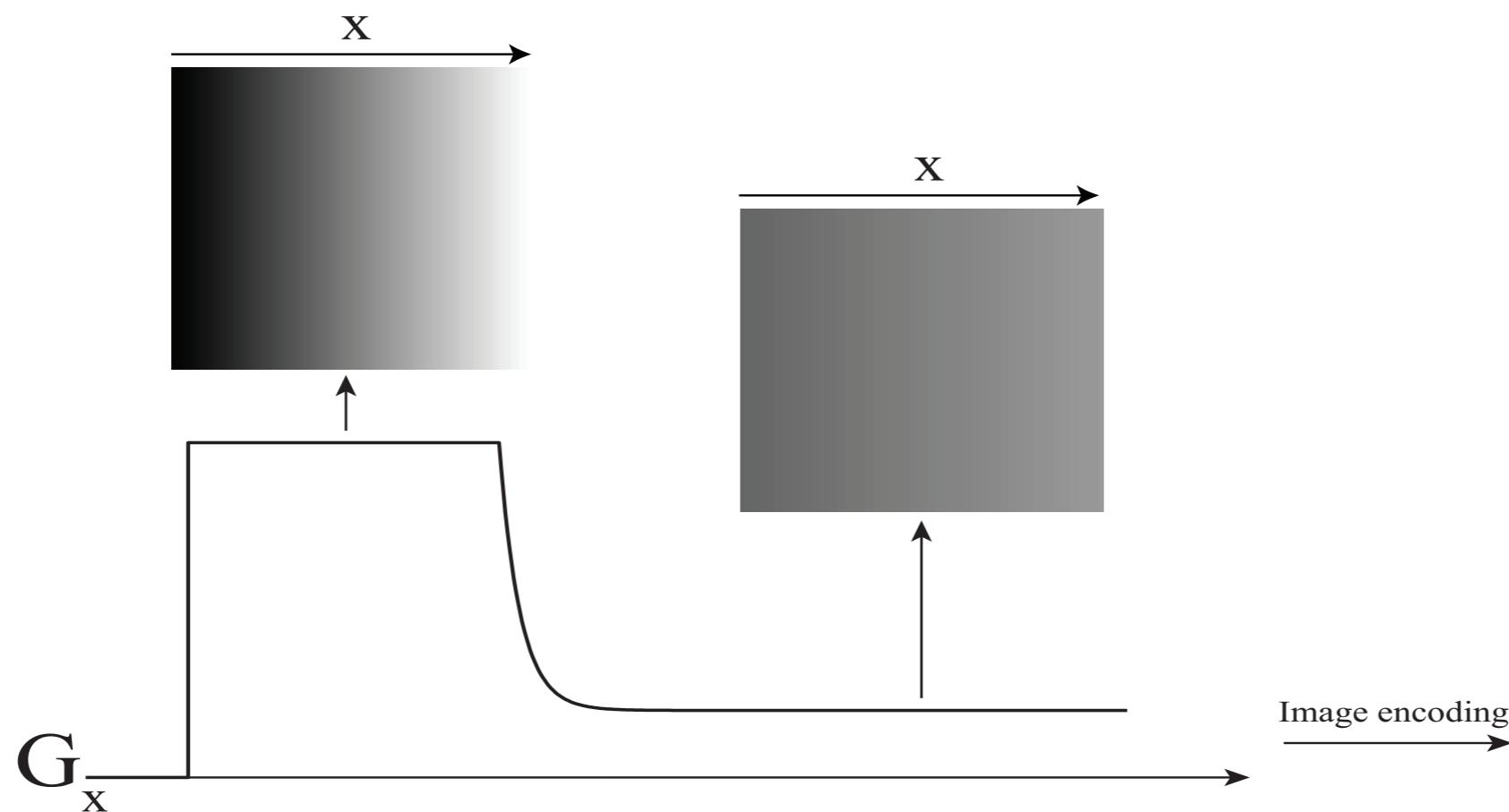
Where does the off-resonance field come from?

非共振场来自哪里?

- There are two sources 有两个来源
- The first is the object (head) itself. 第一个是对象 (头部) 本身



- The second is caused by the diffusion gradient 第二是由扩散梯度引起的





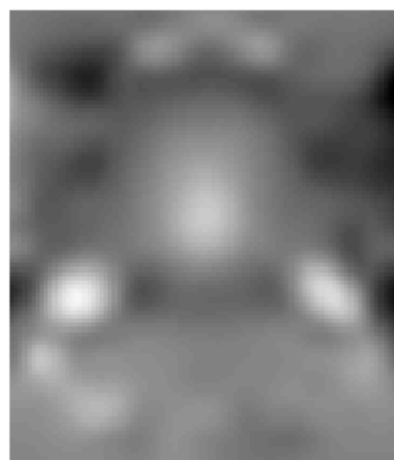
Where does the off-resonance field come from?

非共振场来自哪里?

So for any diffusion weighted volume the off-resonance field is the sum of these two contributions

因此，对于任何扩散加权图像，非共振场都是这两个贡献的总和

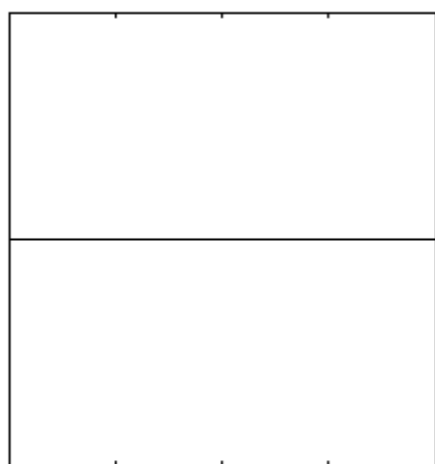
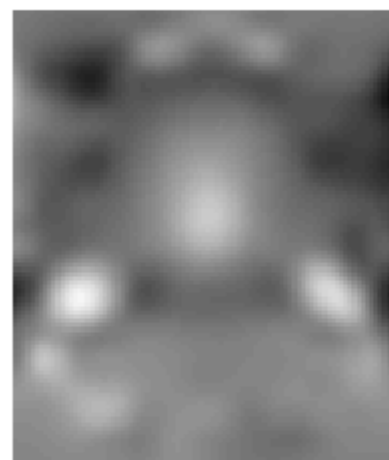
受磁率 Susceptibility Eddy currents 涡流 Total 总和



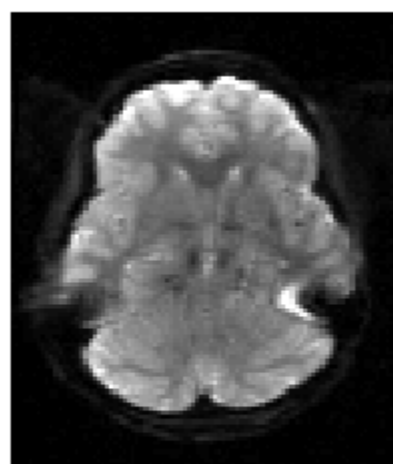
+



=

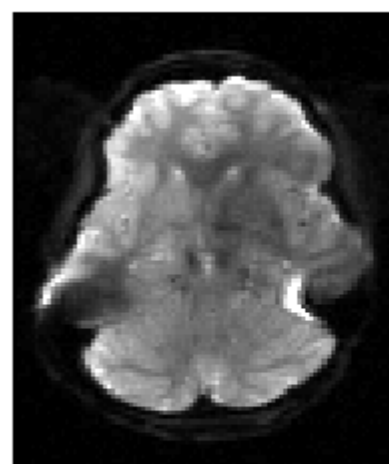


梯度场 Diffusion gradient



“True” object

真实图像



Observed image

观察到的图像

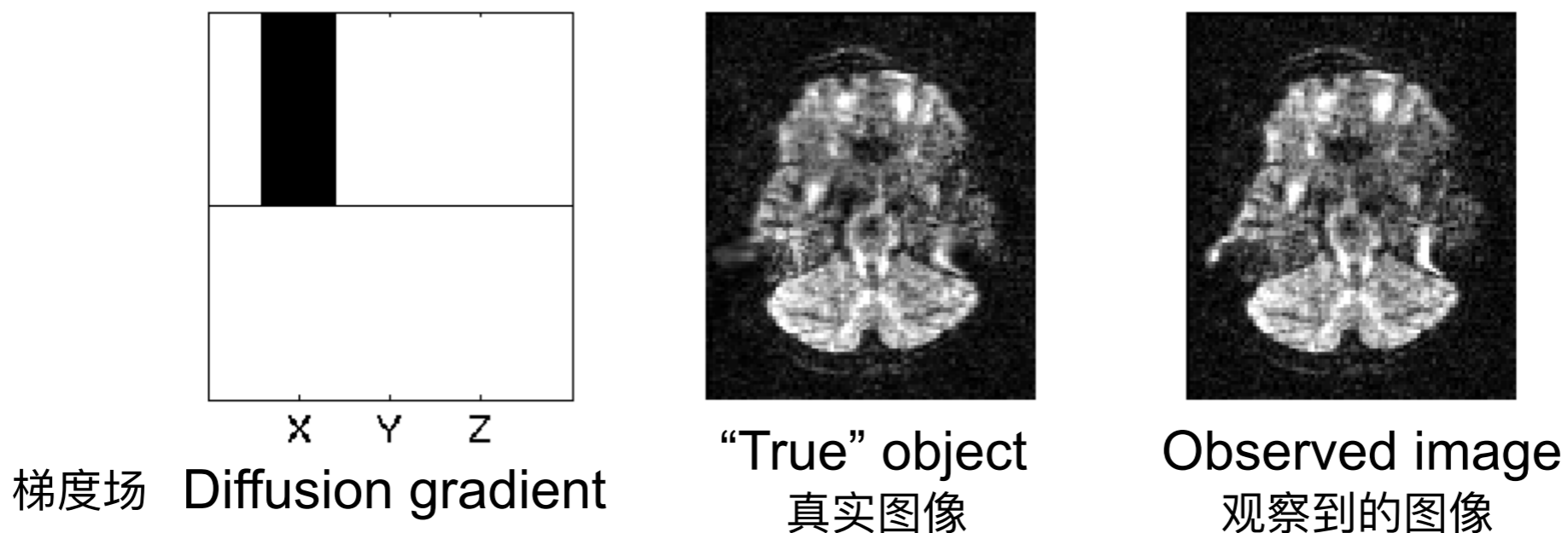
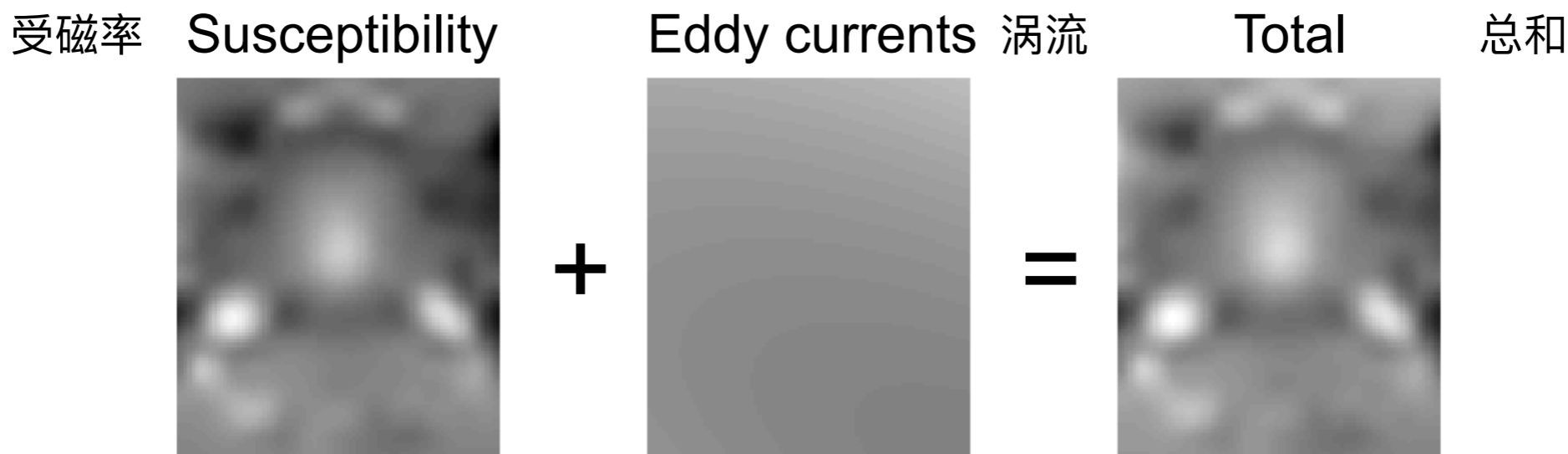


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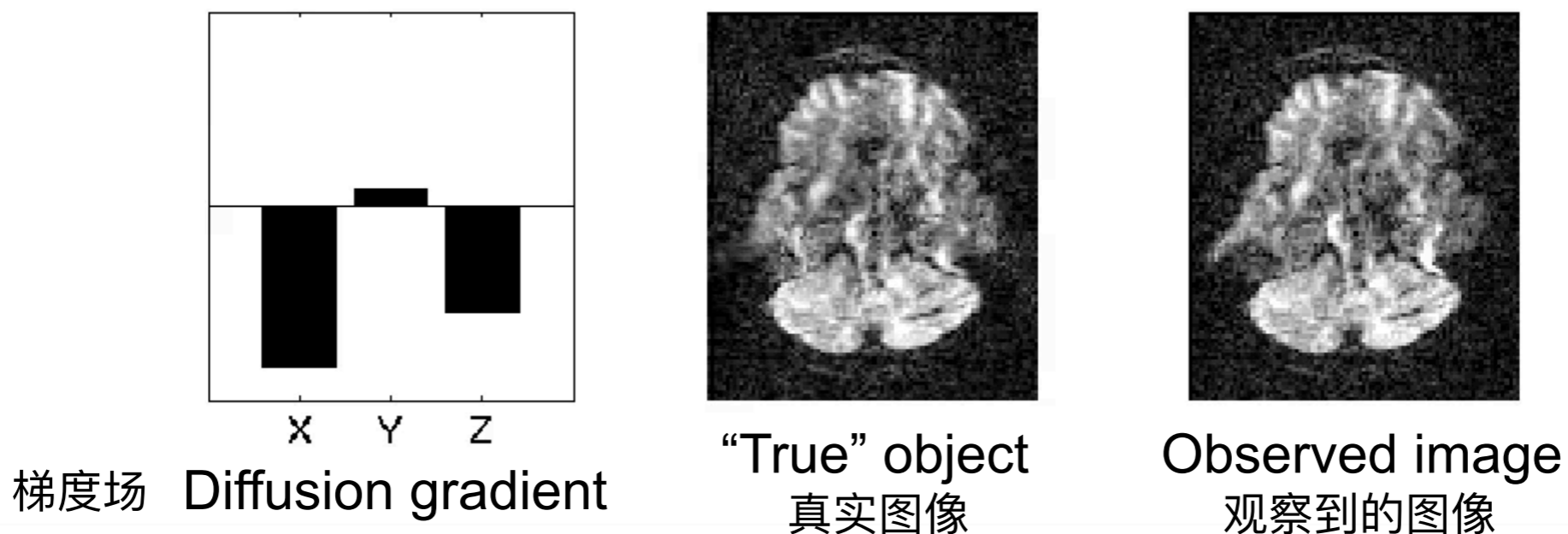
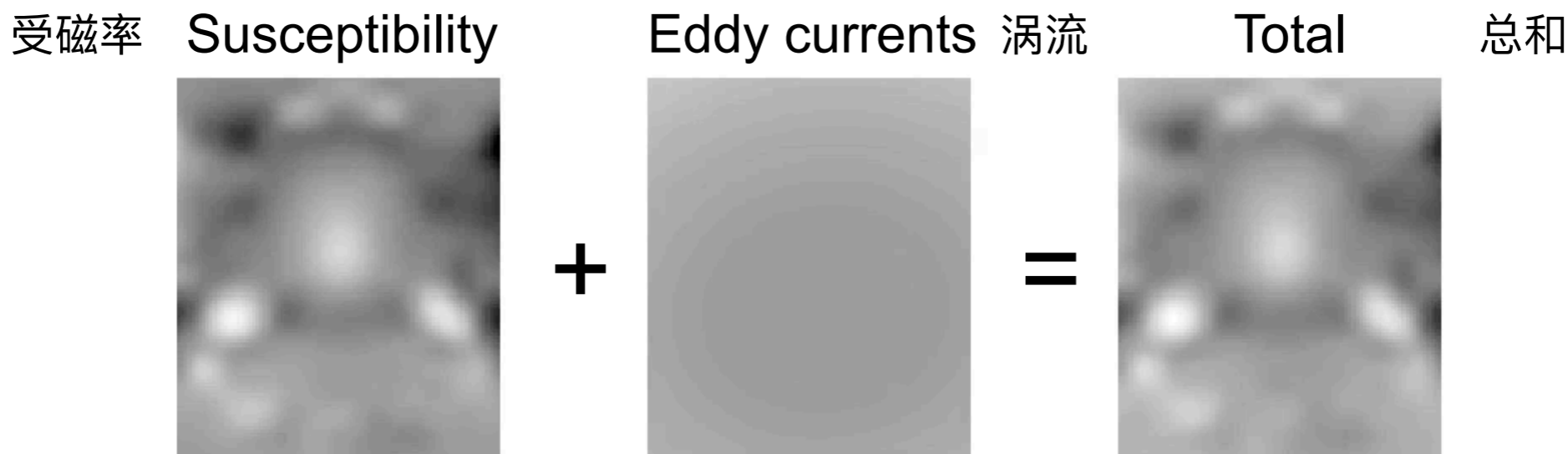


Where does the off-resonance field come from?

非共振场来自哪里?

So for any diffusion weighted volume the off-resonance field is the sum of these two contributions

因此，对于任何扩散加权图像，非共振场都是这两个贡献的总和





Separate estimation of susceptibility- and eddy current-fields

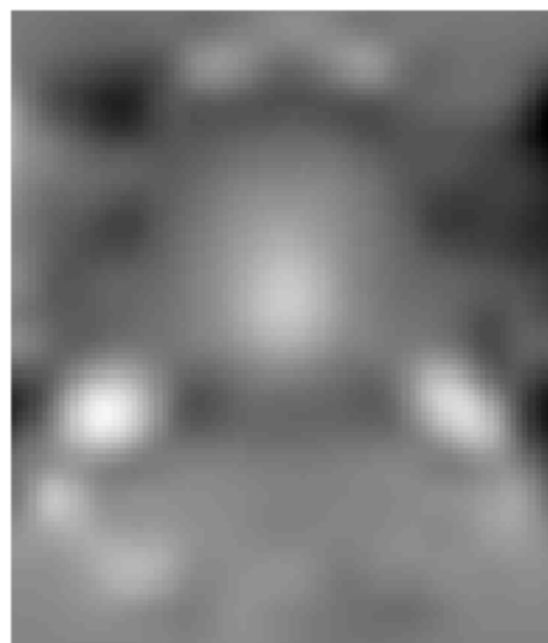
磁化场和涡流场的单独估算

So, what we need to estimate is

因此，我们需要估算的是

One of these per subject

其中一个被试



One of these per volume

其中一个体素



FSL-tools:

topup

eddy



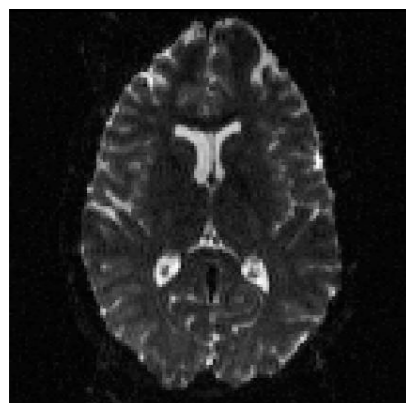
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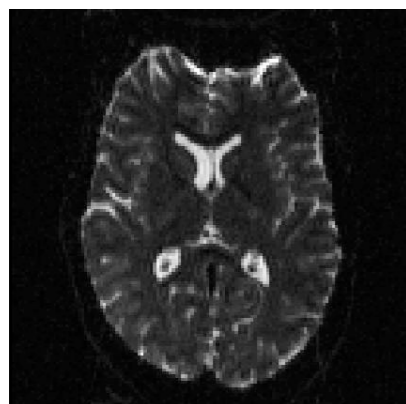


How topup works (very briefly)

topup的工作原理 (非常简短)



$p=[0 \ 1 \ 0]$



$p=[0 \ -1 \ 0]$

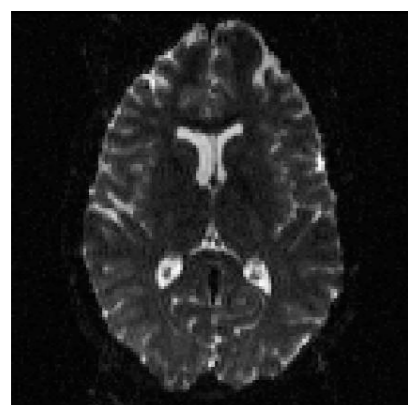
Given two images acquired with different phase-encoding

给定两个使用不同相位编码获取的图像

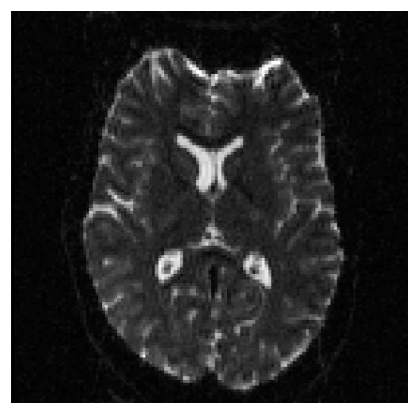


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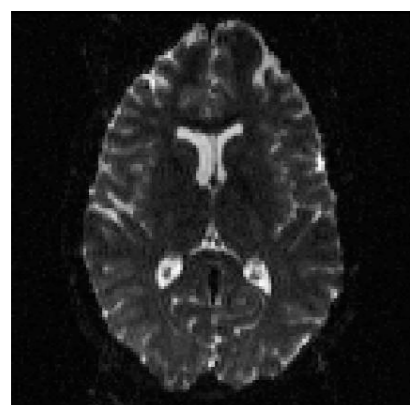
topup “guesses” a field...

topup 猜测一个场

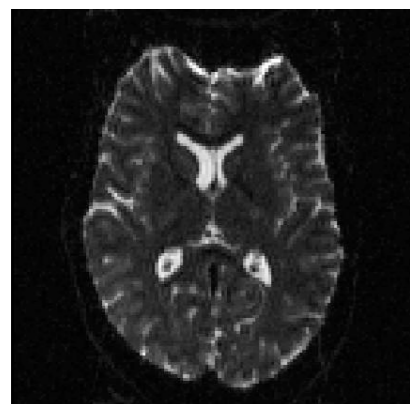


How topup works (very briefly)

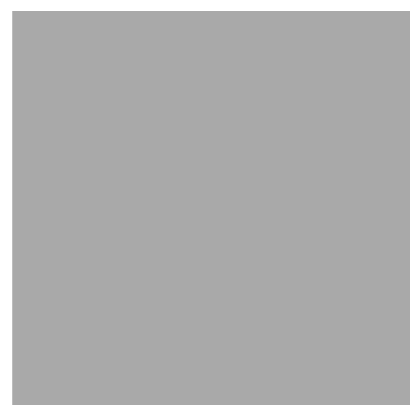
topup的工作原理 (非常简短)



$p=[0 \ 1 \ 0]$



$p=[0 \ -1 \ 0]$



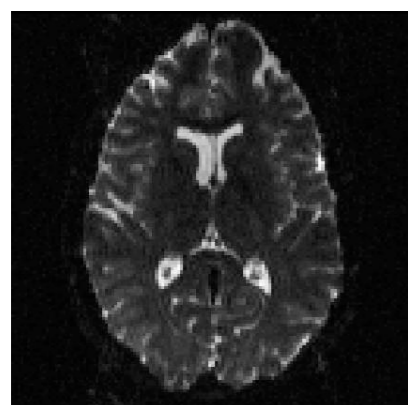
...calculates the displacement maps...

...计算位移图...

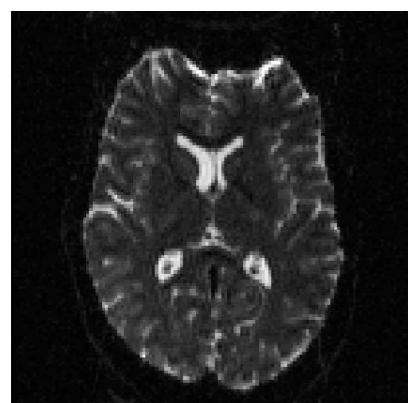
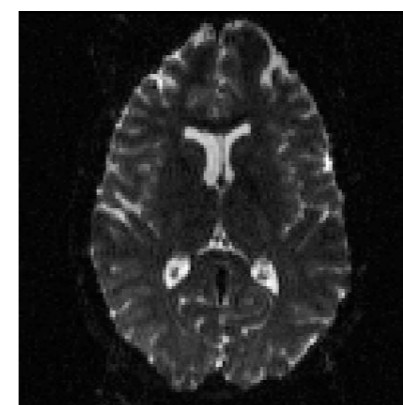


How topup works (very briefly)

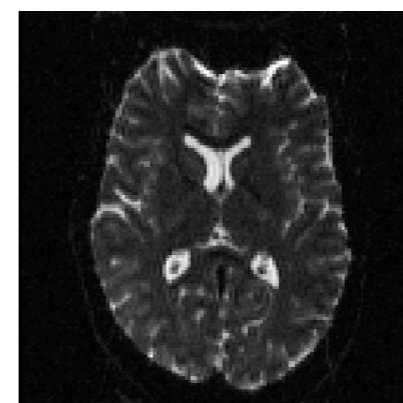
topup的工作原理 (非常简短)



$p=[0 \ 1 \ 0]$



$p=[0 \ -1 \ 0]$



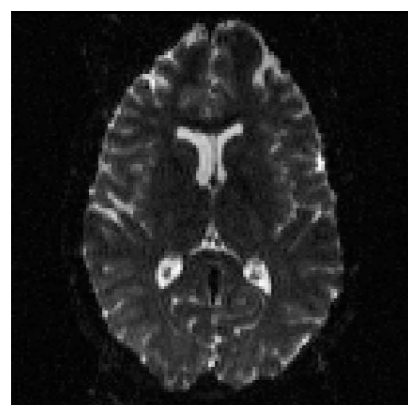
... "corrects" the images...

校正图像

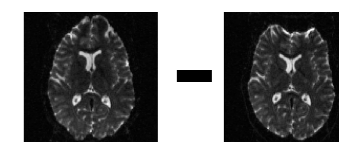
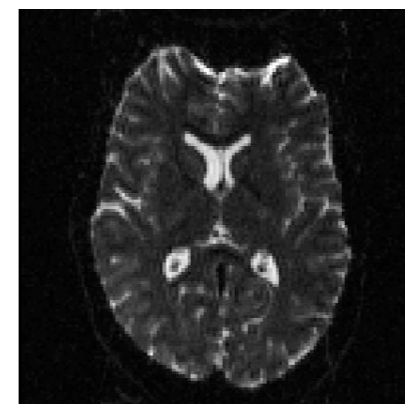
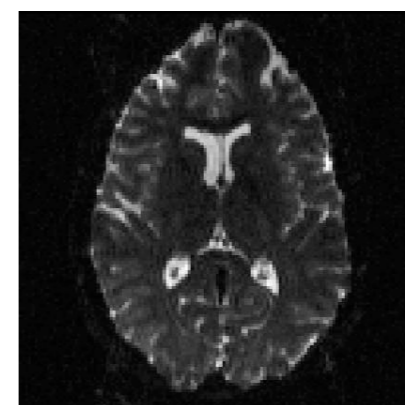
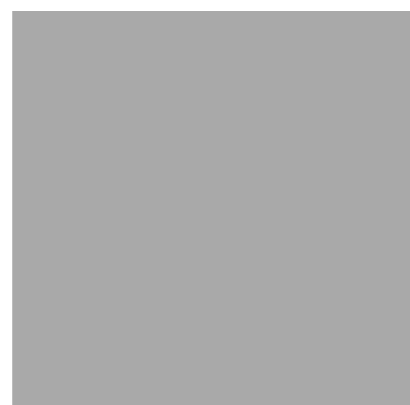


How topup works (very briefly)

topup的工作原理 (非常简短)

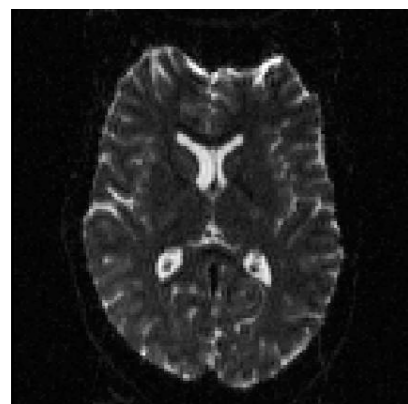


$p=[0 \ 1 \ 0]$



BAD!

差



$p=[0 \ -1 \ 0]$

...and evaluates the results...

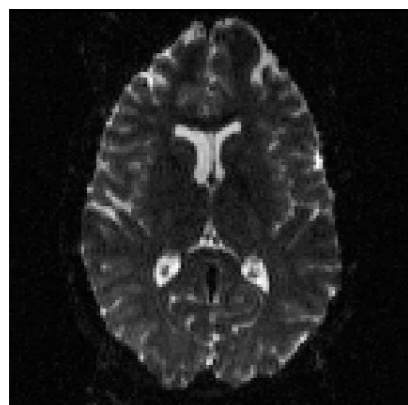
And **this** is the crucial bit.

...并评估结果...这是至关重要的一点。

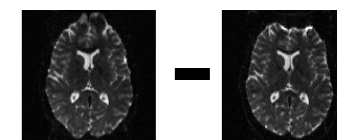
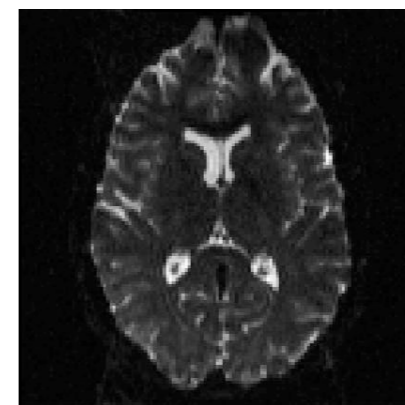
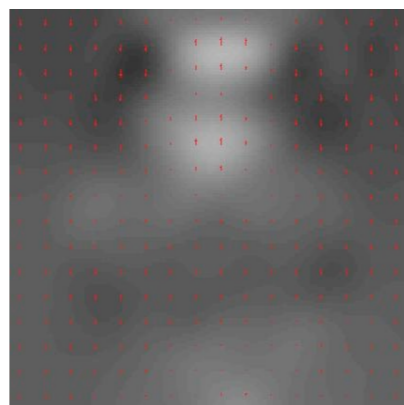
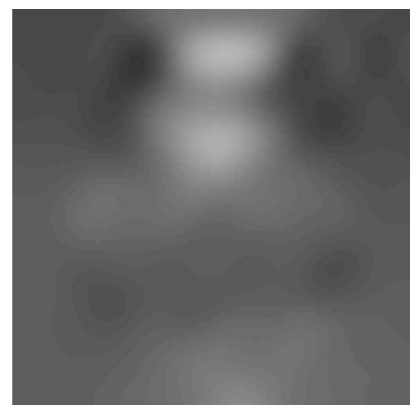


How topup works (very briefly)

topup的工作原理 (非常简短)

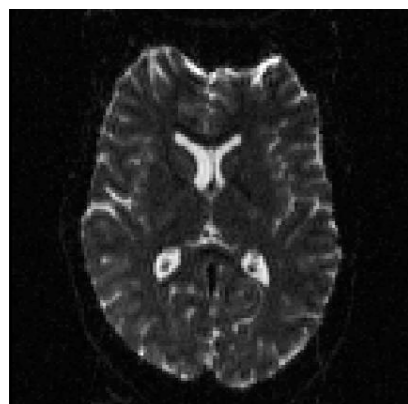


$p=[0 \ 1 \ 0]$

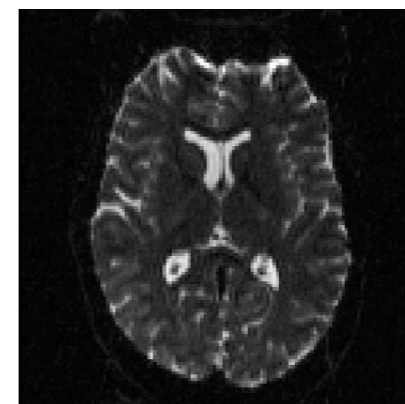
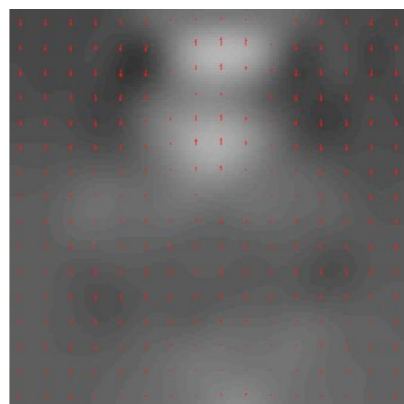


better

好



$p=[0 \ -1 \ 0]$



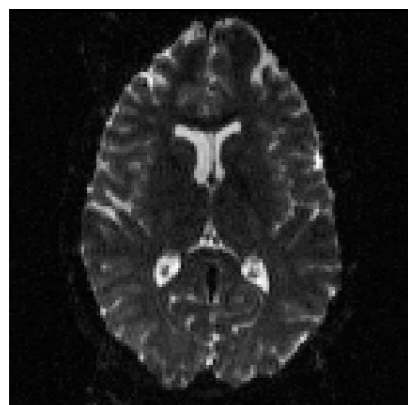
Because topup can then “guess” another field

因为topup然后可以“猜测”另一个场

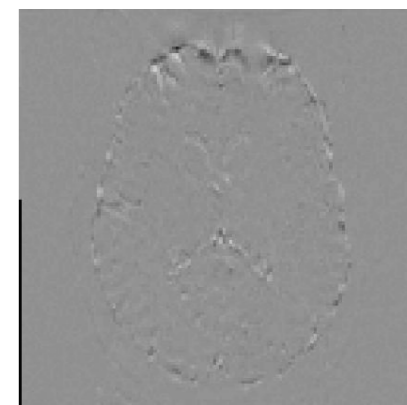
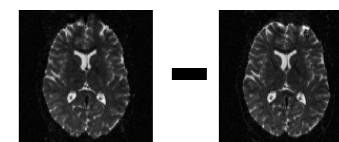
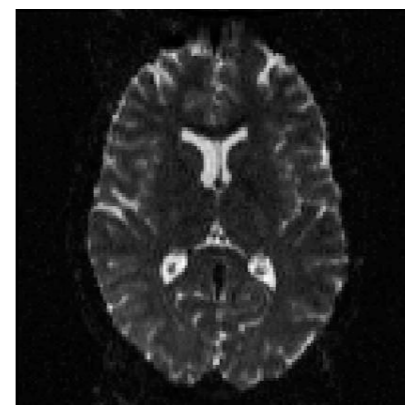
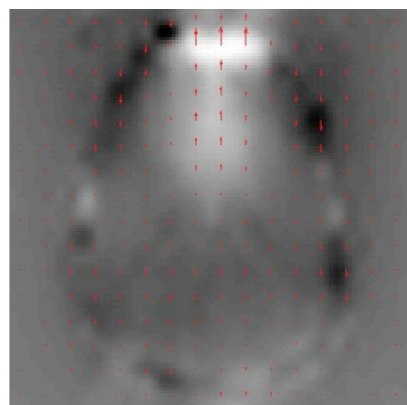
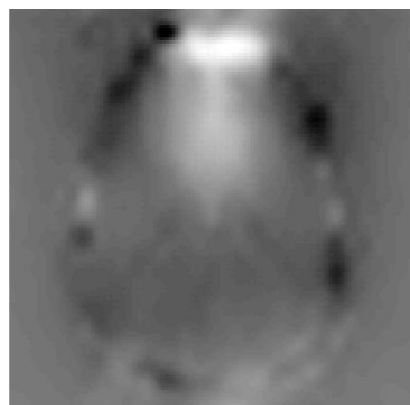


How topup works (very briefly)

topup的工作原理 (非常简短)

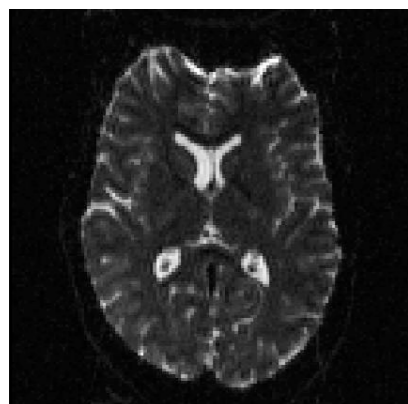


$p=[0 \ 1 \ 0]$

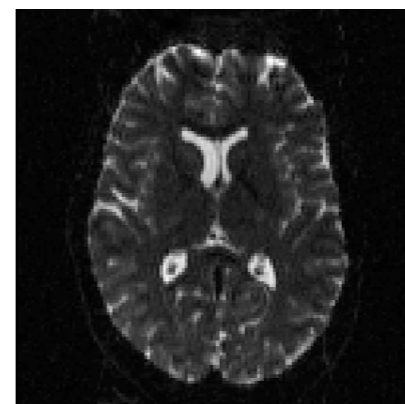
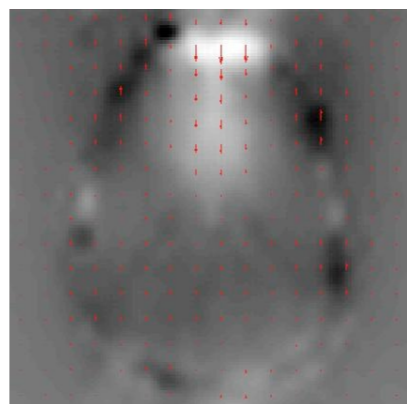


even
better

更好



$p=[0 \ -1 \ 0]$



...and another...until it is happy,
and then it "knows" the field
还有一个...直到高兴, 然后才"知道"这个场



Outline of the talk 大纲

- What is the problem with diffusion data? 扩散数据有什么问题?
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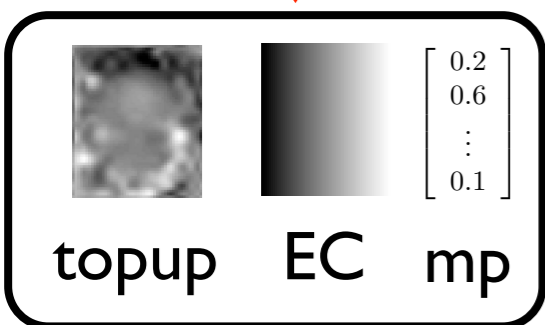
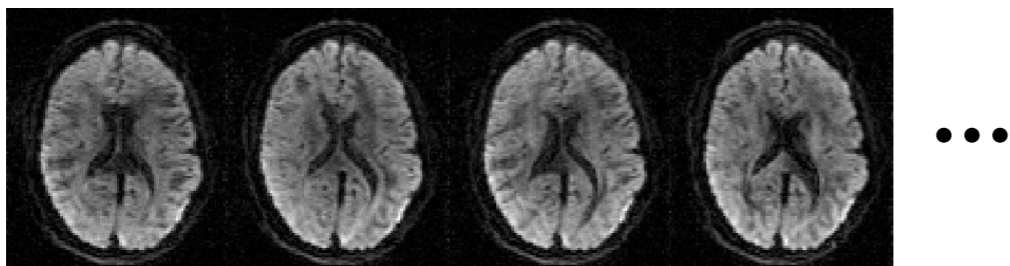


How eddy works

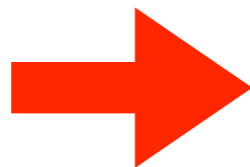
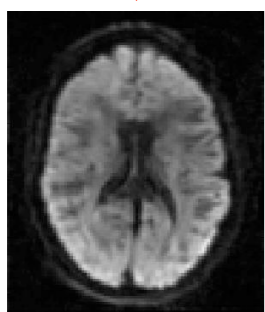
涡流的工作原理

1. For all scans 对于所有扫描

$[1\ 0\ 0]$ $[.6\ -.4\ -.7]$ $[.8\ .6\ 0]$ $[-.4\ .9\ 0]$...



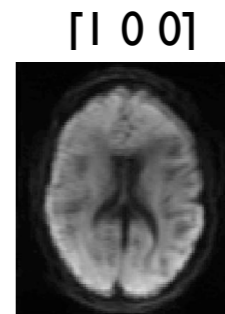
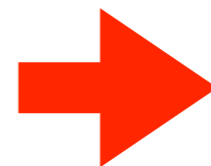
Use susceptibility field and current estimate of EC and movement to "unwarp" scan
使用易感场和 EC 的当前估计值以及运动进行"不扭曲"扫描



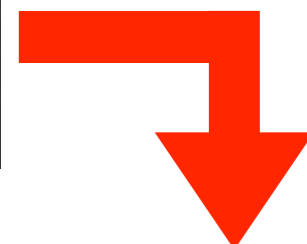
Load into prediction maker

加载到预测创建器

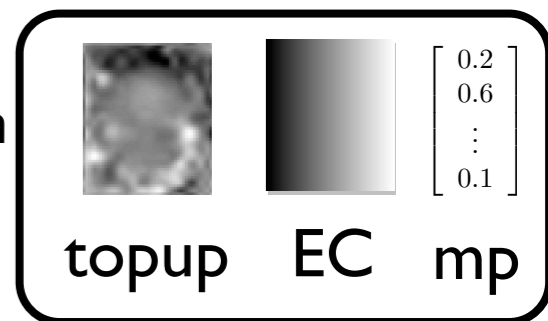
2. For all scans 对于所有扫描



Get prediction
获得预测

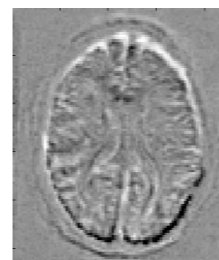


Invert current transform
反转当前矩阵



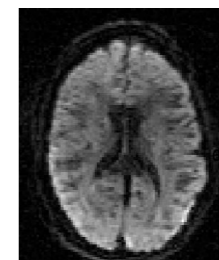
Use difference to update EC and mp
使用差异来更新

EC 和 mp

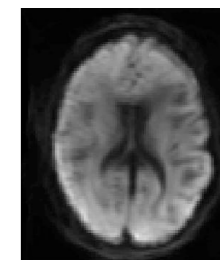


Get prediction in scan space
在扫描空间获取预测

$[1\ 0\ 0]$



$[1\ 0\ 0]$

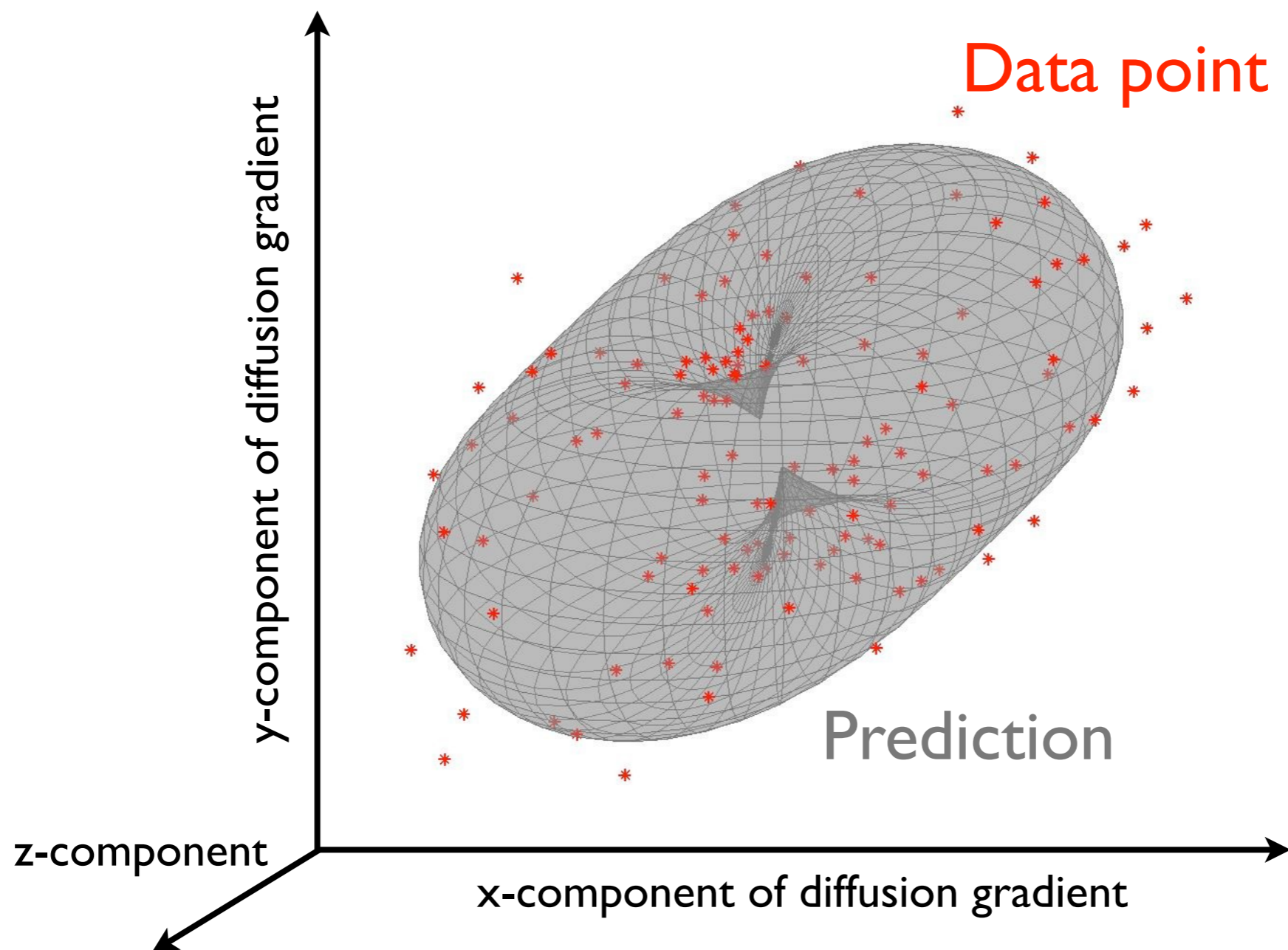


Compare to scan
与扫描进行比较



Under the hood of Zoltar

现在让我们掀起Zoltar的盖头来



The signal is “modelled” in a data-driven fashion assuming that points close together on the unit sphere have similar signal.

假设在单位球体上靠近的点具有相似的信号，则以数据驱动的方式对信号进行“建模”



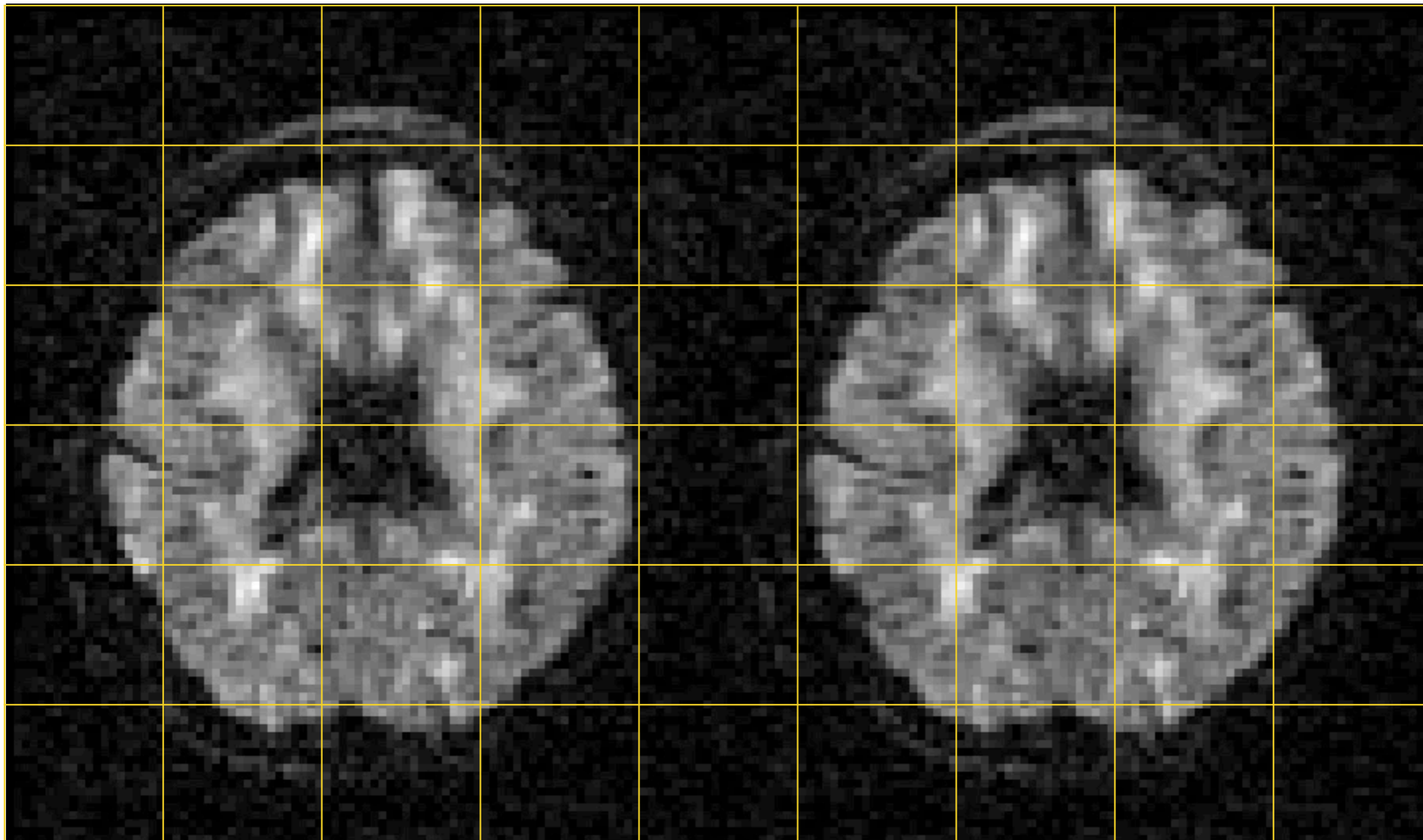
Outline of the talk 大纲

- What is the problem with diffusion data? 扩散数据有什么问题?
- Off-resonance field 非共振场
 - How does it cause distortions? 它如何引起失真?
 - Where does it come from? 它从何而来?
- Registering diffusion data 弥散数据的配准
 - How topup works topup topup如何起作用补满的?
 - How eddy works eddy eddy实现涡流矫正?
- Practicalities 实用性
- **Some results** 一些结果
- Quality control 质控
- New eddy features 新的涡流功能



HCP-data, 150 directions, $b=3000$, blip-up-blip-down

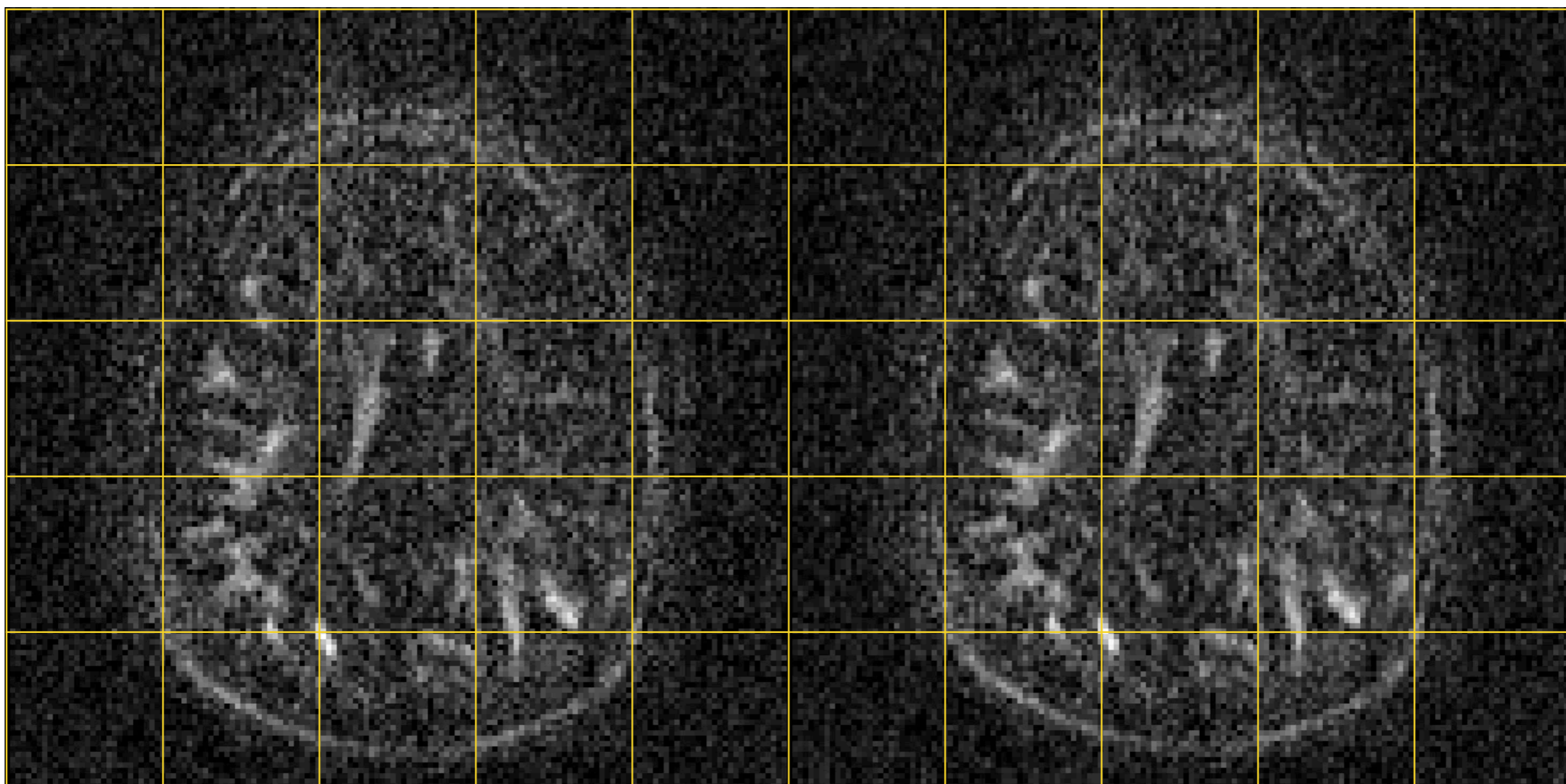
HCP 数据, 150 个方向, $b=3000$, 向上一向下





MGH-data, 198 directions, b=10000!

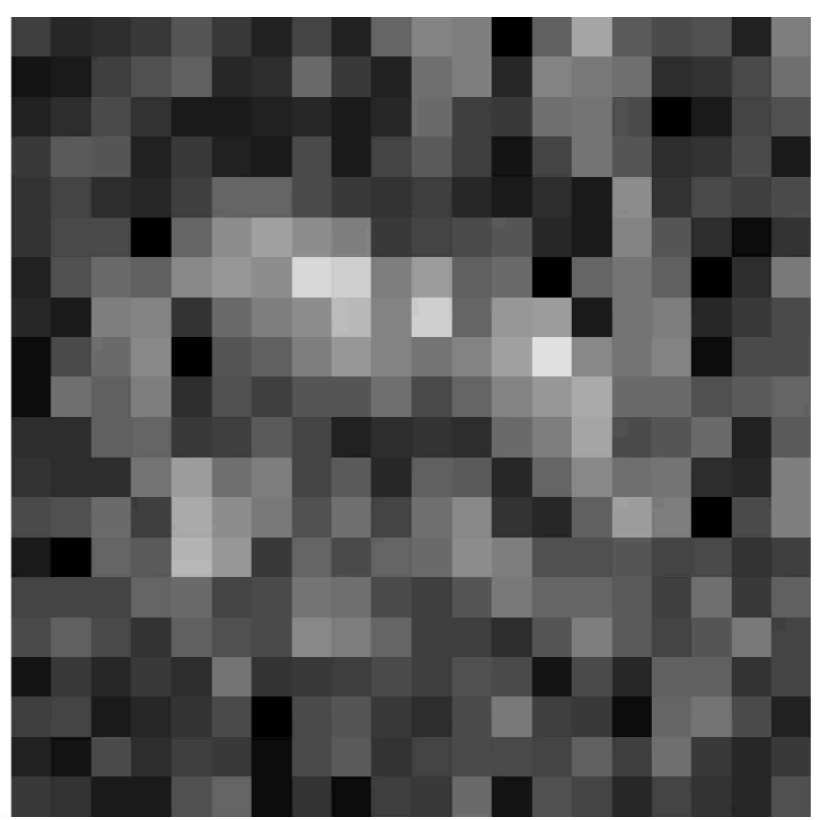
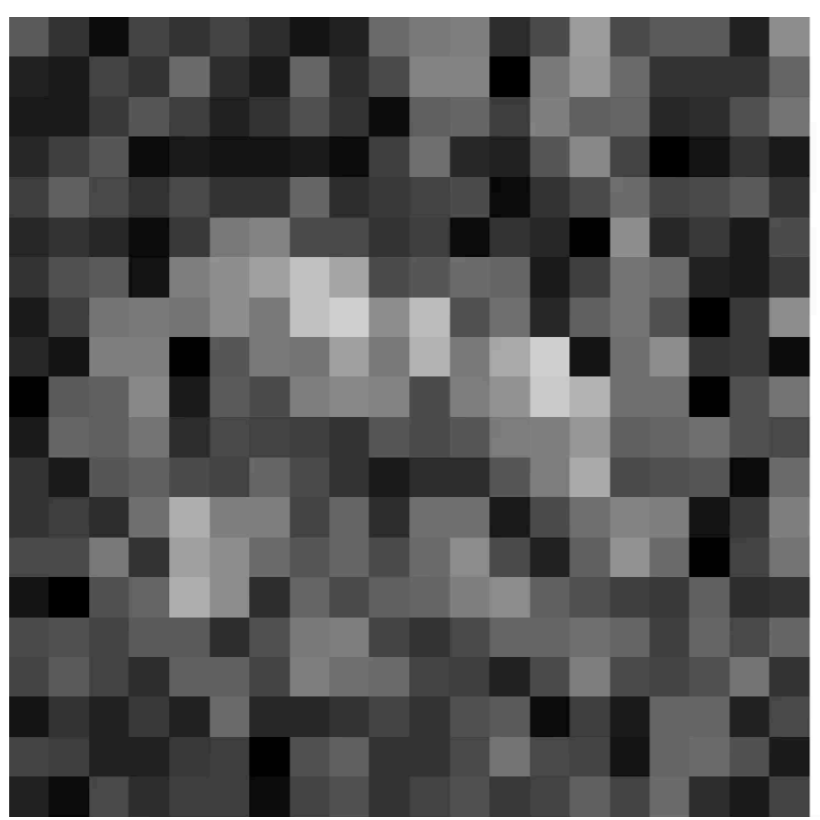
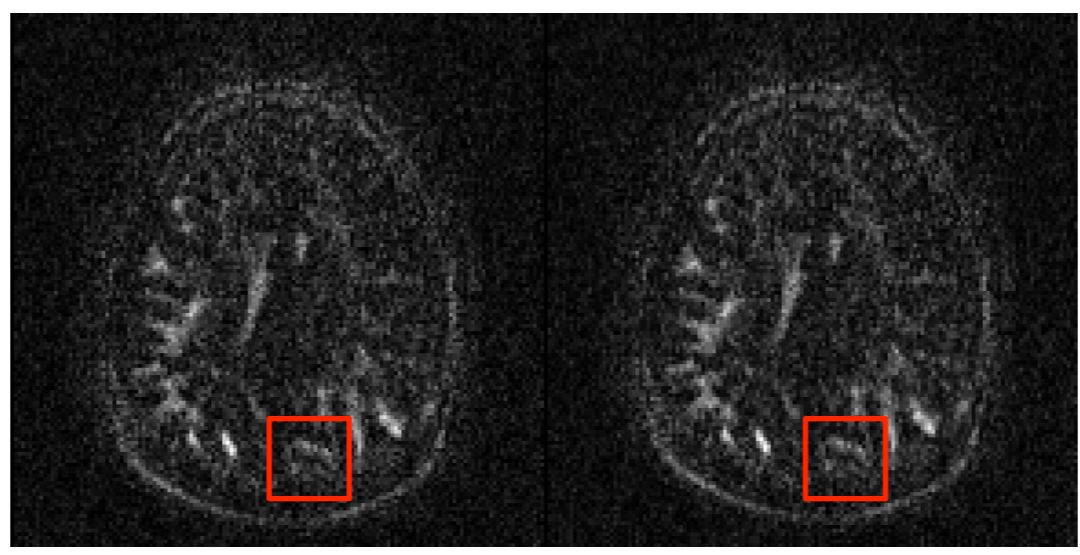
MGH 数据, 198 方向, b=10000!





MGH-data, 198 directions, $b=10000!$

MGH 数据, 198 方向, $b=10000!$





Outline of the talk 大纲





- What is the problem with diffusion data? 扩散数据有什么问题?
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EDDY QC: data quality summary

涡流质控：数据质量总结

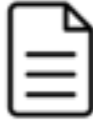
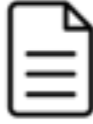

QUAD
(subject)

 S1/qc.json
 S2/qc.json
 S3/qc.json
.
.
.
 S_n/qc.json

SQUAD
(study)

 qc_group.pdf

 qc_group.json

 P1/qc.json
 P2/qc.json
 P3/qc.json

...



EDDY QC: single-subject reports

涡流质控：单个被试报告

Biobank subject A

Volume-to-volume motion

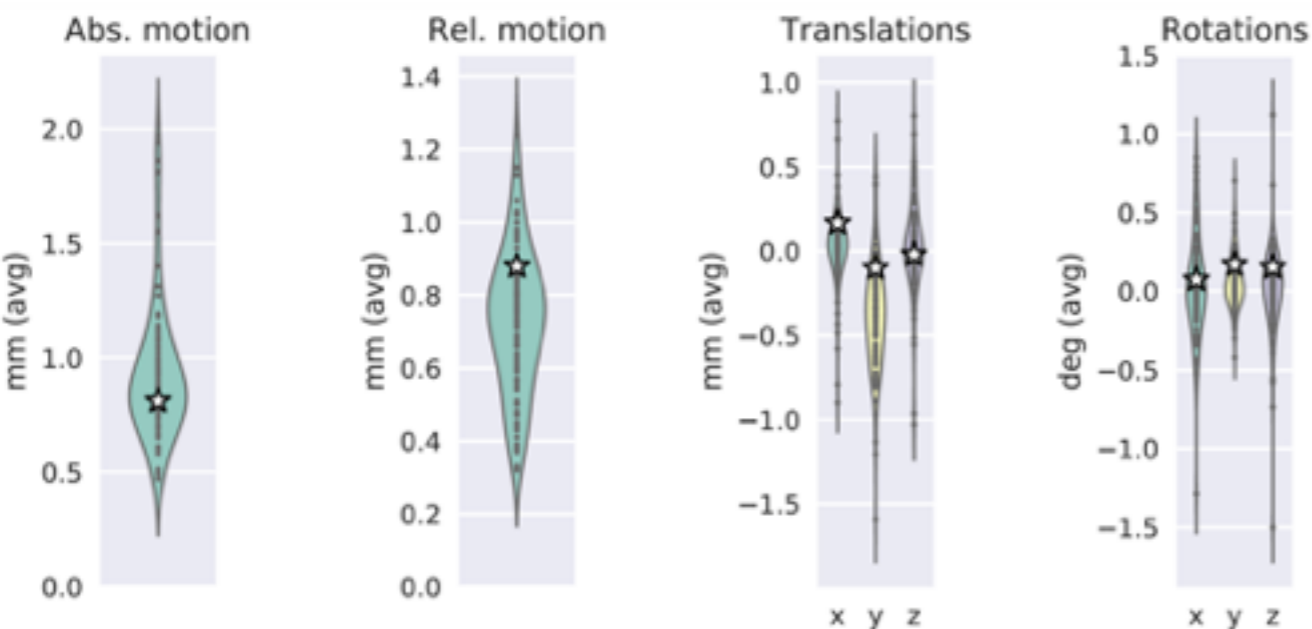
Average abs. motion (mm)	0.81
Average rel. motion (mm)	0.88
Average x translation (mm)	0.17
Average y translation (mm)	-0.10
Average z translation (mm)	-0.02
Average x rotation (deg)	0.07
Average y rotation (deg)	0.17
Average z rotation (deg)	0.15

Within-volume motion

Avg std x translation (mm)	0.02
Avg std y translation (mm)	0.11
Avg std z translation (mm)	0.04
Avg std x rotation (deg)	0.05
Avg std y rotation (deg)	0.05
Avg std z rotation (deg)	0.06

Outliers

Total outliers (%)	0.11
Outliers (b=1000 s/mm ²)	0.22
Outliers (b=2000 s/mm ²)	0.00
Outliers (PE dir=[0. 1. 0.])	0.00
Outliers (PE dir=[0. -1. 0.])	0.11



Biobank subject B

Volume-to-volume motion

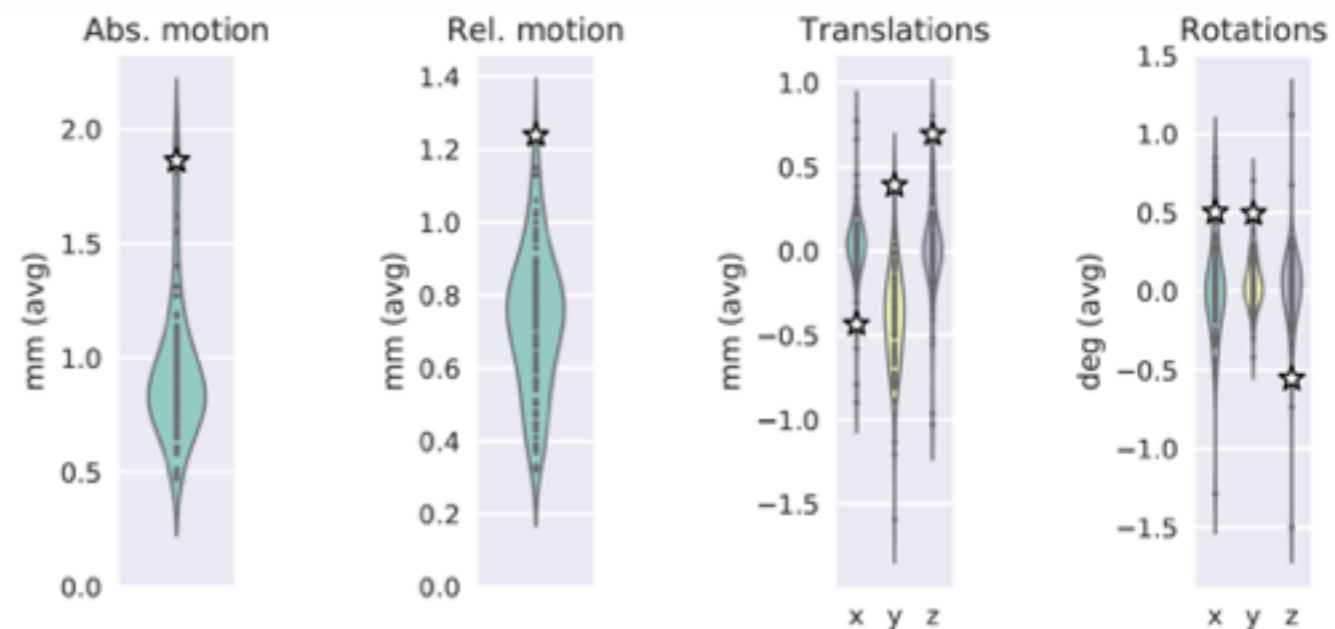
Average abs. motion (mm)	1.86
Average rel. motion (mm)	1.24
Average x translation (mm)	-0.43
Average y translation (mm)	0.39
Average z translation (mm)	0.69
Average x rotation (deg)	0.50
Average y rotation (deg)	0.49
Average z rotation (deg)	-0.55

Within-volume motion

Avg std x translation (mm)	0.08
Avg std y translation (mm)	0.22
Avg std z translation (mm)	0.13
Avg std x rotation (deg)	0.15
Avg std y rotation (deg)	0.09
Avg std z rotation (deg)	0.11

Outliers

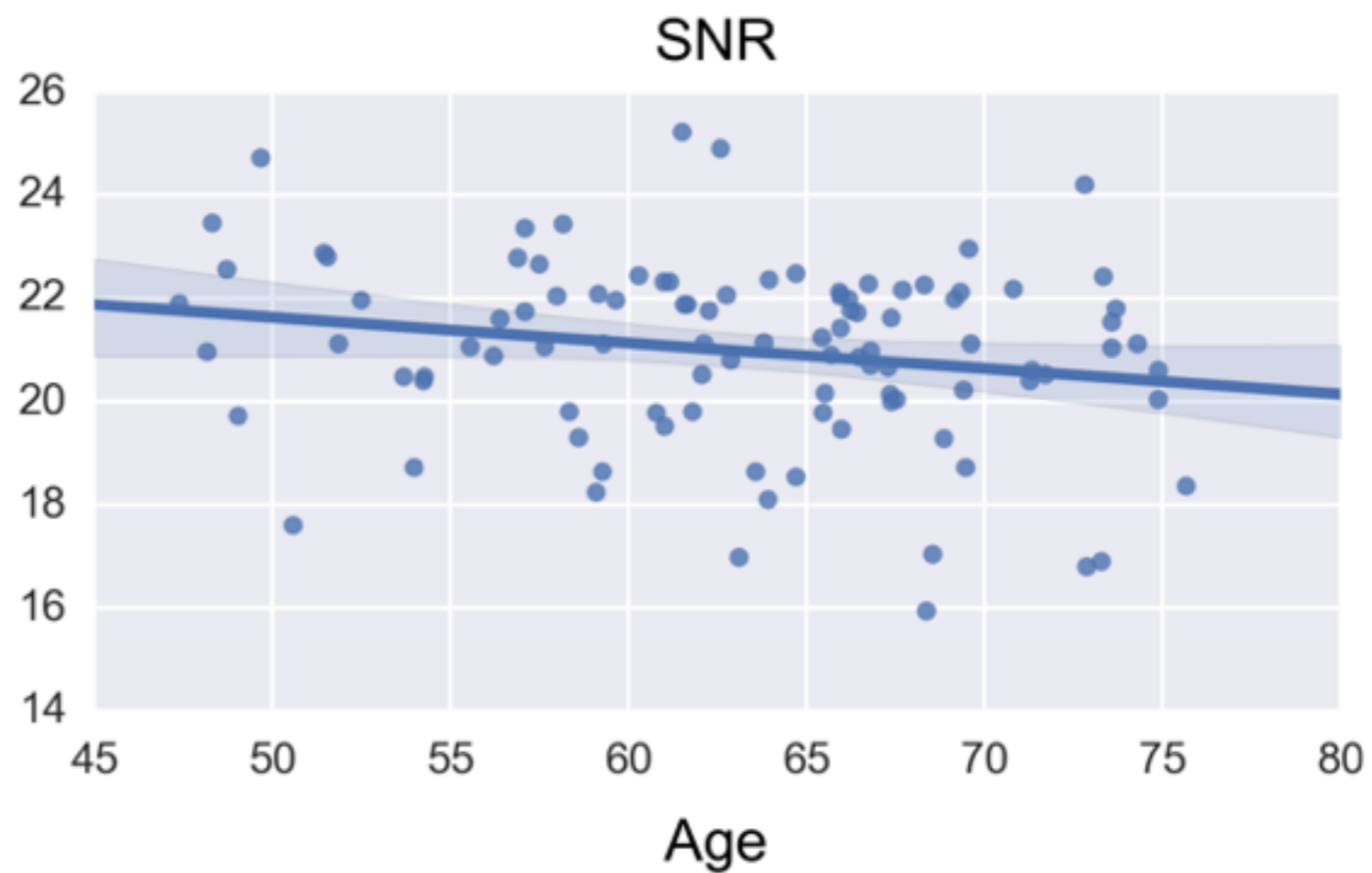
Total outliers (%)	2.86
Outliers (b=1000 s/mm ²)	4.69
Outliers (b=2000 s/mm ²)	1.13
Outliers (PE dir=[0. 1. 0.])	2.55
Outliers (PE dir=[0. -1. 0.])	2.66





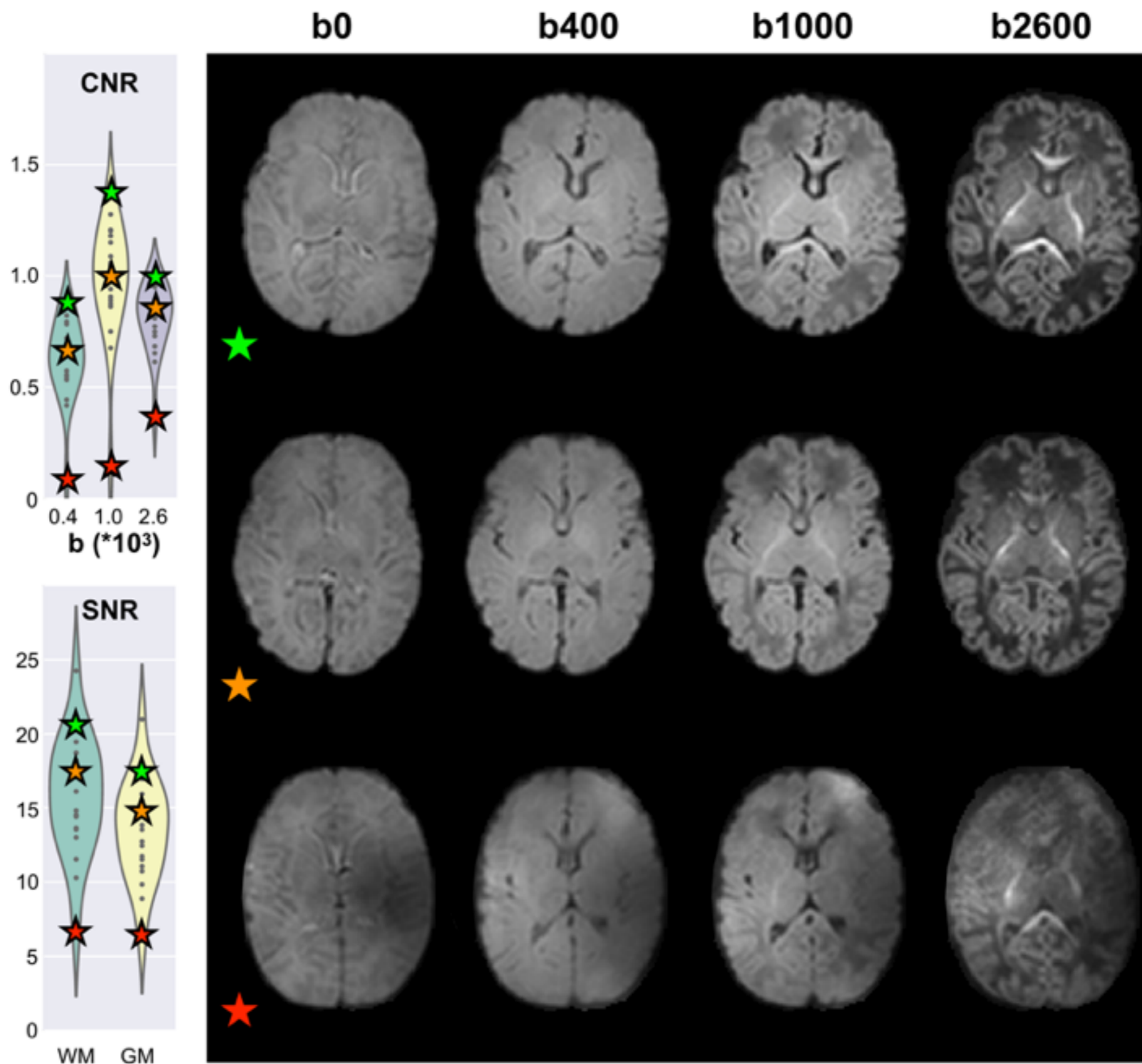
EDDY QC: group report

涡流质控：组报告





Data quality illustration 数据质量说明





Outline of the talk

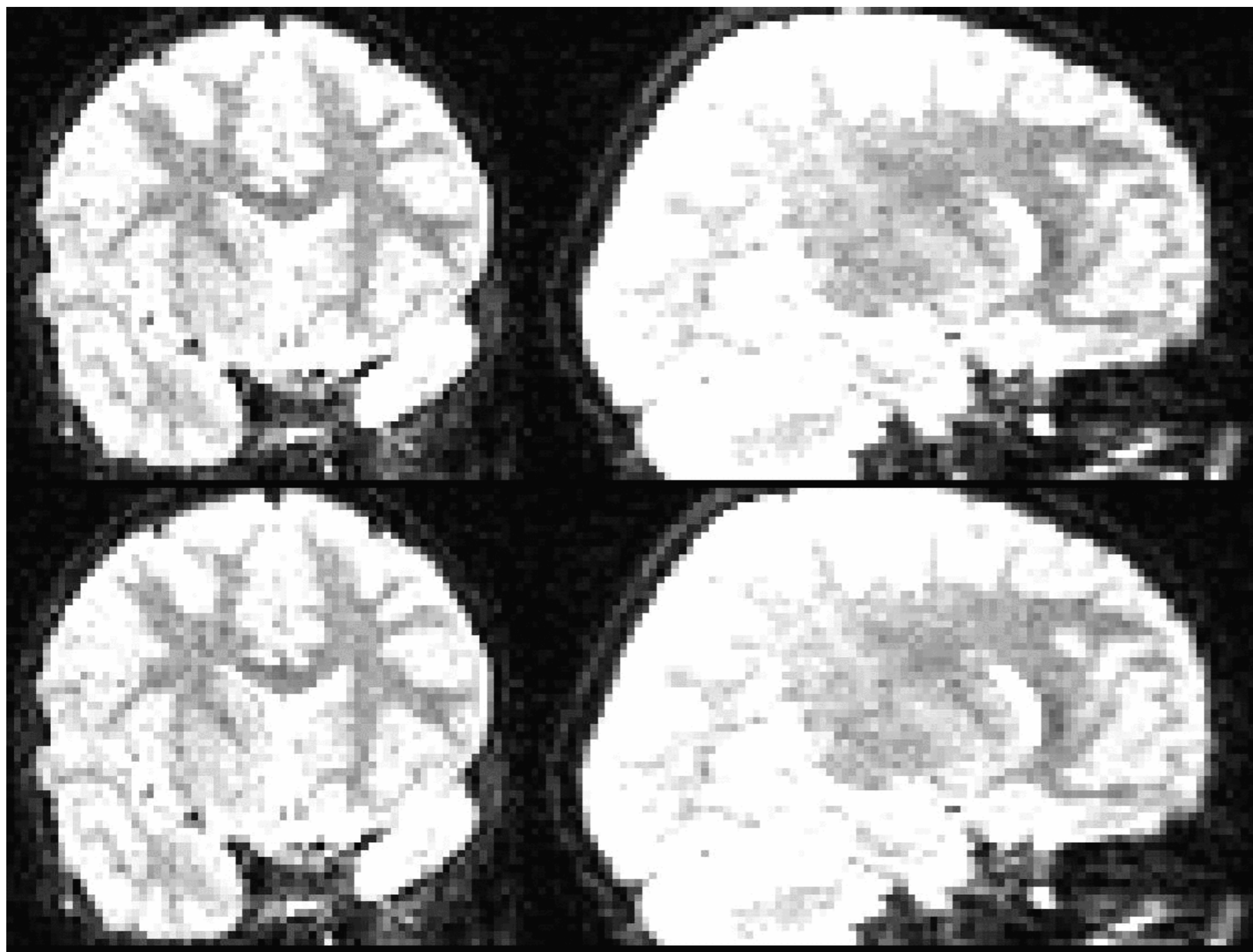
概况

- What is the problem with diffusion data?
- Off-resonance field
- Registering diffusion data
- Practicalities
- Some results
- **New eddy features**
 - **Movement-induced dropout** 运动引起的异常
- Intra-volume motion



Norwegian data. 32 directions.

Hundreds of children. 挪威数据 32个方向 数百名儿童



Eight year old
who gets tired
towards the end
of scanning

八岁的孩子在扫描结束时感到疲倦

After outlier
detection and
replacement by
eddy

经过异常检测并由边缘
值替换



Outline of the talk

概况

- What is the problem with diffusion data?
- Off-resonance field
- Registering diffusion data
- Practicalities
- Some results
- New eddy features
 - Movement-induced dropout
 - **Intra-volume motion** 图像间运动

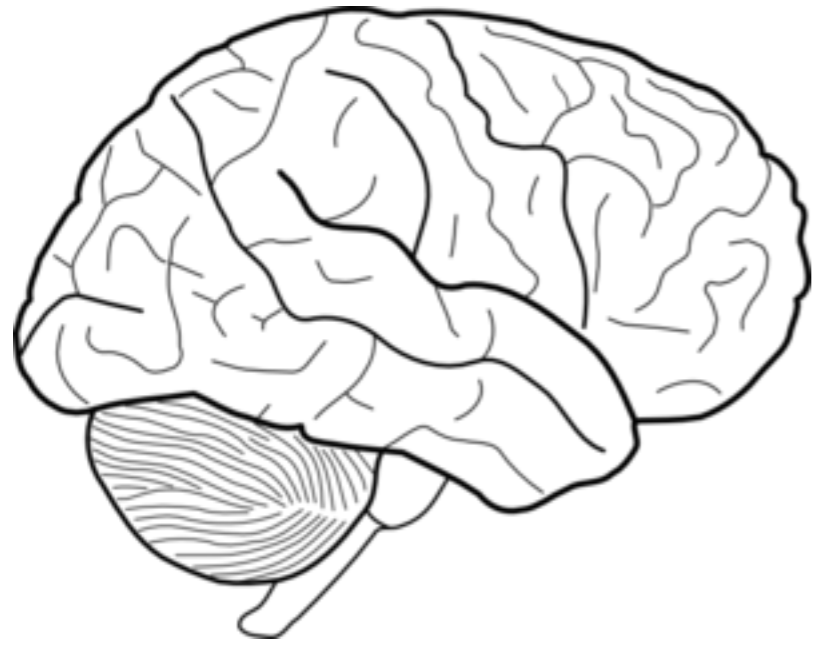


Intra-volume movement

图像间运动

One of the (possibly naive) assumptions of most movement correction is that any movement is instantaneous and occurs between the acquisition of consecutive volumes.

大多数运动校正的（可能是天真的）假设之一是任何运动都是瞬时的并且发生在连续每帧图像的获取之间。



This is the brain we set out to image

这是我们即将开始扫描的大脑

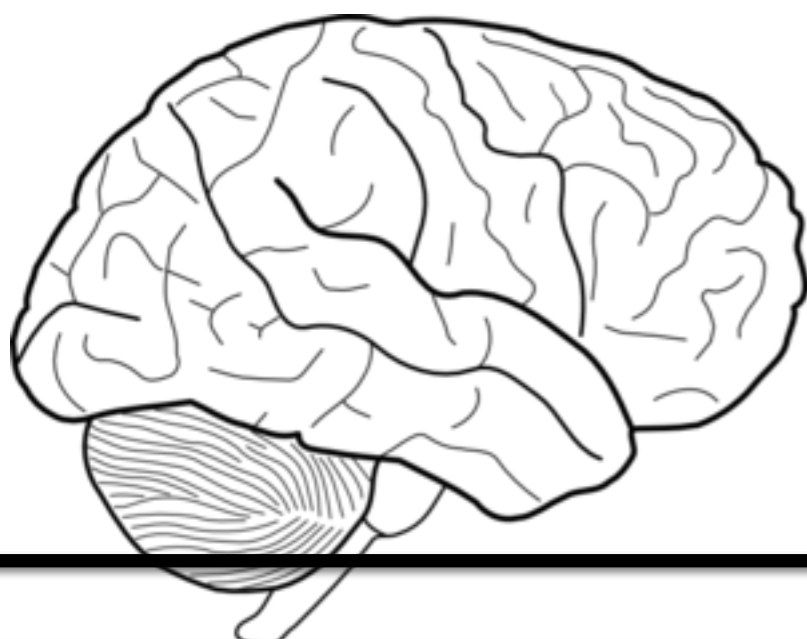


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This is the brain
we set out to
image

这是我们即将开始扫描的大脑



这是我们获得的第一层

And here we have
acquired the first
slice



Intra-volume movement

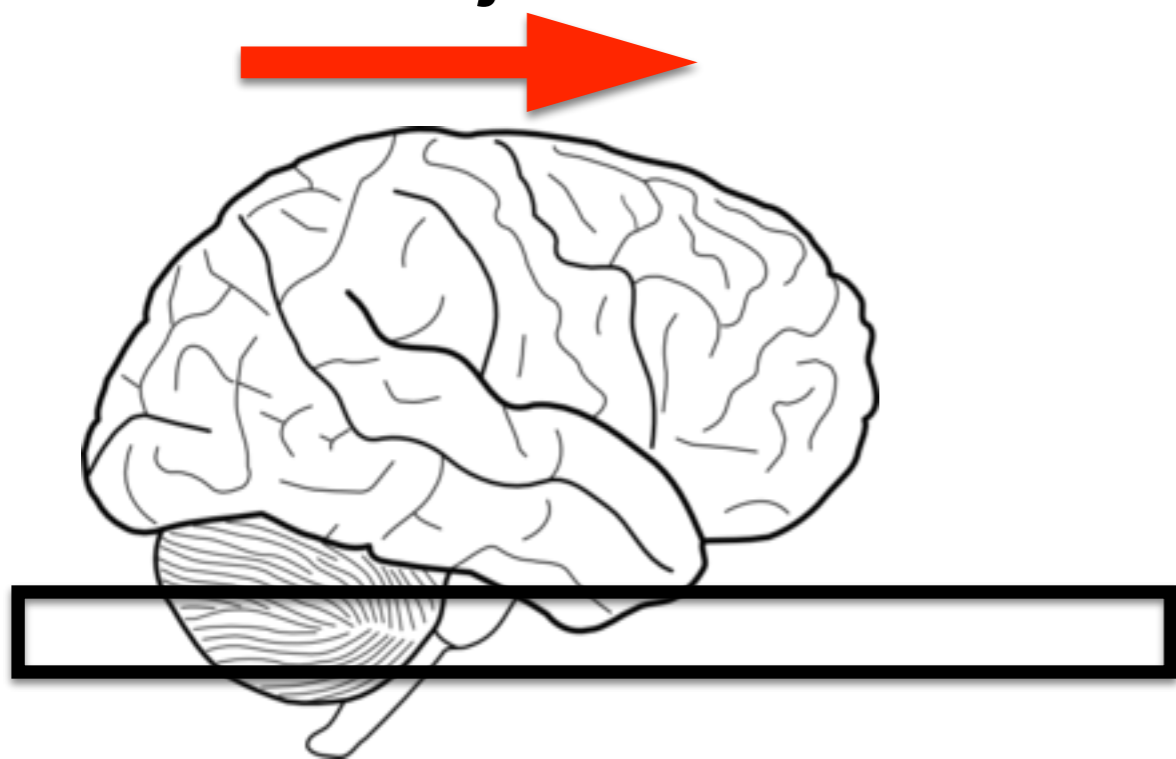
图像间运动

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大多数运动校正的（可能是天真的）假设之一是任何运动都是瞬时的并且发生在连续每帧图像的获取之间。

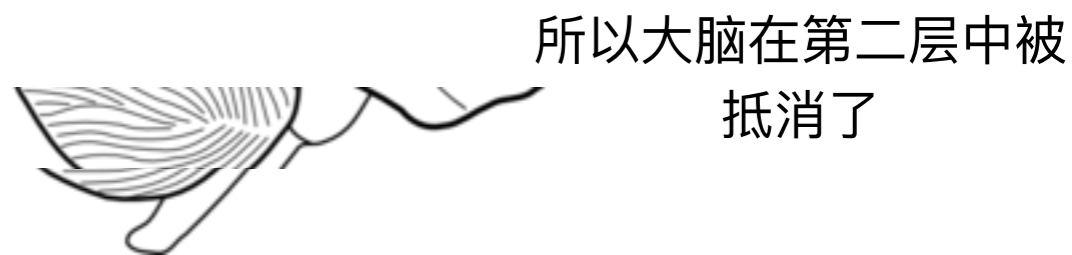
But the subject moves

但是被试在移动



This is the brain we set out to image

这是我们即将开始扫描的大脑



So the brain is offset in the second slice

所以大脑在第二层中被抵消了



Intra-volume movement

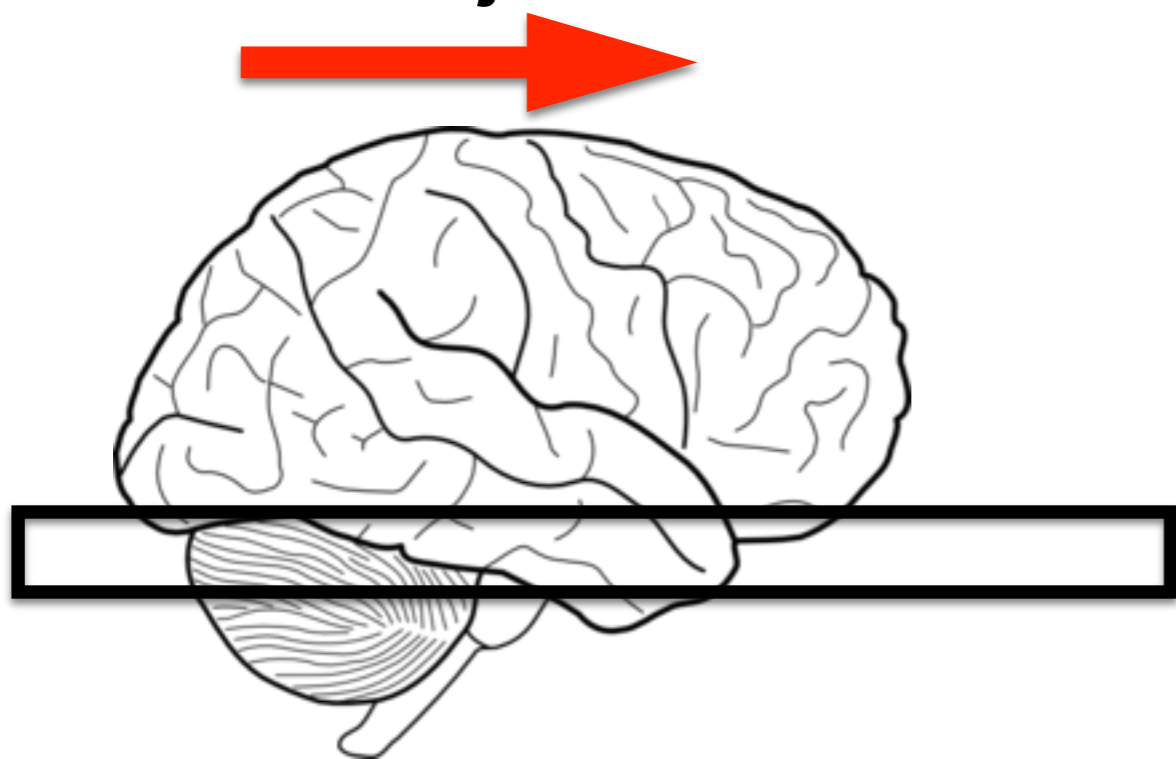
图像间运动

One of the (possibly naive) assumptions of most movement correction is that any movement is instantaneous and occurs between the acquisition of consecutive volumes.

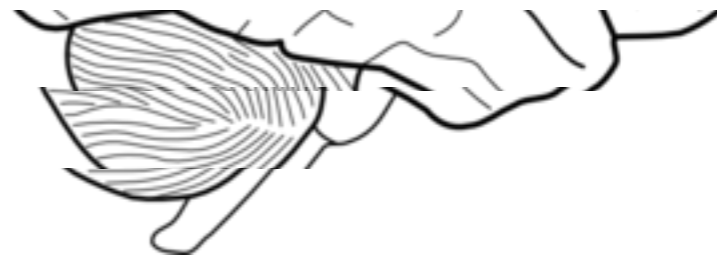
大多数运动校正的（可能是天真的）假设之一是任何运动都是瞬时的并且发生在连续每帧图像的获取之间。

But the subject moves

但是被试在移动



在第三层中更加明显



This is the brain we set out to image

这是我们即将开始扫描的大脑

And even more so in the third slice



Intra-volume movement

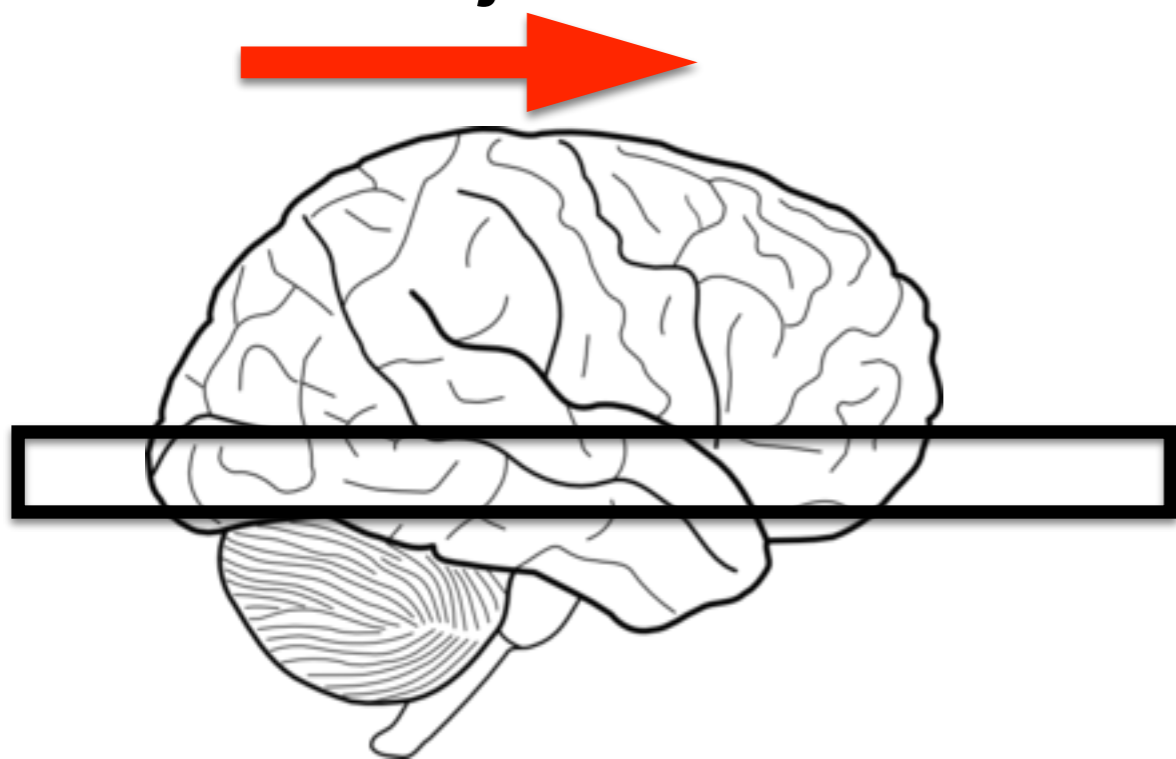
图像间运动

One of the (possibly naive) assumptions of most movement correction is that any movement is instantaneous and occurs between the acquisition of consecutive volumes.

大多数运动校正的（可能是天真的）假设之一是任何运动都是瞬时的并且发生在连续每帧图像的获取之间。

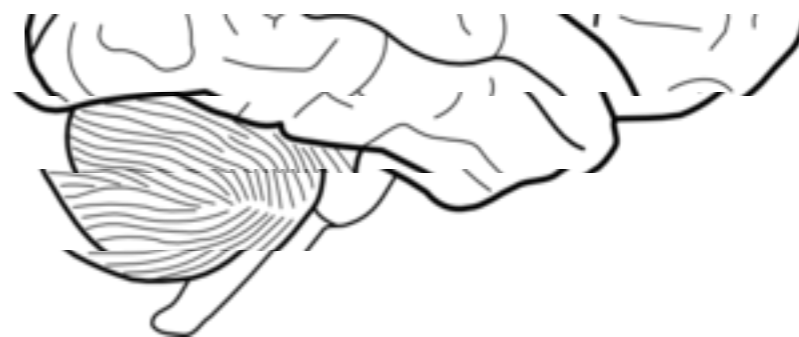
But the subject moves

但是被试在移动



This is the brain we set out to image

这是我们即将开始扫描的大脑



And more ...

更多



Intra-volume movement

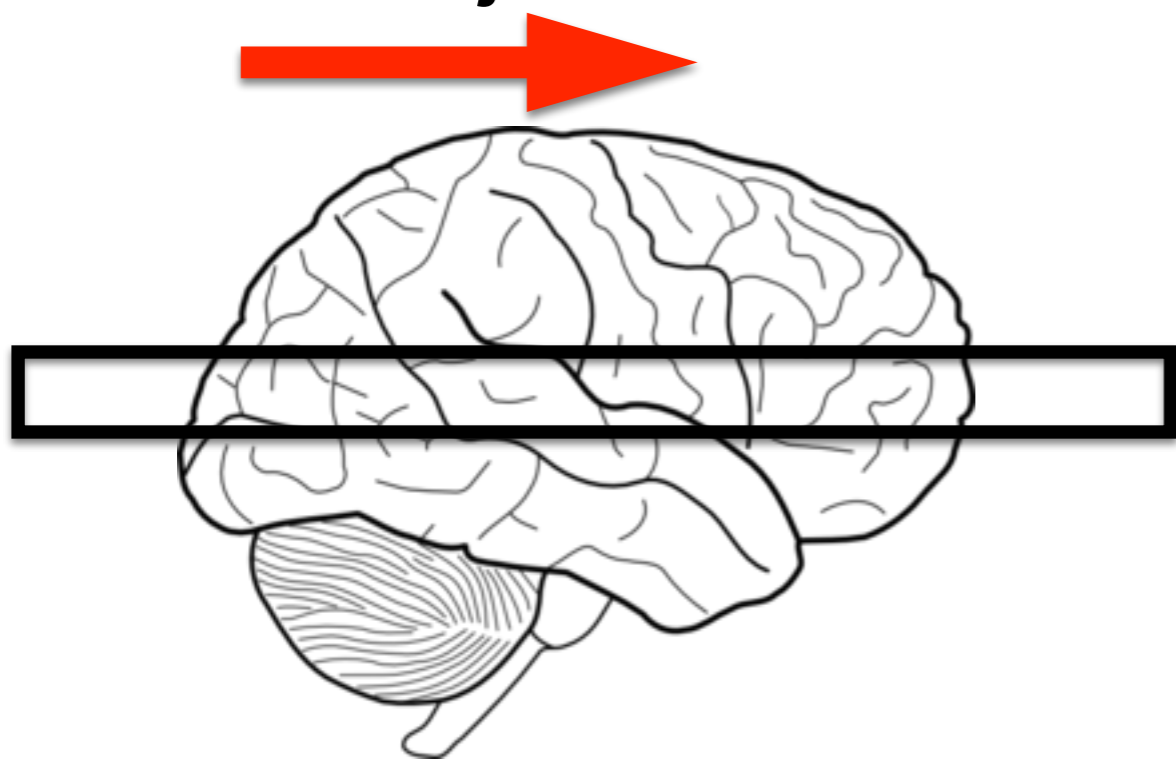
图像间运动

One of the (possibly naive) assumptions of most movement correction is that any movement is instantaneous and occurs between the acquisition of consecutive volumes.

大多数运动校正的（可能是天真的）假设之一是任何运动都是瞬时的并且发生在连续每帧图像的获取之间。

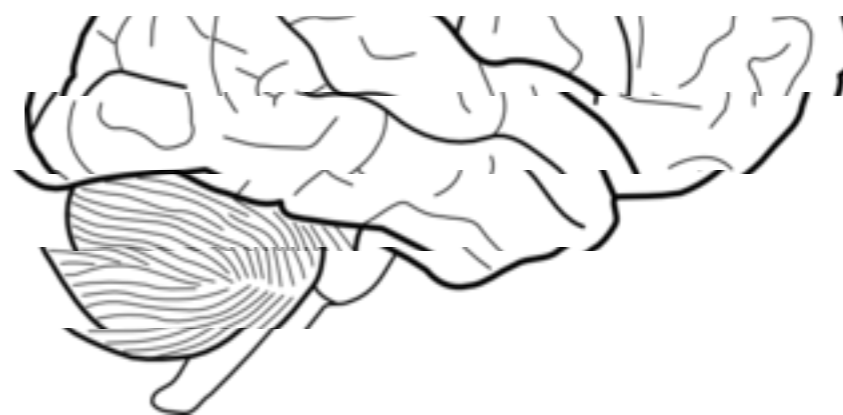
But the subject moves

但是被试在移动



This is the brain we set out to image

这是我们即将开始扫描的大脑



... and more ...

更多

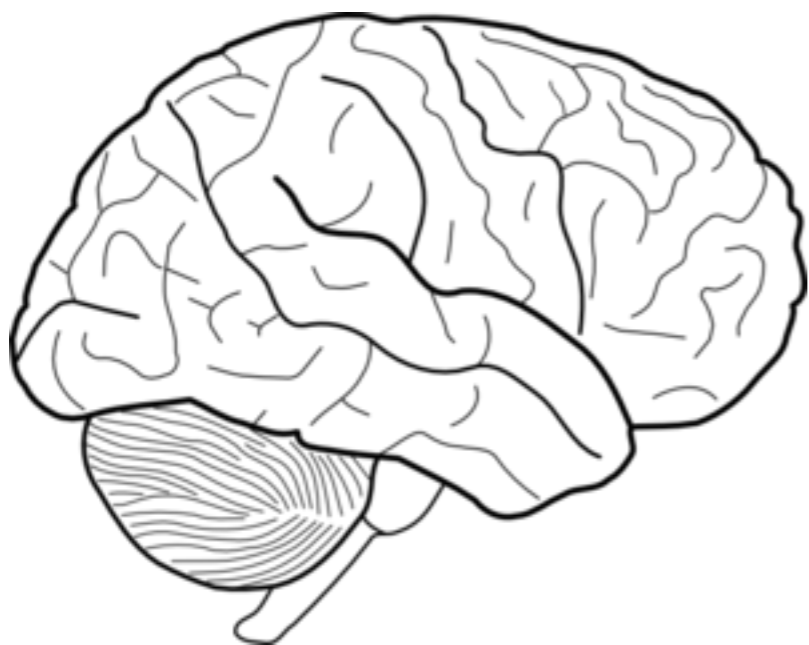


Intra-volume movement

图像间运动

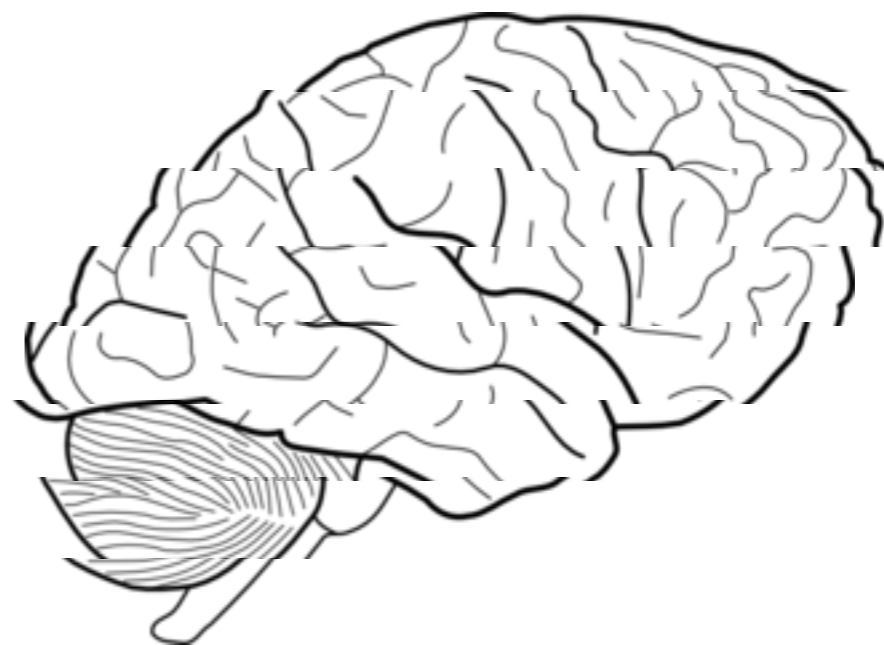
One of the (possibly naive) assumptions of most movement correction is that any movement is instantaneous and occurs between the acquisition of consecutive volumes.

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This is the brain
we set out to
image

这是我们即将开始扫描的大脑



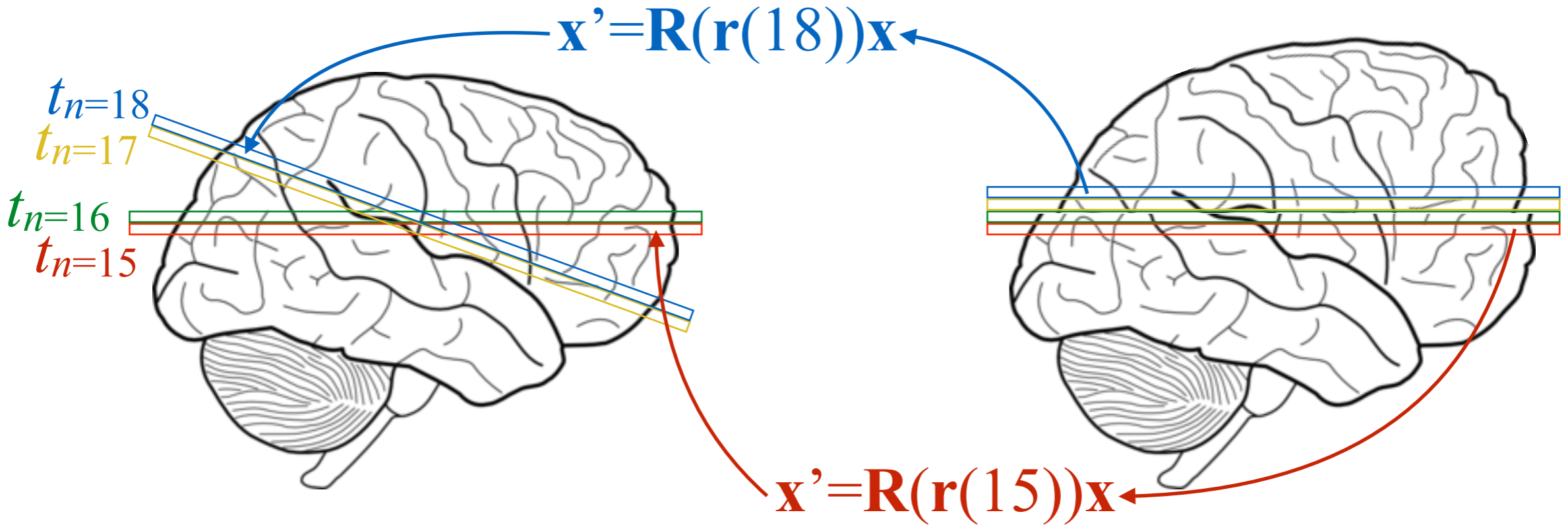
etc.



Intra-volume movement

图像间运动

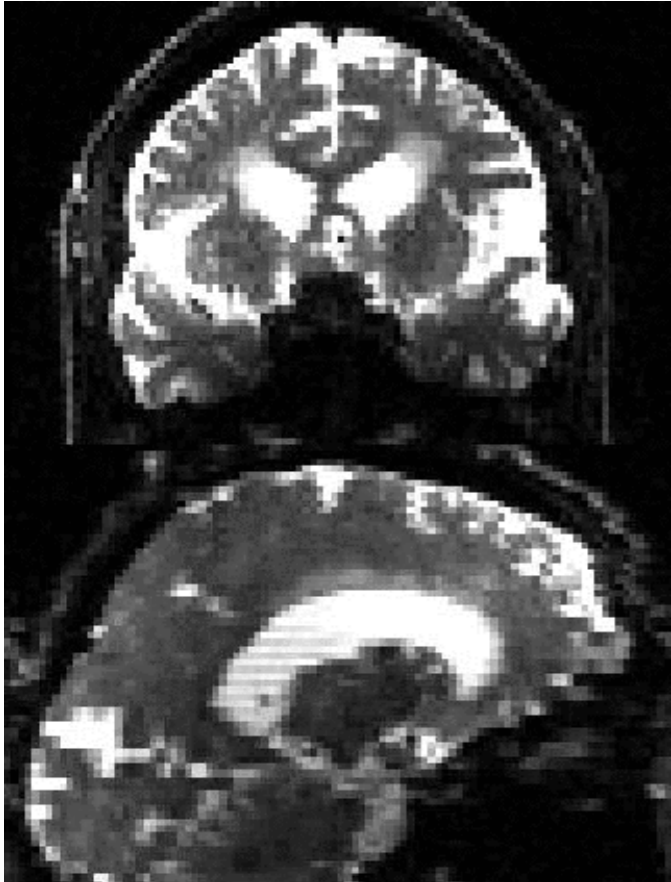
- This is known as the “slice-to-vol” problem or the “intra-volume movement” problem.
这被称为“层到”问题或“体积内运动”问题
- The new version of eddy addresses this problem. 新版本的eddy解决了这个问题
- It estimates the slice wise movement through the same Gaussian Process based forward model.
- 它通过相同的基于高斯过程的正演模型估计切片运动





Intra-volume movement

图像间运动



Original data
原始数据

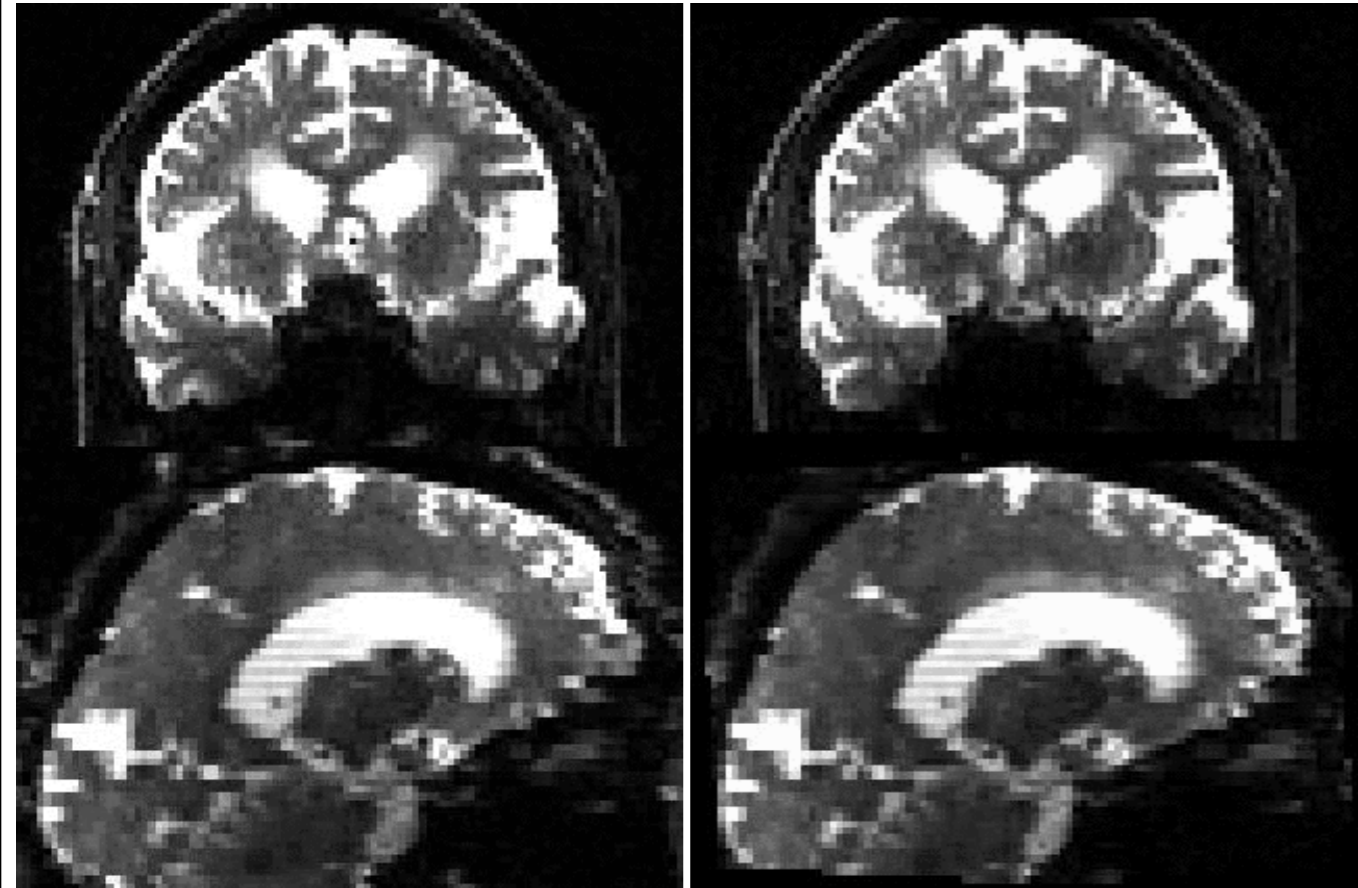
Problematic elderly subject. Lots of movement induced signal loss and intravolume movement

有问题的老年人。大量运动引起信号丢失和图像间运动



Intra-volume movement

图像间运动



Original data

After correction
without outlier
correction
异常值校正后

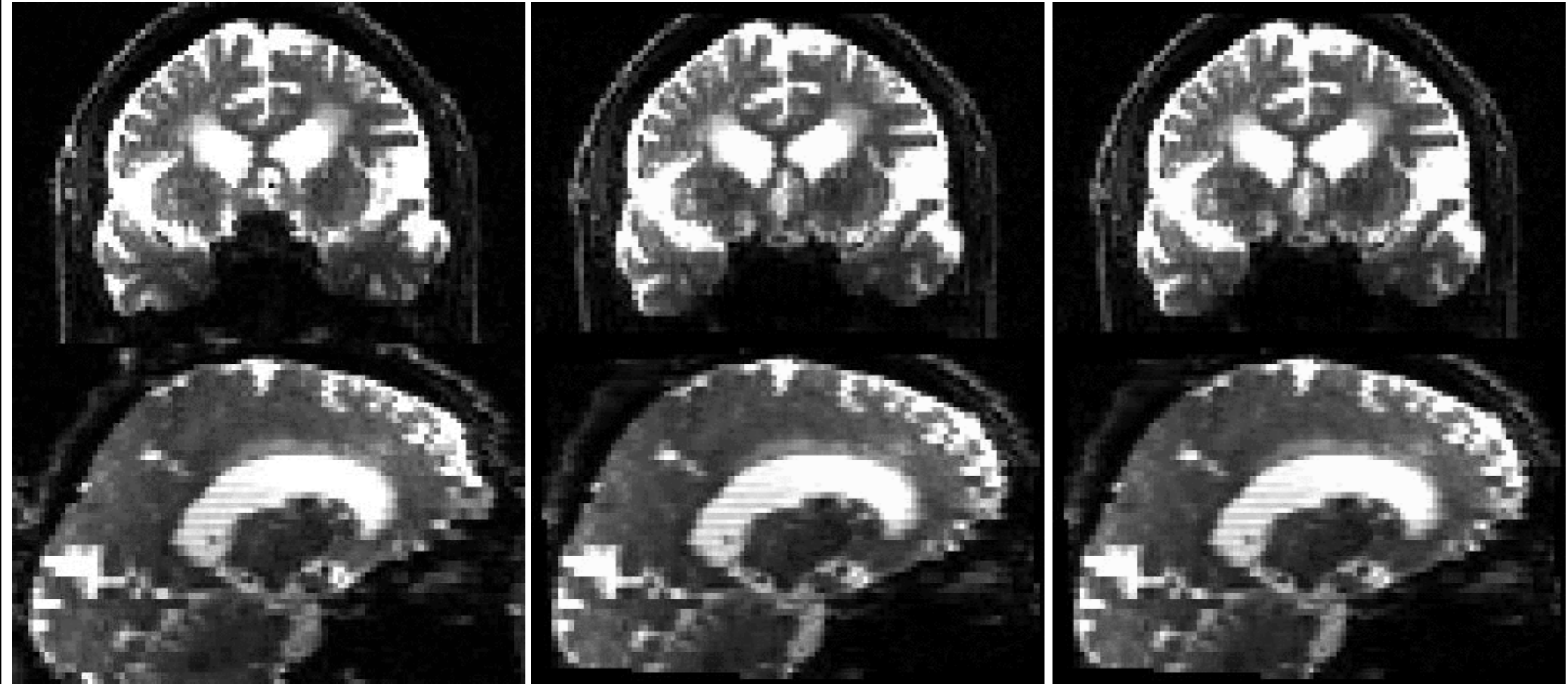
Problematic elderly subject. Lots of movement induced signal loss and intravolume movement

有问题的老年人。大量运动引起信号丢失和图像间运动



Intra-volume movement

图像间运动



Original data

After correction
without outlier
correction

After correction
with outlier
replacement

用异常值替换校正后

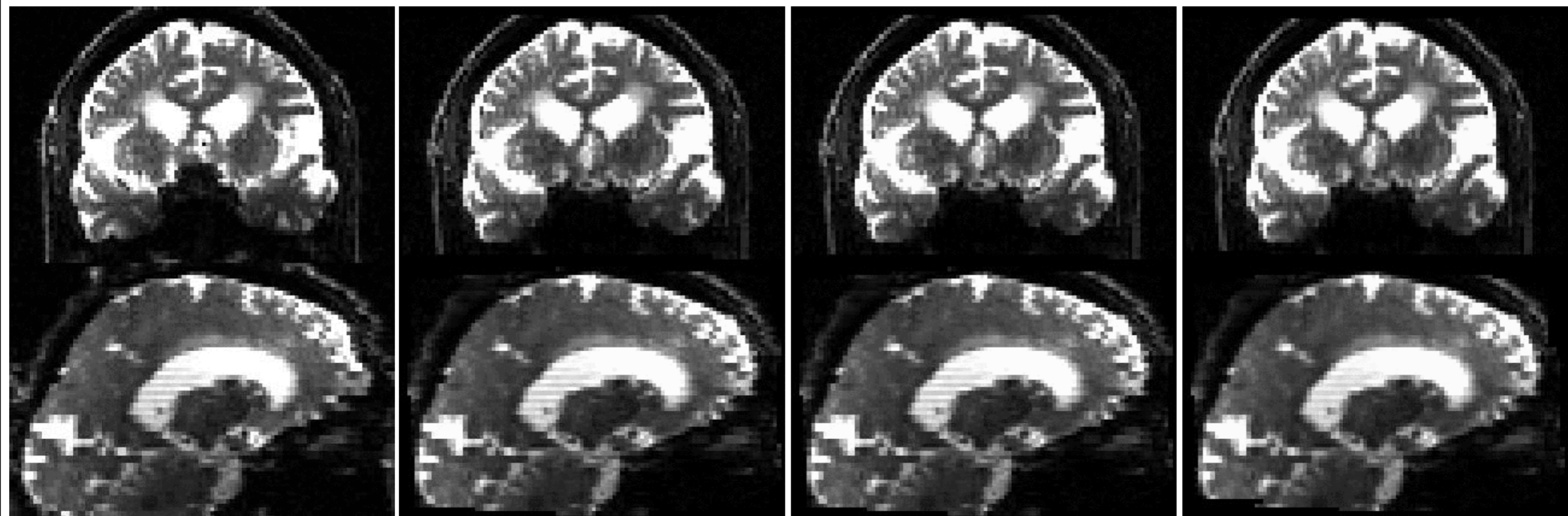
Problematic elderly subject. Lots of movement induced signal loss and intravolume movement

有问题的老年人。大量运动引起信号丢失和图像间运动



Intra-volume movement

图像间运动



Original data

原始数据

After correction

without outlier
correction

After correction

with outlier
replacement

After intravolume

movement
correction.

经过图像间运动校正

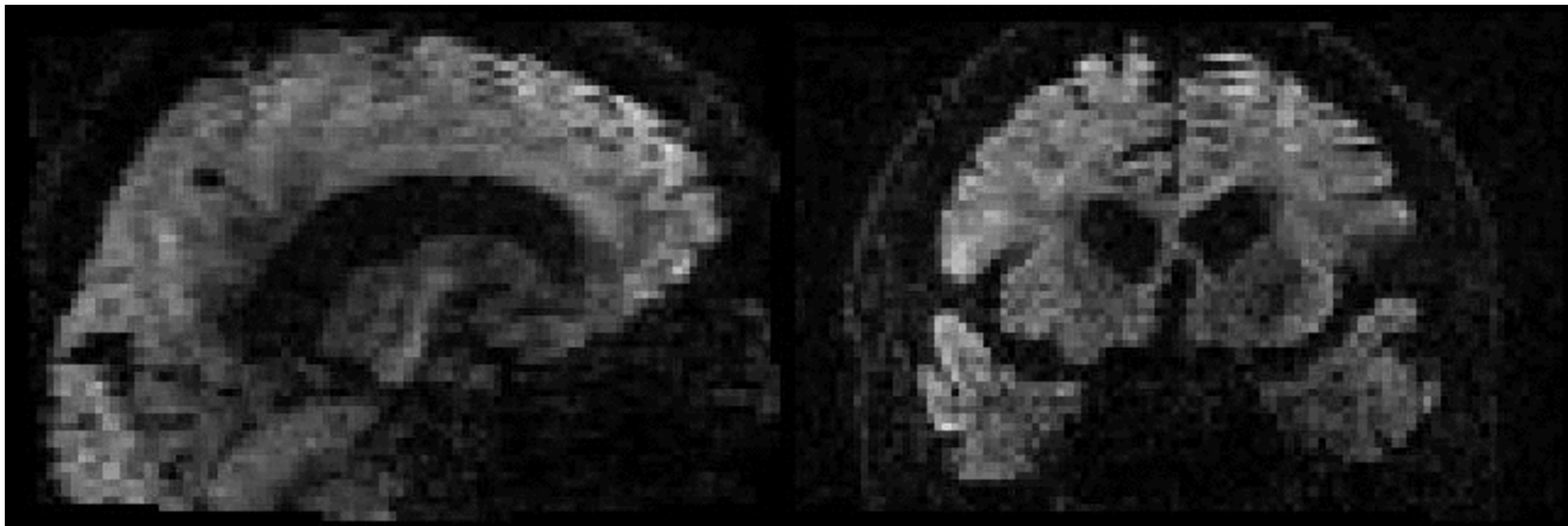
Problematic elderly subject. Lots of movement induced signal loss and intravolume movement

有问题的老年人。大量运动引起信号丢失和图像间运动



Intra-volume movement

图像间运动



Highlighting the difference between just OLR and OLR combined with S2V correction

突出OLR和OLR之间的差异以及S2V校正

Problematic elderly subject. Lots of movement induced signal loss and intravolume movement

有问题的老年人。大量运动引起信号丢失和图像间运动